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 Computational Electromagnetics Research Center

## Novel and Effective Preconditioners for Iterative Solvers

Fast Algorithms and Parallel Computing  
for the Solution of Extremely Large Integral Equations  
in Computational Electromagnetics

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## Prerequisites

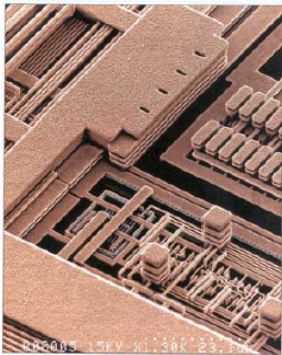
- Maxwell's equations, Helmholtz equation
- Integral equations, surface integral equations
- Iterative solvers
- Fast multipole method(s) (FMM)
- Multi-level fast multipole algorithm (MLFMA)
- Parallel MLFMA
- Hierarchical Parallelization

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## Real-Life Problem

### Electromagnetic Modeling of Microcircuits

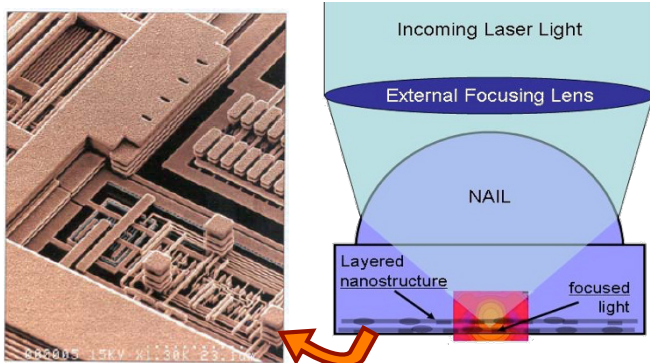


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## Real-Life Problem

### Nano-Optical Imaging Systems



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### Examples to Dielectric Problems

**Photonic crystals**

3-D modelling

Ö. Ergül, T. Malas, and L. Gürel, "Analysis of dielectric photonic-crystal problems with MLFMA and Schur-complement preconditioners," *J. Lightwave Technol.*, vol. 29, no. 6, pp. 888–897, Mar. 2011.

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### Examples to Dielectric Problems

**Red blood cells**

3-D modelling

Equivalent currents

**Near-zone electric field**

**Diagnosis**

Ö. Ergül, A. Arslan-Ergül, and L. Gürel, "Computational study of scattering from healthy and diseased red blood cells using surface integral equations and the multilevel fast multipole algorithm," *J. Biomed. Opt.*, vol. 15, no. 4, 045004, Jul./Aug. 2010.

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### Radiation into Living Organisms

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### Microwave Imaging

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## Antennas

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## Mobile Device Antennas

Bluetooth  
 Wi-Fi  
 GPS  
 UMTS  
 GSM

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## Satellite Antennas

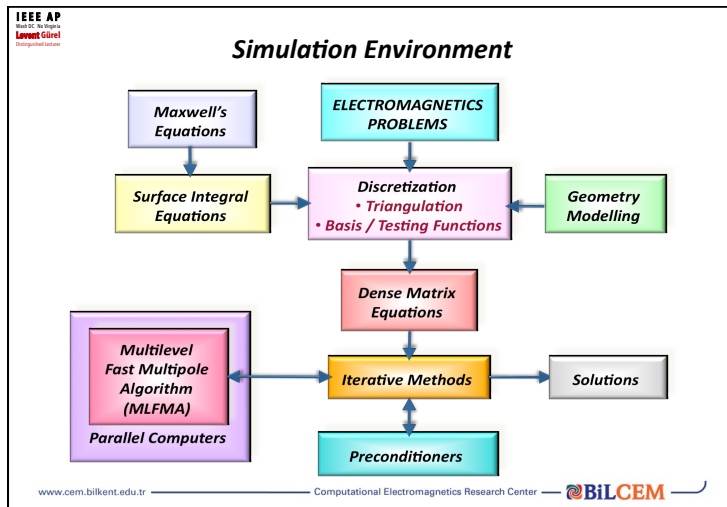
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## Antennas Mounted on Platforms

- Interaction of multiple antennas
- Characteristics of mounted antennas (different from isolated antennas)
- Optimization of the placement of the antennas

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**Maxwell's Equations**

$$\nabla \times \vec{E}(\vec{r}, t) = -\frac{\partial}{\partial t} \vec{B}(\vec{r}, t)$$

$$\nabla \times \vec{H}(\vec{r}, t) = \frac{\partial}{\partial t} \vec{D}(\vec{r}, t) + \vec{J}(\vec{r}, t)$$

$$\nabla \cdot \vec{B}(\vec{r}, t) = 0$$

$$\nabla \cdot \vec{D}(\vec{r}, t) = \rho(\vec{r}, t)$$

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**Surface Integral Equations**

- Electric-Field Integral Equation (EFIE):**

$$-\hat{t}(\mathbf{r}) \cdot ik \int_{S'} d\mathbf{r}' \left( \vec{I} - \frac{\nabla \nabla'}{k^2} \right) g(\mathbf{r}, \mathbf{r}') \cdot \mathbf{J}(\mathbf{r}') = \frac{1}{\eta} \hat{t}(\mathbf{r}) \cdot \mathbf{E}^{inc}(\mathbf{r})$$
- Magnetic-Field Integral Equation (MFIE):**

$$\mathbf{J}(\mathbf{r}) - \hat{\mathbf{n}}(\mathbf{r}) \times \int_{S'} d\mathbf{r}' \mathbf{J}(\mathbf{r}') \times \nabla' g(\mathbf{r}, \mathbf{r}') = \hat{\mathbf{n}}(\mathbf{r}) \times \mathbf{H}^{inc}(\mathbf{r})$$
- Combined-Field Integral Equation (CFIE):**

$$CFIE = \alpha EFIE + (1 - \alpha) MFIE$$
- Hybrid-Field Integral Equation (HFIE):**

$$HFIE = \alpha(\mathbf{r}) EFIE + [1 - \alpha(\mathbf{r})] MFIE$$

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**Discretization**

**Number of unknowns**

$$\mathbf{J}(\mathbf{r}) = \sum_{n=1}^N a_n \mathbf{b}_n(\mathbf{r})$$

**Matrix equations:**

$$\sum_{n=1}^N Z_{mn}^{E,M,C,H} a_n = v_m^{E,M,C,H}, \quad m = 1, 2, \dots, N$$

**Matrix elements:**

$$Z_{mn}^E = \int_{S_m} d\mathbf{r} \mathbf{t}_m(\mathbf{r}) \cdot \int_{S_n} d\mathbf{r}' \vec{G}(\mathbf{r}, \mathbf{r}') \cdot \mathbf{b}_n(\mathbf{r}')$$

$$Z_{mn}^M = \int_{S_m} d\mathbf{r} \mathbf{t}_m(\mathbf{r}) \cdot \mathbf{b}_n(\mathbf{r}) - \int_{S_m} d\mathbf{r} \mathbf{t}_m(\mathbf{r}) \cdot \hat{\mathbf{n}} \times \int_{S_n} d\mathbf{r}' \mathbf{b}_n(\mathbf{r}') \times \nabla' g(\mathbf{r}, \mathbf{r}')$$

$$Z_{mn}^C = \alpha Z_{mn}^E + (1 - \alpha) \frac{i}{k} Z_{mn}^M \quad Z_{mn}^H = \alpha_m Z_{mn}^E + (1 - \alpha_m) \frac{i}{k} Z_{mn}^M$$

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### Matrix Elements...

...are electromagnetic interactions

$$Z_{mn}^E = \int_{S_m} d\mathbf{r} \mathbf{t}_m(\mathbf{r}) \cdot \int_{S_n} d\mathbf{r}' \bar{\mathbf{G}}(\mathbf{r}, \mathbf{r}') \cdot \mathbf{b}_n(\mathbf{r}')$$

Testing functions Basis functions

$$\sum_{n=1}^N Z_{mn}^E a_n = v_m^E, \quad m = 1, 2, \dots, N$$

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### Geometry Discretization

Modeling with millions of triangles.

Mesh Size:  $\lambda/10$

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### Matrix Equation

System of Linear Equations

$$\mathbf{A} \cdot \mathbf{x} = \mathbf{b}$$

$$\mathbf{Z} \cdot \mathbf{a} = \mathbf{v}$$

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### Iterative Solutions

• Large matrix equations

$$\bar{\mathbf{Z}} \cdot \mathbf{a} = \mathbf{v}$$

Parallel Multilevel Fast Matrix-Vector Multiplication (MLFMA)

$$\bar{\mathbf{Z}} \cdot \mathbf{x} = \mathbf{y}$$

Iterative Solution

- CG and CGS
- BiCG and BiCGStab
- GMRES
- LSQR

Preconditioner

- BDP
- NFP
- Filtered NFP
- SAI
- Nested PCs

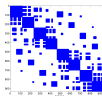
$$\bar{\mathbf{M}} \cdot \mathbf{z} = \mathbf{w}$$

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## Preconditioners (for MLFMA)

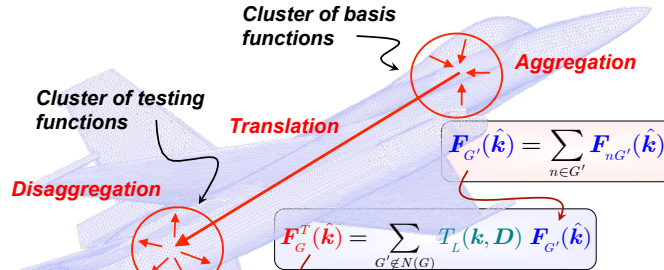
- \* **Near-Field Preconditioners**
  - LU (too expensive)
  - ILU: Incomplete LU
  - SAI: Sparse Approximate Inverse
  - INF: Iterative Near-Field Preconditioner
- \* **Full-Matrix Preconditioners (Approximate)**
  - Use more than the available near-field matrix
- \* **Schur Preconditioners for Dielectric Formulations**



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## Fast Multipole Method



**Cluster of basis functions**

**Cluster of testing functions**

**Translation**

**Aggregation**

**Disaggregation**

$$F_{G'}(\hat{k}) = \sum_{n \in G'} F_{nG'}(\hat{k}) a_n$$

$$F_G^T(\hat{k}) = \sum_{G' \notin N(G)} T_L(k, D) F_{G'}(\hat{k})$$

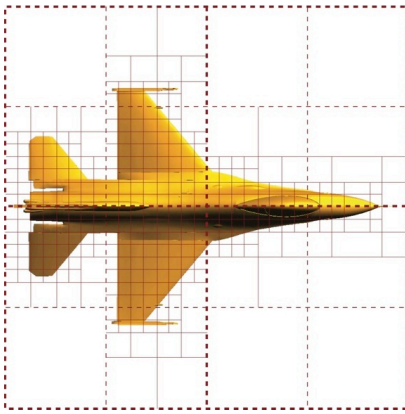
$$\sum_{n=1}^N Z_{mn} a_n = \frac{1}{4\pi} \int d^2 \hat{k} F_{mG}^C(\hat{k}) \cdot F_G^T(\hat{k})$$

**Complexity:  $O(N^{3/2})$**

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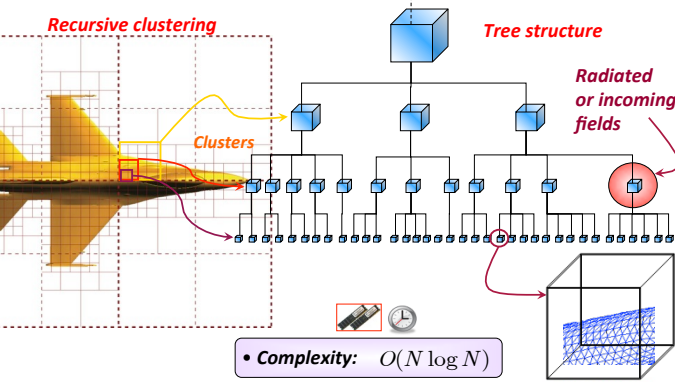
## Multilevel Fast Multipole Algorithm



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## Multilevel Fast Multipole Algorithm



**Recursive clustering**

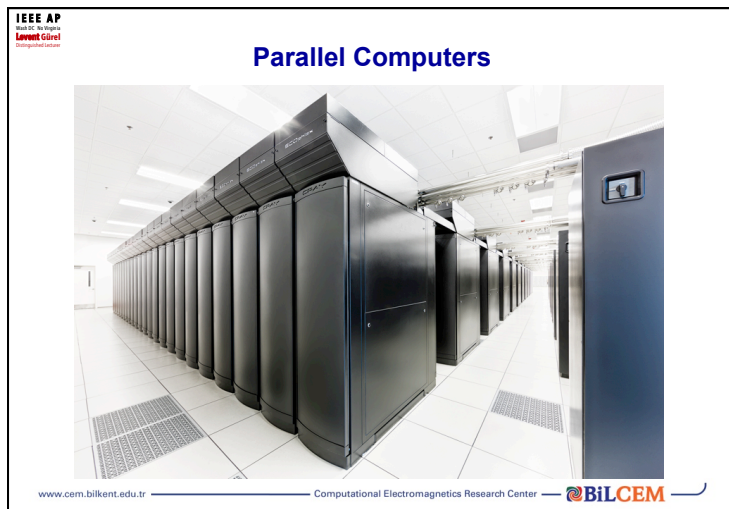
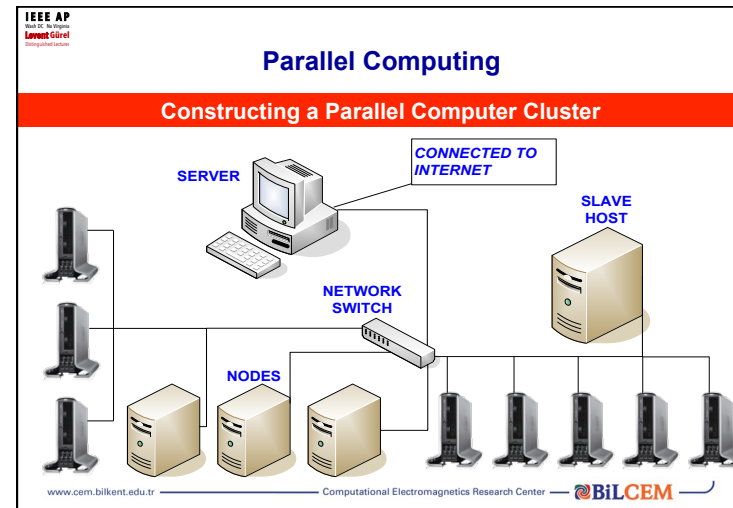
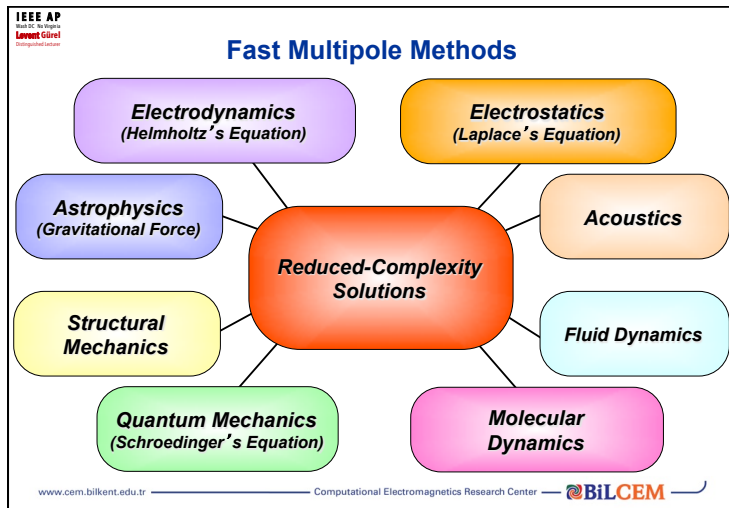
**Tree structure**

**Clusters**

**Radiated or incoming fields**

**Complexity:  $O(N \log N)$**

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**Parallel Computing**

**Constructing Parallel Computer Clusters**

**64-Core Cluster**

8 nodes  
 Per node: Two Intel Xeon 5445 3 GHz Quad-Core Processors  
 Total of 64 cores  
 Per node: 32 GB DDR2-667 533 MHz RAM  
 Total of 256 GB of RAM  
 Network: Infiniband

**136-Core Cluster**

Per node: Two Intel Xeon 5472 3 GHz Quad-Core Processors  
 Total of 136 cores  
 Per node: 4 GB DDR2-667 533 MHz RAM  
 Total of 544 GB of RAM  
 Network: Infiniband

**Not in www.top500.org!!!**

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## What is the Main Source of Efficiency?

$N$ Unknowns	$O(N^3)$ Gaussian Elimination	$O(N^2)$ Iterative MOM (MVM)	$O(N^{3/2})$ Single-Level FMM	$O(N \log N)$ Multi-Level FMM
1000	1 s	2 s	4 s	8 s
$10^6$	32 years	23 days	35 h	7 h
$10^7$	32 K years	6.3 years	46 days	89 h
$10^8$	32 M years	630 years	4 years	46 days
$10^9$	32 G years	63 K years	127 years	1.5 years (555 days)

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## What is the Main Source of Efficiency?

**Answer:** Reduced complexity of a fast algorithm is the main source of efficiency, NOT parallelization.

Nevertheless, parallelization is useful for reducing the CPU time and essential for memory usage.

Parallelization is necessary, but not sufficient.

**Dilemma:** Faster algorithms with lower computational complexity require more complicated programming (ironic?), and hence they are much more difficult to parallelize.

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## 53 Million Unknowns

Sphere with radius of  $120\lambda$  and diameter of  $240\lambda$

November 2007

**53,112,384 Unknowns**

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## 69 Million Unknowns

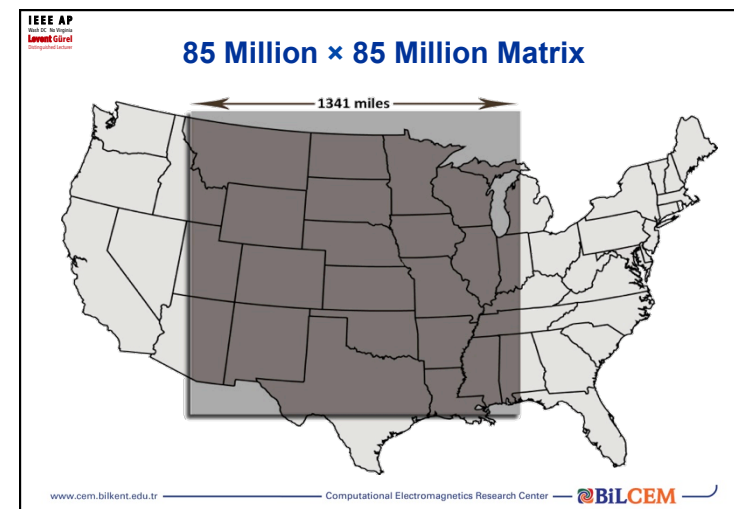
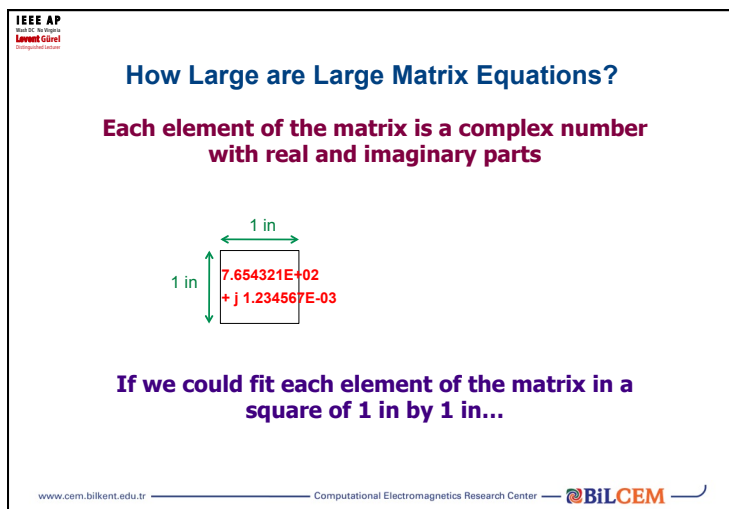
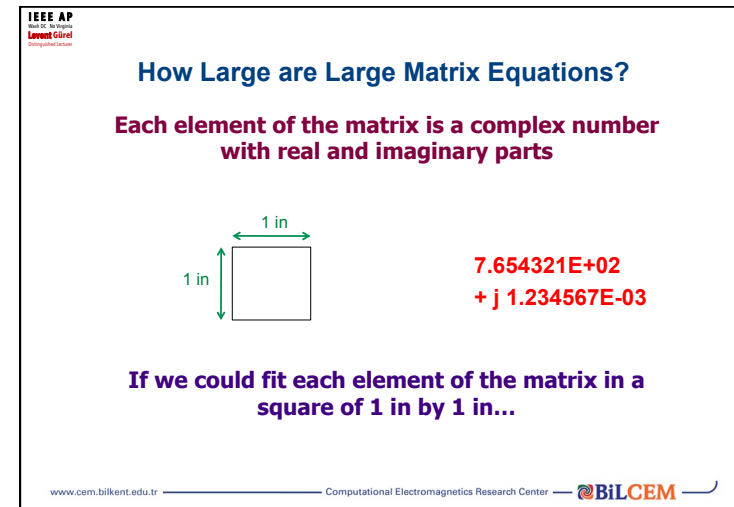
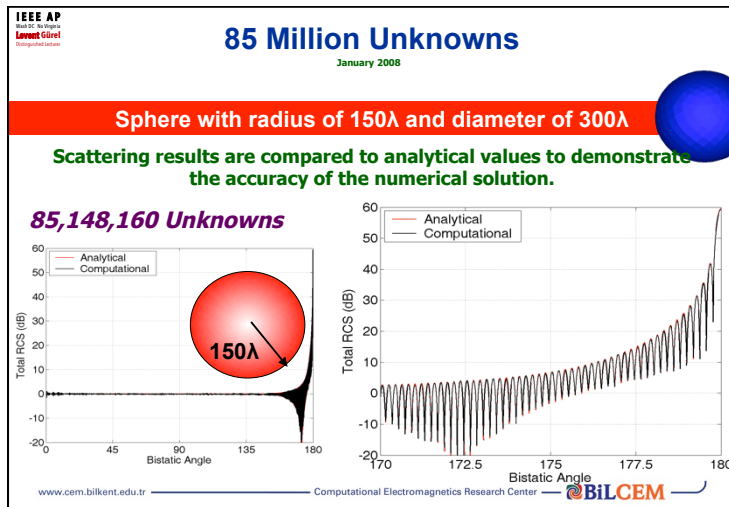
Sphere with radius of  $150\lambda$  and diameter of  $300\lambda$

December 2007

**69,177,600 Unknowns**


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## Intel Pamphlet on the World Record



Case Study  
 Quad-Core Intel® Xeon® processor 5300 series  
 Computational Electromagnetics

### Breakthrough in Scientific Computing: BiLCEM Sets World Record in Computational Electromagnetics

Bilkent University opens the door to a secret universe thanks to Quad-Core Intel® Xeon® processor 5300 series

Bilkent University in Ankara, Turkey, is one of the world's leading research universities and home to the Bilkent University Computational Electromagnetics Research Center (BiLCEM) a globally respected institute specializing in the solution of the largest and most difficult problems in computational electromagnetics (CEM). BiLCEM investigates and analyzes electromagnetic interactions and wave phenomena through computations that typically involve millions of unknowns. While it is extremely challenging, finding answers to CEM problems can result in far-reaching benefits for humanity. To make significant advances in the field,

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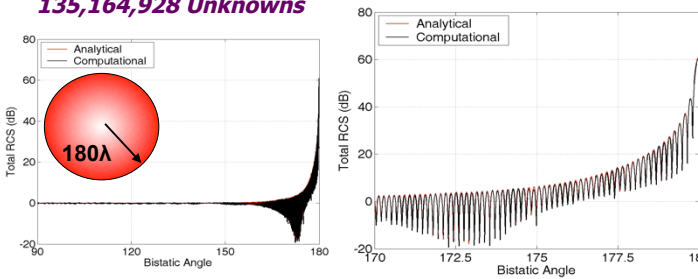
## 135 Million Unknowns

August 2008

### Sphere with radius of $180\lambda$ and diameter of $360\lambda$

Scattering results are compared to analytical values to demonstrate the accuracy of the numerical solution.

### 135,164,928 Unknowns



Two plots showing Total RCS (dB) vs Bistatic Angle. The left plot shows a sharp resonance peak at approximately 175 degrees. The right plot shows a series of oscillations between 170 and 180 degrees. Both plots compare Analytical (red line) and Computational (black line) results, showing excellent agreement.

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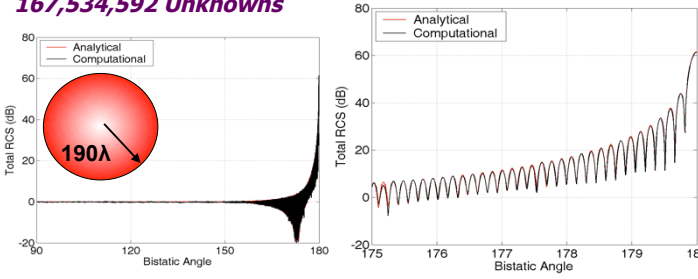
## 167 Million Unknowns

August 2008

### Sphere with radius of $190\lambda$ and diameter of $380\lambda$

Scattering results are compared to analytical values to demonstrate the accuracy of the numerical solution.

### 167,534,592 Unknowns



Two plots showing Total RCS (dB) vs Bistatic Angle. The left plot shows a sharp resonance peak at approximately 175 degrees. The right plot shows a series of oscillations between 175 and 180 degrees. Both plots compare Analytical (red line) and Computational (black line) results, showing excellent agreement.

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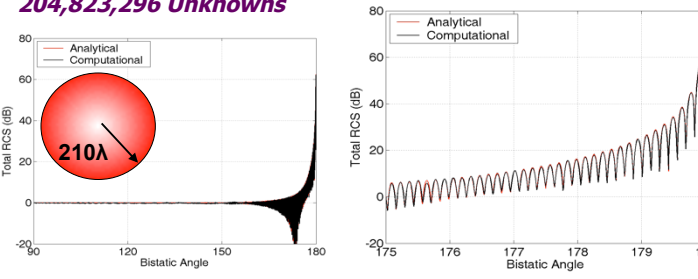
## 205 Million Unknowns

September 2008

### Sphere with radius of $210\lambda$ and diameter of $420\lambda$

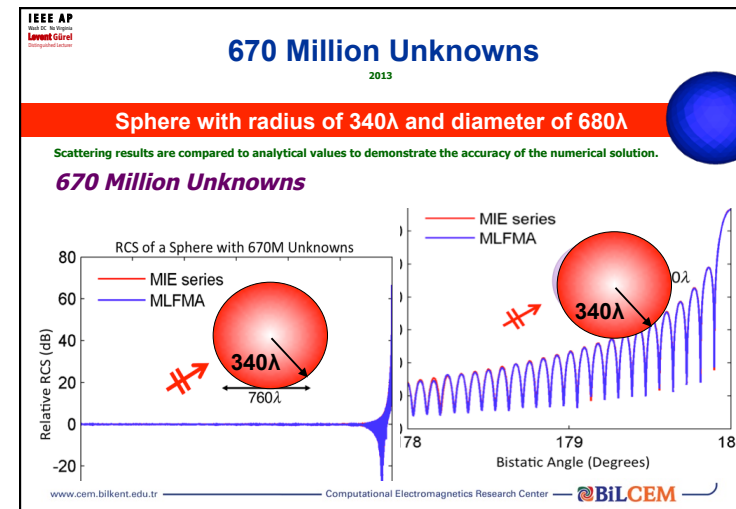
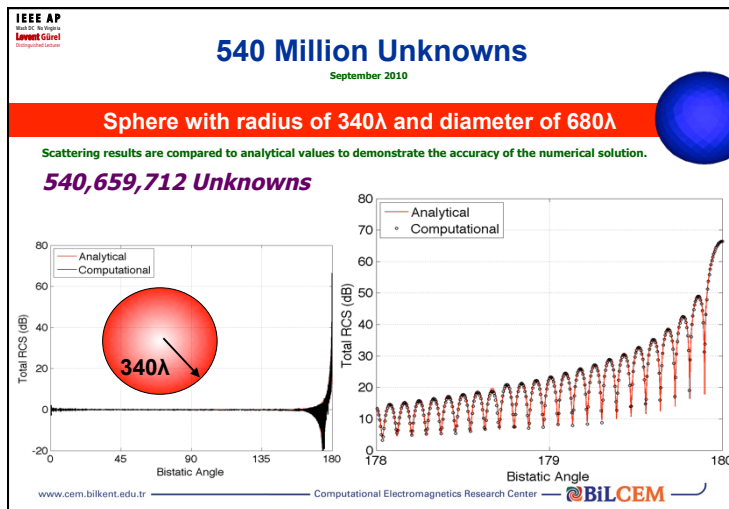
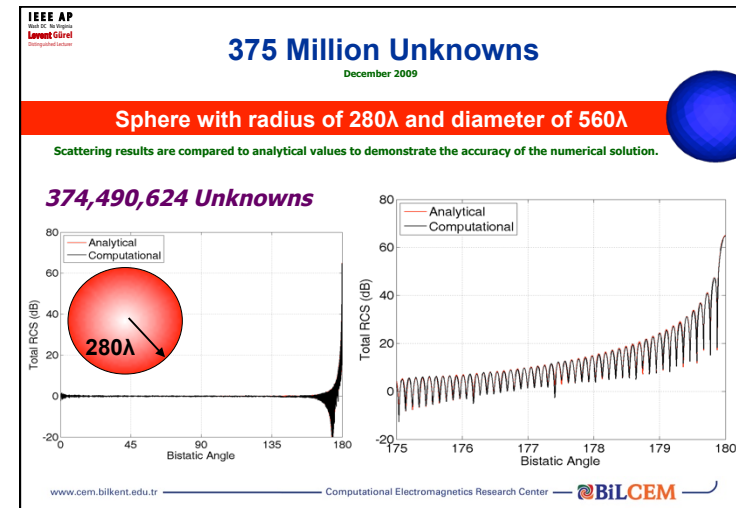
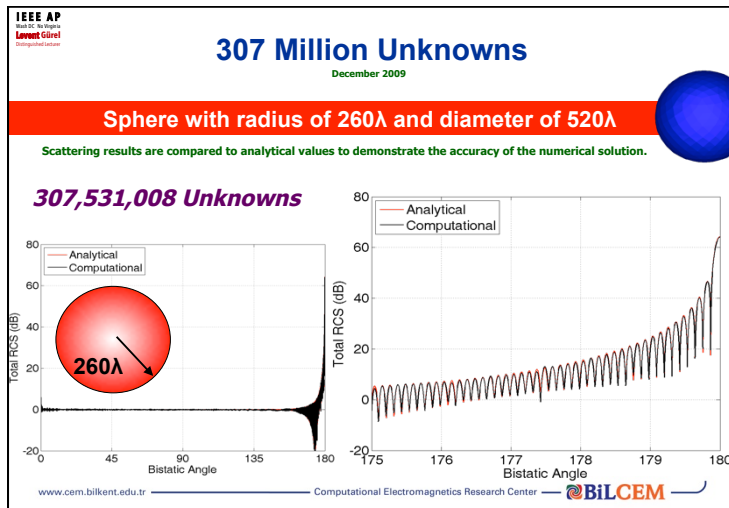
Scattering results are compared to analytical values to demonstrate the accuracy of the numerical solution.

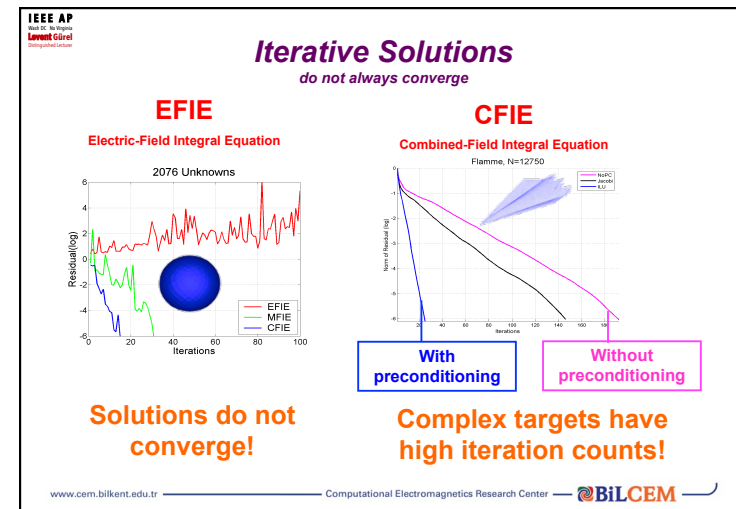
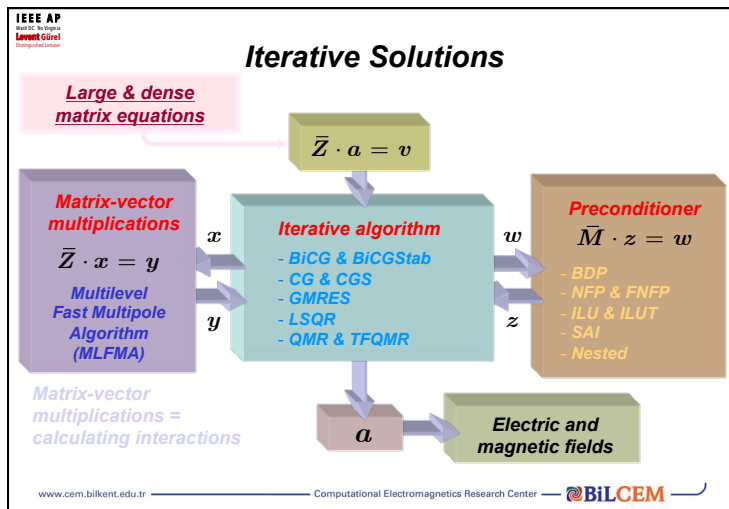
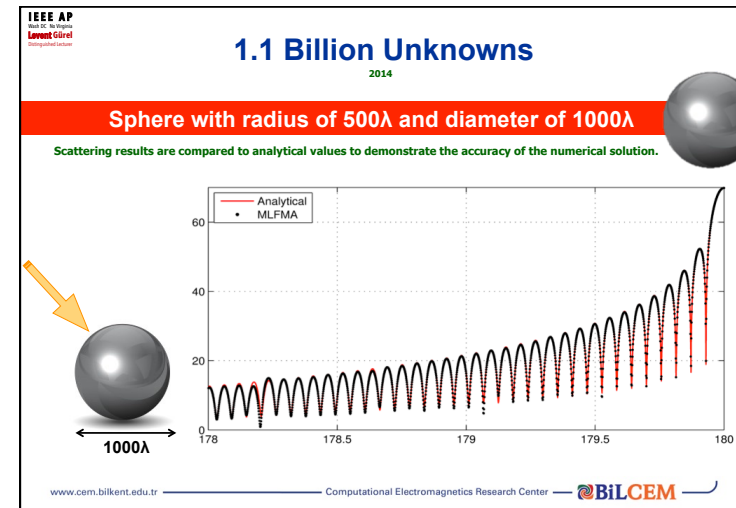
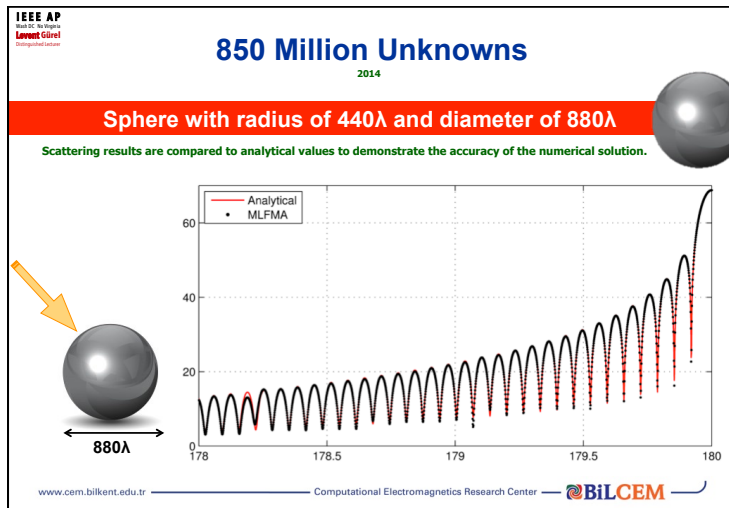
### 204,823,296 Unknowns



Two plots showing Total RCS (dB) vs Bistatic Angle. The left plot shows a sharp resonance peak at approximately 175 degrees. The right plot shows a series of oscillations between 175 and 180 degrees. Both plots compare Analytical (red line) and Computational (black line) results, showing excellent agreement.

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## Forward-Type Preconditioners

For the iterative solution of  $\bar{Z} \cdot a = v$

find  $\bar{M} \approx \bar{Z}$ ,

for which the solution of  $\bar{M} \cdot z = y$  is cheap.

Then, solve  $\bar{M}^{-1} \cdot \bar{Z} \cdot a = \bar{M}^{-1} \cdot v$

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## Iterative Solutions

require matrix-vector multiplications in the form of  $\bar{Z} \cdot x$ .

Matrix-vector multiplication is provided by MLFMA in  $O(N \log N)$  time.

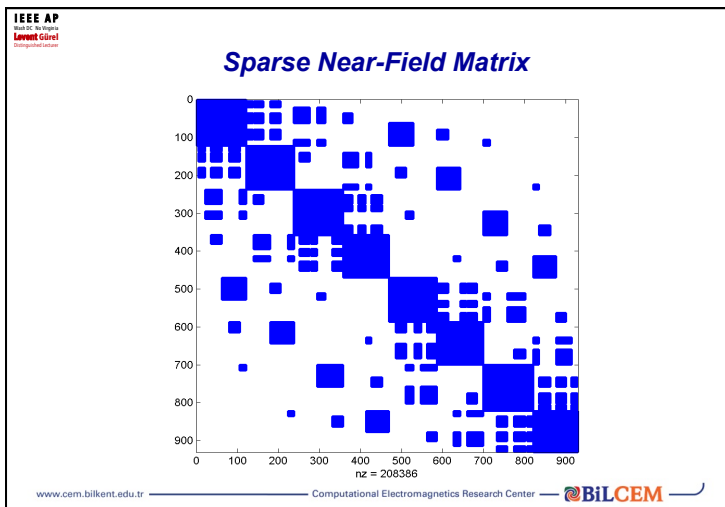
Only near-field interactions are stored:

$$\bar{Z} \cdot x = (\bar{Z}^{NF} + \bar{Z}^{FF}) \cdot x$$

Sparse near-field matrix  $\leftarrow$   $\bar{Z}^{NF}$   $\bar{Z}^{FF}$  Far-field interactions by MLFMA

$\bar{M} \approx \bar{Z}$  may be  $\bar{Z}^{NF}$

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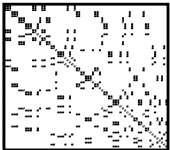
## Challenges and Requirements

- ▶ System matrix is not readily available!
- ▶ Large linear systems!
- ▶ Indefinite systems!
- ▶ Apply sparse preconditioning techniques
- ▶  $O(N \log N)$  complexity (or lower)
- ▶ Parallelizable

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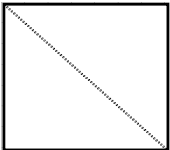
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## Simple Preconditioners



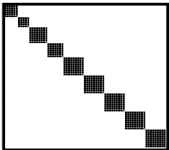
**Filtered:**

- Stronger elements in the impedance matrix are selected
- Adjustable size
- Difficult to factorize and use



**Diagonal:**

- Diagonal (self-unknown) elements in the impedance matrix are selected
- Size is fixed
- Easy to factorize and use



**Block Diagonal:**

- Block-diagonal (self-cluster) elements in the impedance matrix are selected
- Size is fixed
- Easy to factorize and use

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 Mehmet Gürel  
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## Preconditioners (for MLFMA)

- ★ *Near-Field Preconditioners*
- ★ *Full-Matrix Preconditioners (Approximate)*
- ★ *Schur Preconditioners for Dielectric Formulations*

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## Sparse Near-Field Preconditioners

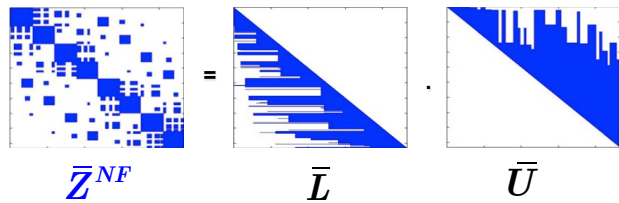
- **LU** (too expensive)
- **ILU: Incomplete LU**
- **SAI: Sparse Approximate Inverse**
- **INF: Iterative Near-Field Preconditioner**

Alternatively: Use more than the available near-field matrix

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## Inverse of a Sparse Matrix is NOT Sparse!



$\bar{Z}^{NF} = \bar{L} \cdot \bar{U}$

$$\bar{Z}^{NF} = \bar{L} \cdot \bar{U}, \quad x = (\bar{L} \cdot \bar{U})^{-1} \cdot y$$

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## Metamaterials Split-Ring Resonators

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## SRR Walls

**Meta Property:  
Stop band in  
frequency!**

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## Special Configurations

Closed-Ring Resonators (CRRs)

**All pass!**

Thin Wire Array (TWA)

**No pass!**

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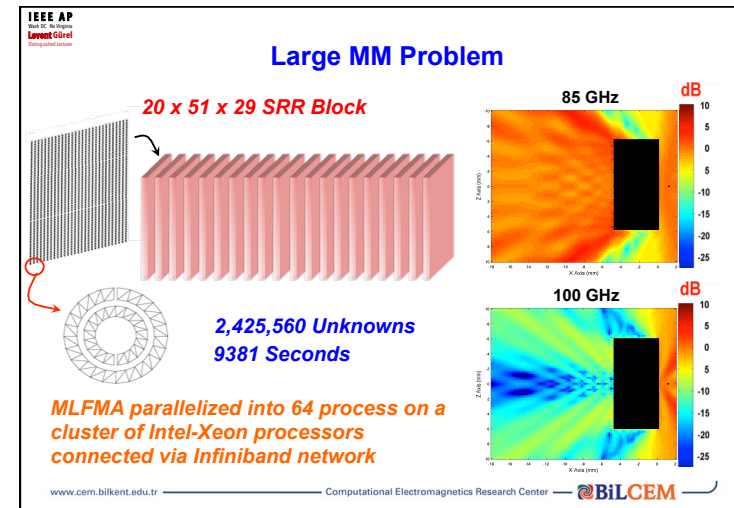
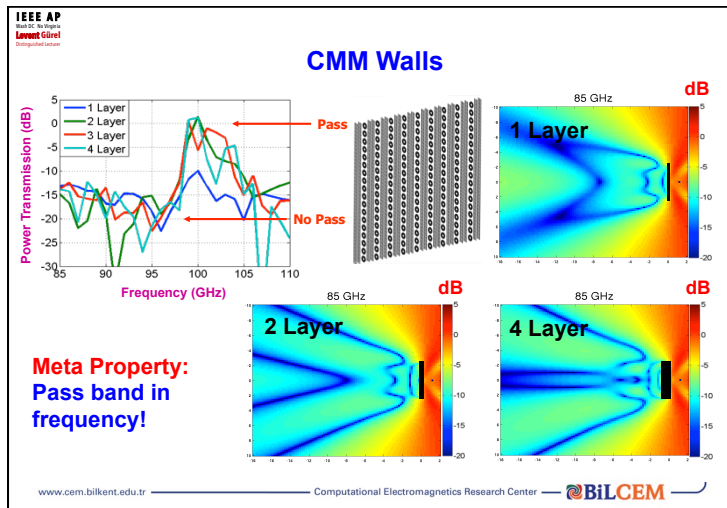
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## Composite Metamaterial (CMM)

Split-Ring Resonators (SRRs)

Thin Wire Array (TWA)

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### BENCHMARKING

Available from  
[www.cem.bilkent.edu.tr](http://www.cem.bilkent.edu.tr)

**Scattering from sphere (radius:  $20\lambda$  -  $340\lambda$ )**  
**Web-based application: Upload the computational results and get the error with respect to analytical Mie-series solutions.**

**Scattering from NASA Almond (size:  $94\lambda$  -  $1514\lambda$ )**  
**Web-based application: Upload the computational results and get the error with respect to our results.**

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### WEB-BASED BENCHMARKING TOOL

BILCEM | Benchmarking

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Benchmarking Tool for Assessing the Accuracy of Solutions of a Class of Extremely Large Electromagnetic Scattering Problems

**Explanation**

The file to be uploaded must have the following properties:

- It must have 1801 rows and 2 columns
- Each row corresponds to an RCS value, with theta and phi components of its e-field power in dB scale.
- These RCS values are samples at a cut, for example x-y plane, with 0.1 degree between them. First value is the back-scattering, and the last value is the forward-scattering value. That is, samples start at 0 degree and end at 180 degree incremented by 0.1 degree.

**Benchmark Sphere Results**

- Radius: 20 wavelengths.
- Radius: 40 wavelengths.
- Radius: 60 wavelengths.
- Radius: 80 wavelengths.
- Radius: 96 wavelengths.
- Radius: 120 wavelengths.
- Radius: 160 wavelengths.
- Radius: 180 wavelengths.
- Radius: 210 wavelengths.
- Radius: 240 wavelengths.
- Radius: 280 wavelengths.
- Radius: 340 wavelengths.

**Benchmark Almond Results**

- Radius: 94.7 wavelengths.
- Radius: 180.4 wavelengths.
- Radius: 278.7 wavelengths.
- Radius: 757.4 wavelengths.

Unlock Internet

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