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New Techniques and Improved Methods for Fault Location



Making Electric Power Safer, More Reliable, and More Economical[®]

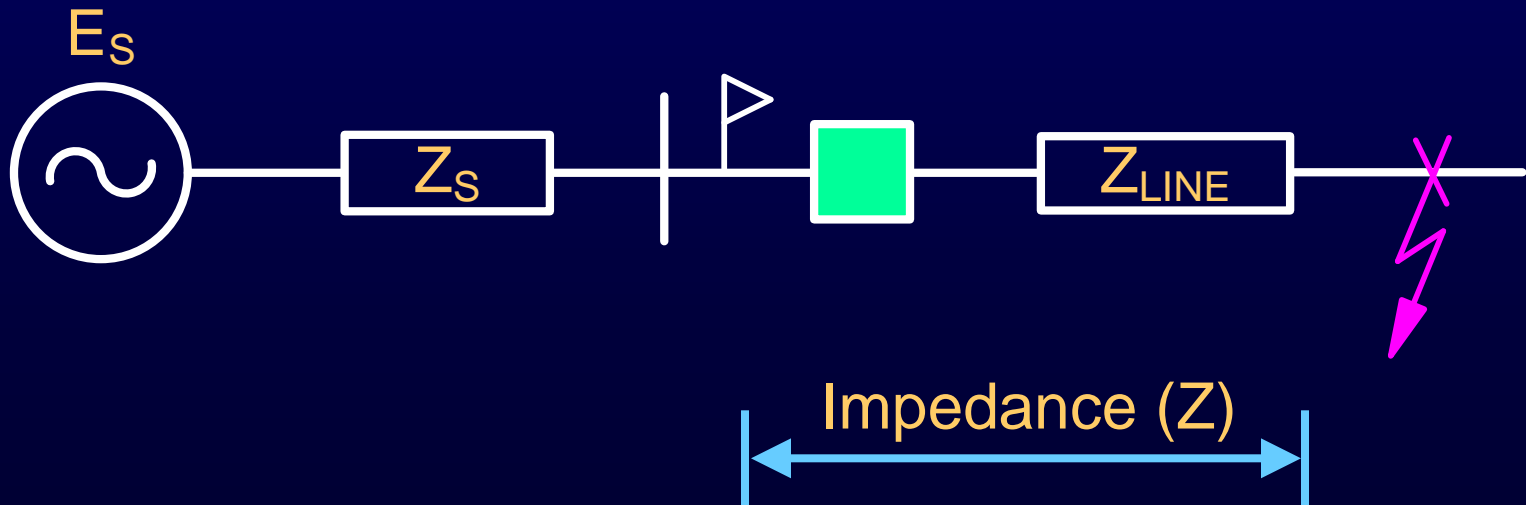
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Fault Location (FL) Methods

- Impedance-based methods
 - ◆ Single-ended method
 - ◆ Multi-ended method
 - Real-time calculations in relays
 - Offline software tools
- Traveling wave (TW) method

Impedance-Based FL

What Is Impedance-Based Fault Location?

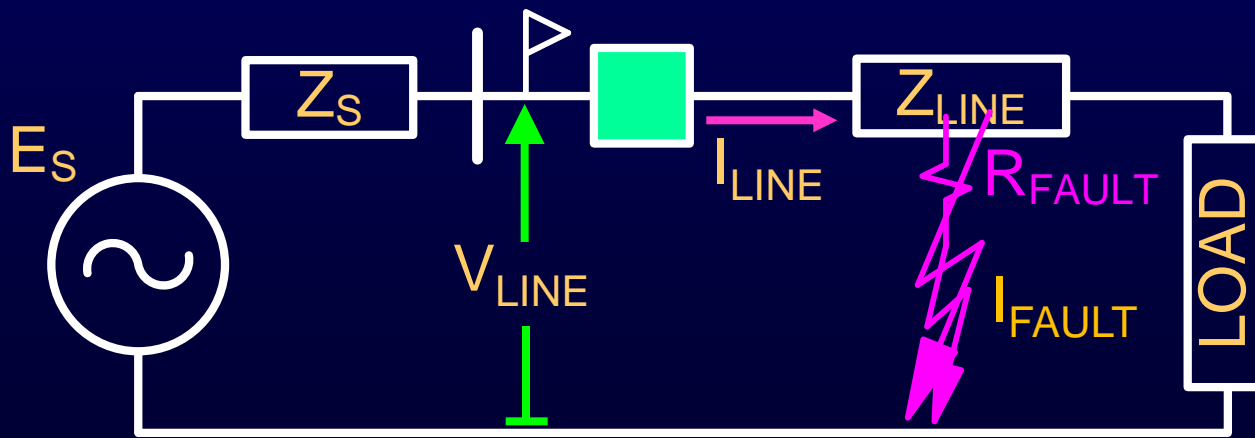


Impedance \rightarrow Distance

$$\text{Distance} = \frac{\text{Im}(V_L \cdot I_{FLT}^*)}{\text{Im}(I_L \cdot Z_L \cdot I_{FLT}^*)} \cdot \text{Line Length}$$

Single-Ended Method

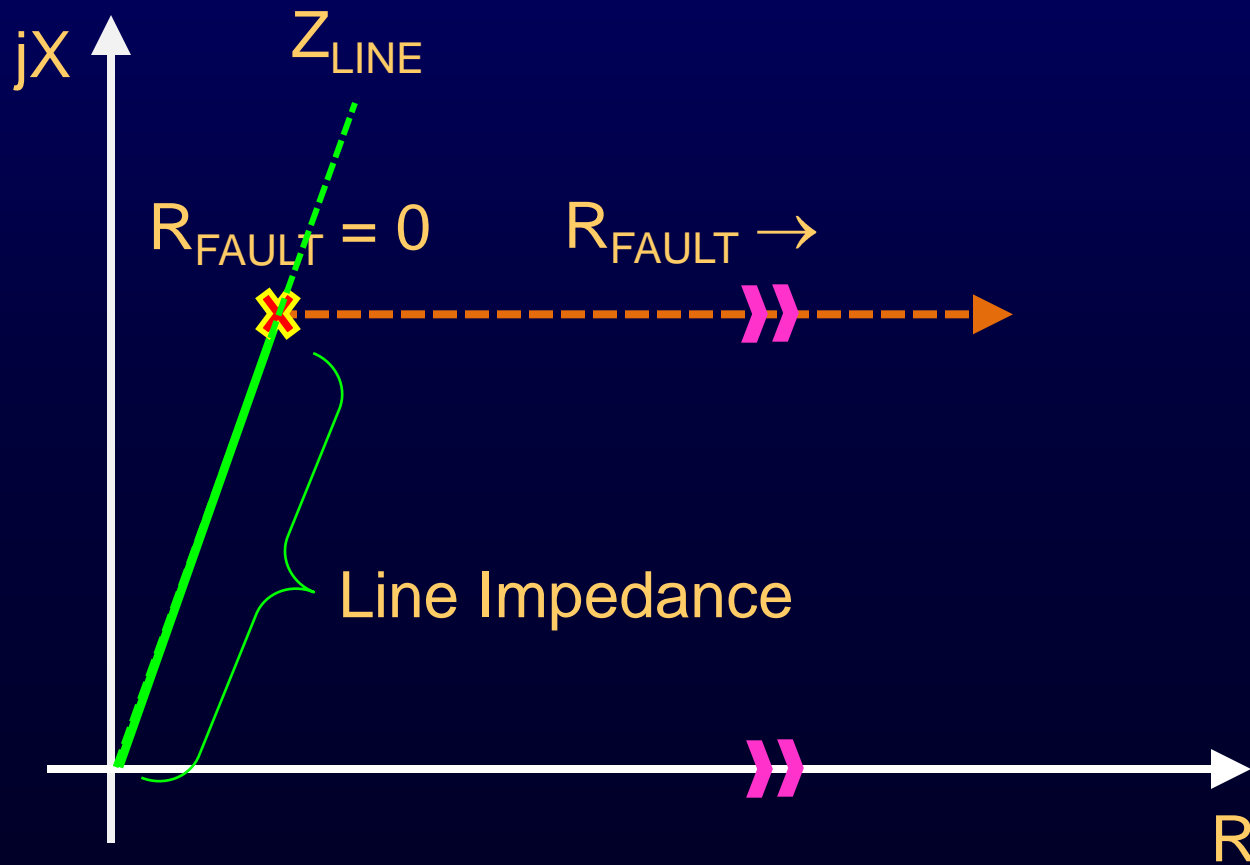
Uses Only Local Current and Voltage



$$I_{LINE} = I_{FAULT}$$

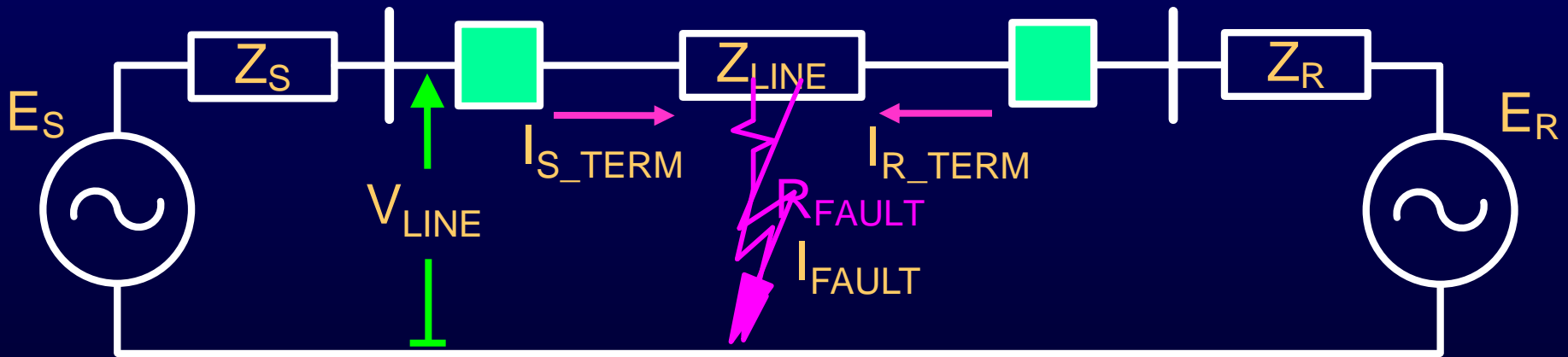
∴ Radial System → Single-Ended Method

Single-Ended Method



Single-Ended Method

Multisource System



$$R_{FAULT} = 0$$

$$I_{FAULT} \neq I_{S_TERM}$$

No Problem

$$R_{FAULT} \neq 0$$

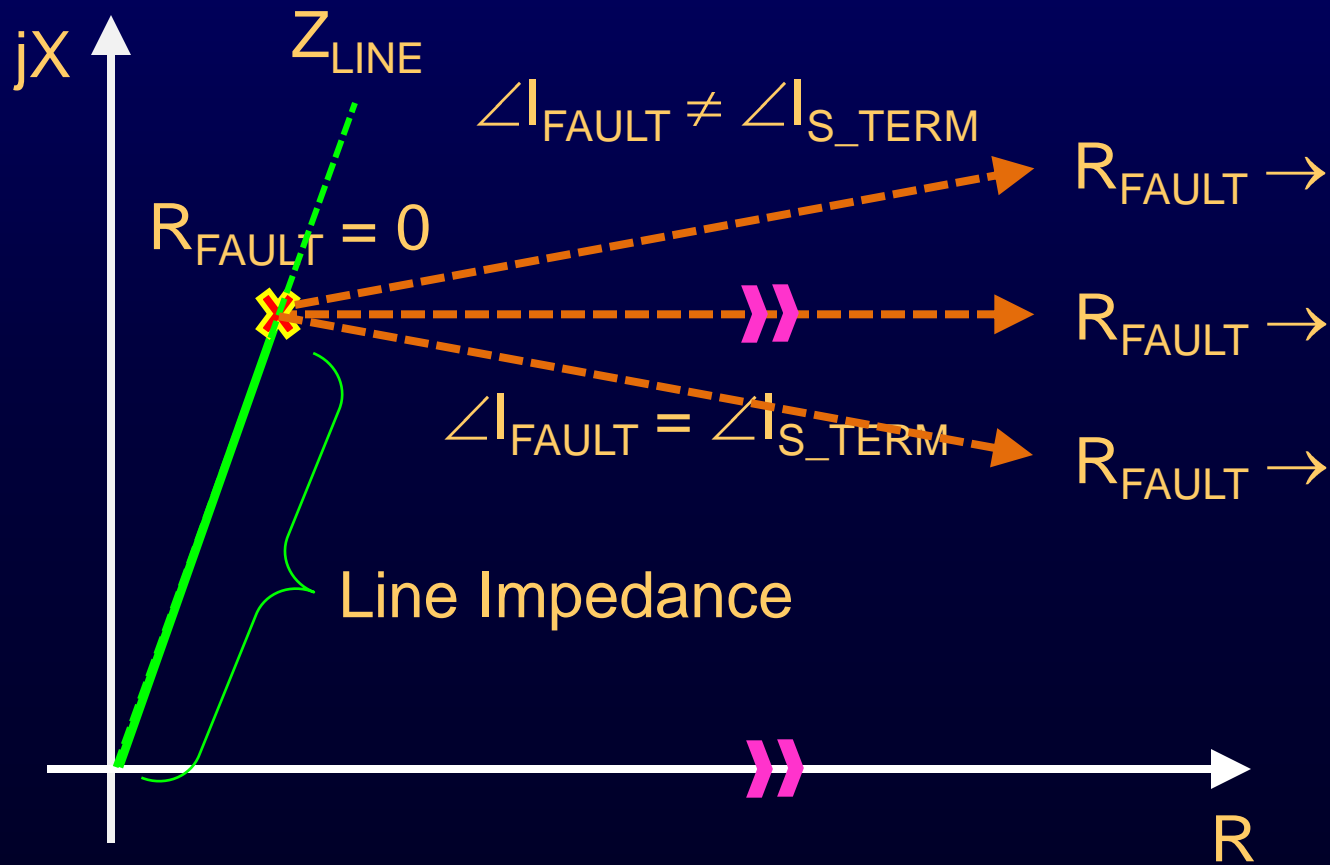
$$\angle I_{FAULT} = \angle I_{S_TERM}$$

No Problem

$$\angle I_{FAULT} \neq \angle I_{S_TERM}$$

Problem!

Single-Ended Method

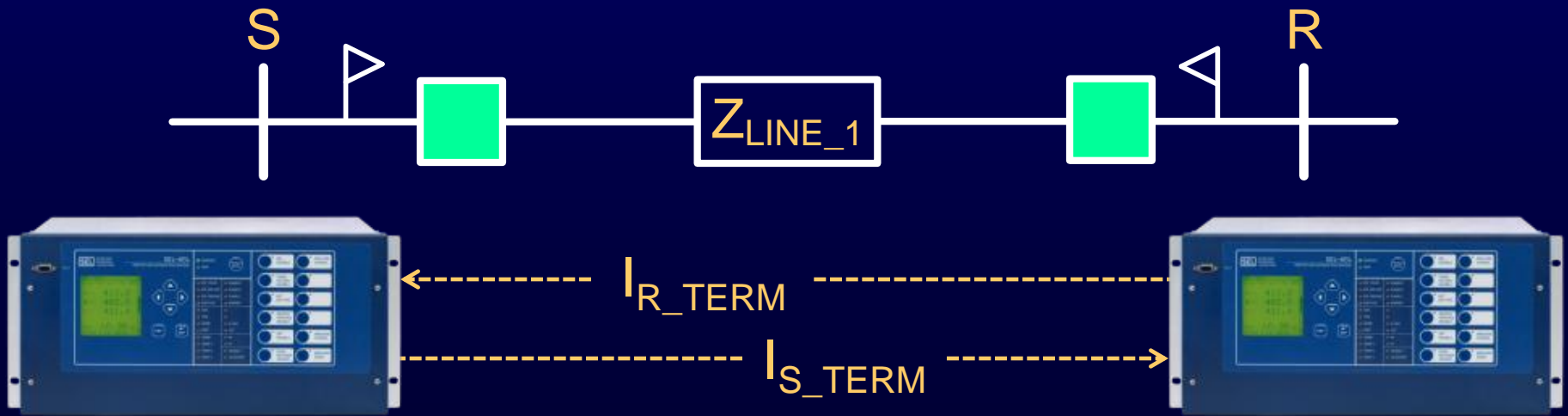


Multi-Ended Fault Location Requires Communications

- Real time
 - Between devices (*relays*)
 - Natural for line differential
- Offline
 - Between devices and data concentrator (central unit)

Multi-Ended Fault Location

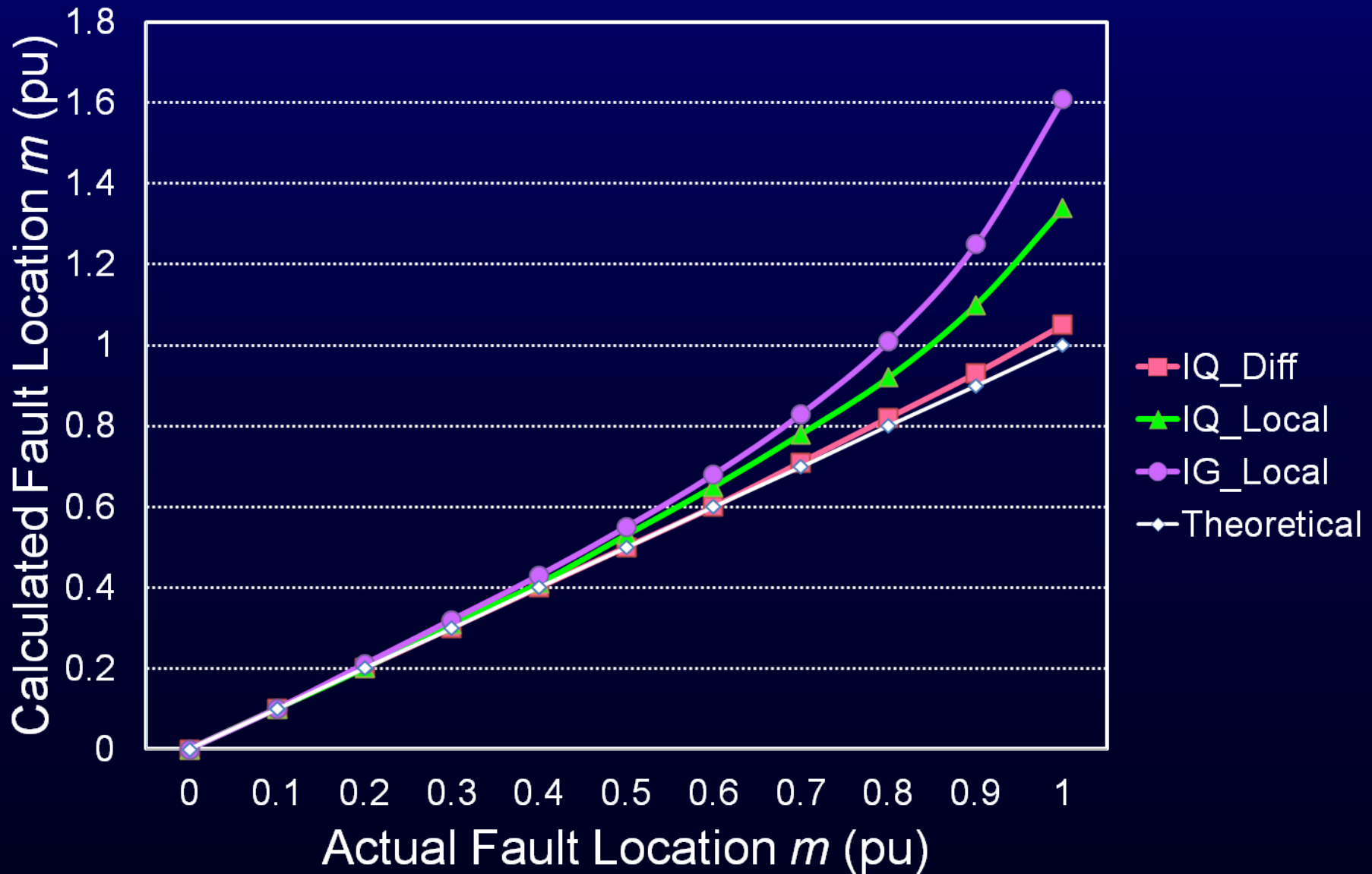
Real Time



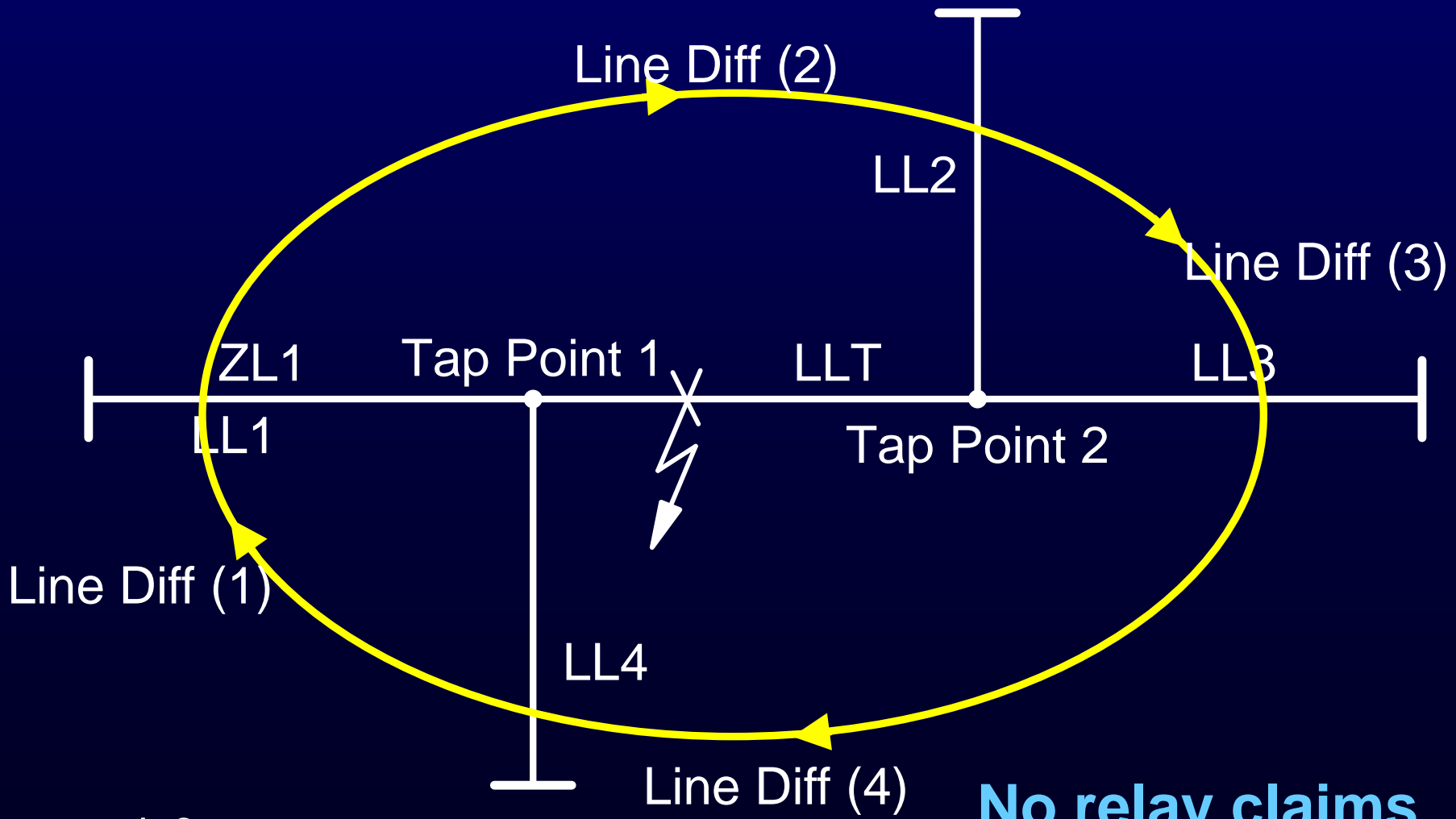
Distance =

$$\frac{\text{Im}\{V_L \cdot (I_{R_TERM} + I_{S_TERM})^*\}}{\text{Im}\{I_L \cdot Z_L \cdot (I_{R_TERM} + I_{S_TERM})^*\}} \cdot \text{Line Length}$$

Impact of Polarizing Quantities



Four-Terminal FL Between Taps



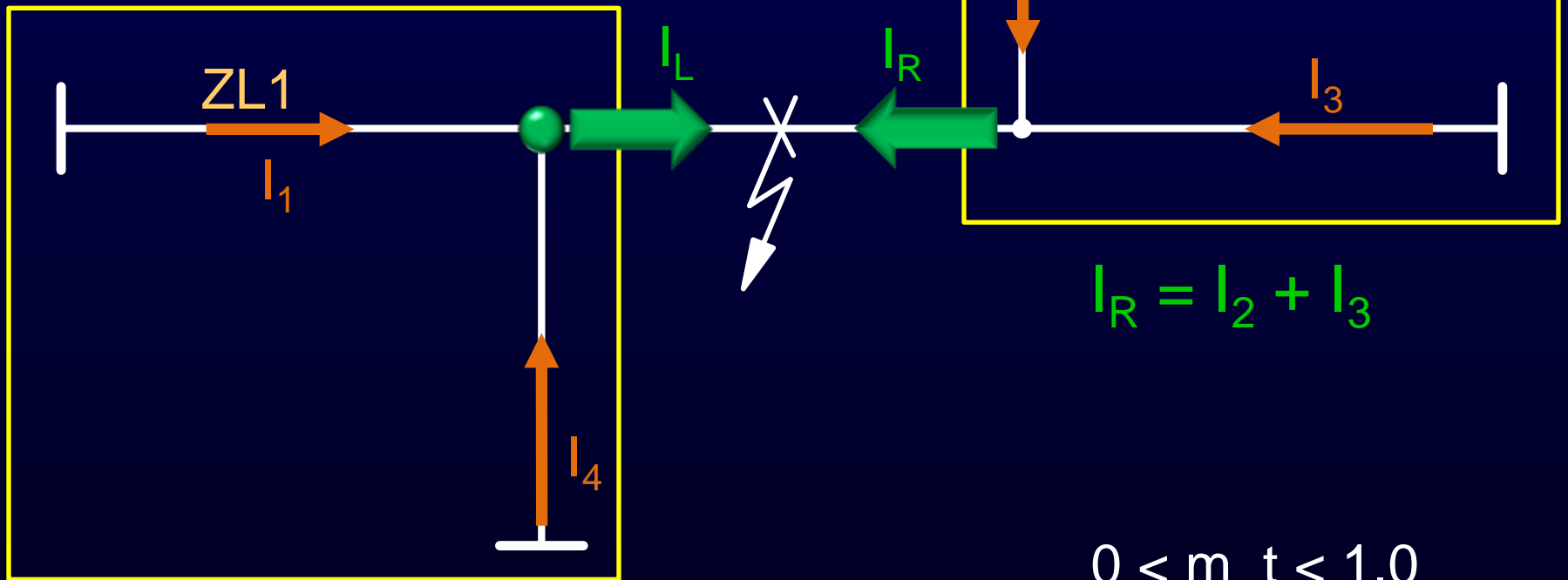
$m > 1.0$
Fault not in my section

**No relay claims
fault in own section!**

Four-Terminal FL Between Taps

$$I_L = I_1 + I_4$$

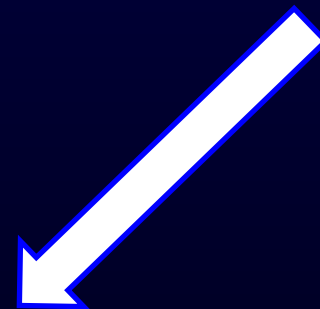
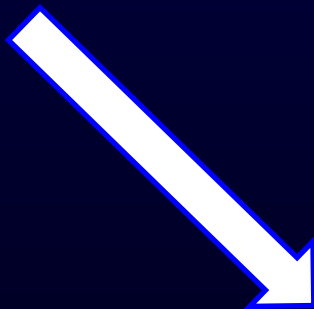
$$V_{TAP} = V_1 - (I_1 + k_0 \cdot I_{G_{-1}}) \cdot Z_{L1}$$



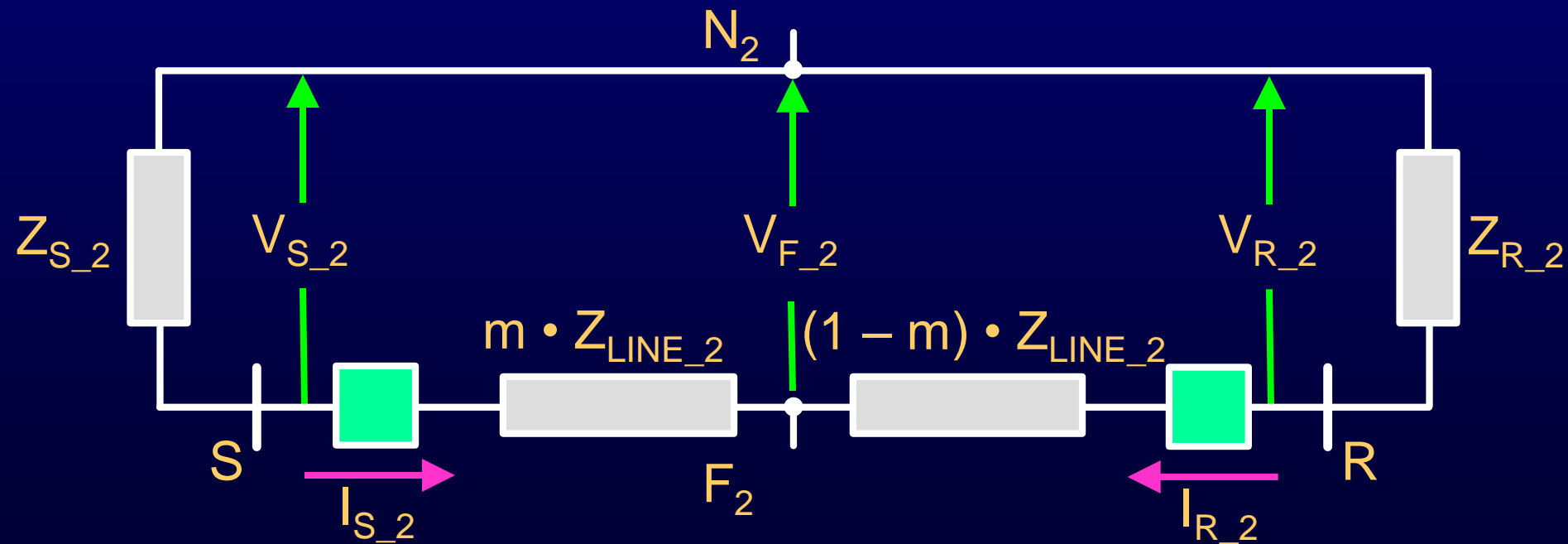
$$0 < m_t < 1.0$$

Fault in middle section

Multi-Ended Fault Location Offline



Use Negative Sequence



Terminal S:

$$V_{2_F} = V_{S_2} + m \cdot Z_{LINE_2} \cdot I_{S_2}$$

Terminal R:

$$V_{2_F} = V_{R_2} + (1 - m) \cdot Z_{LINE_2} \cdot I_{R_2}$$

Solve for m

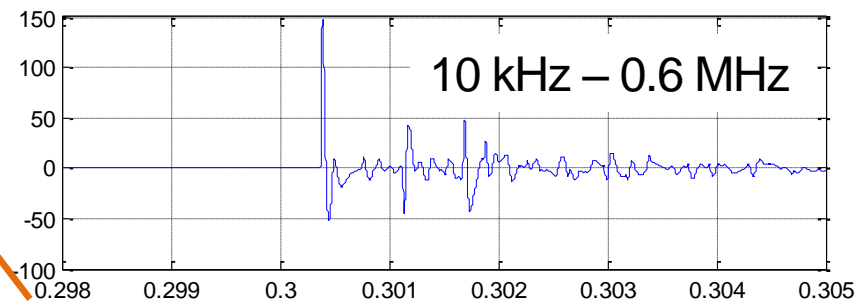
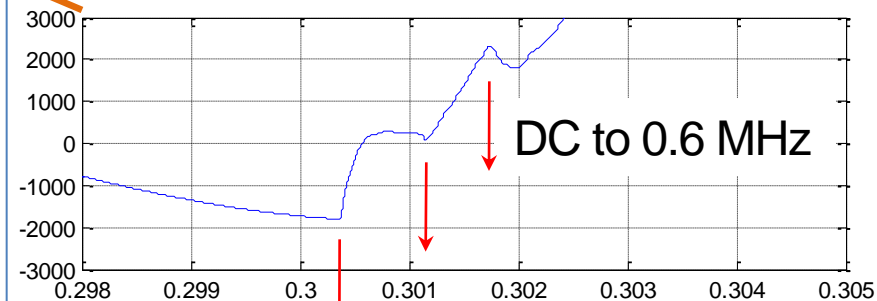
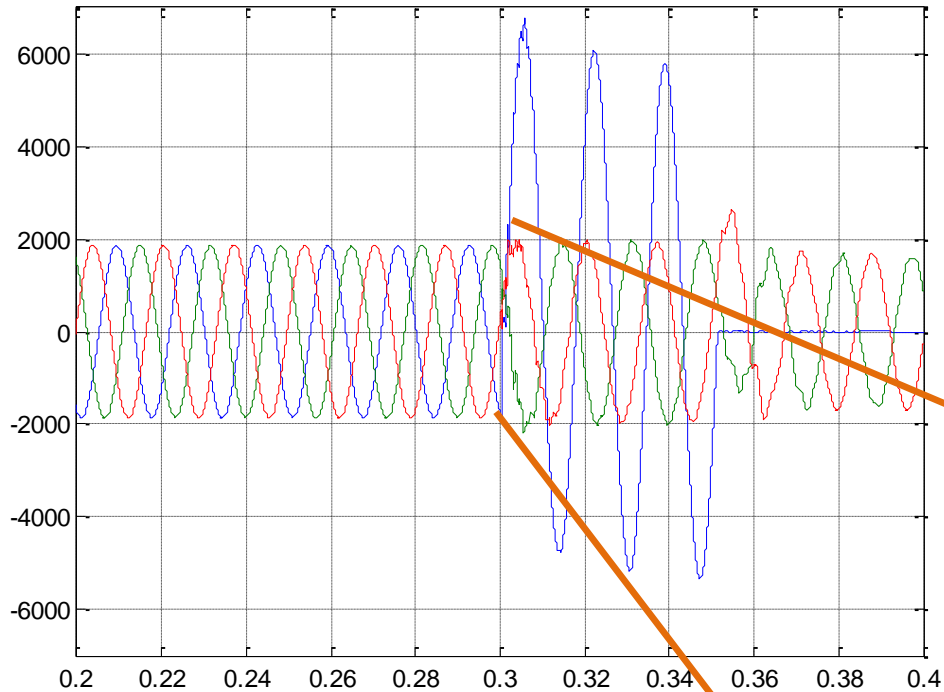
$$m = \frac{V_{R_2} - V_{S_2} + Z_{\text{LINE}_2} \cdot I_{R_2}}{Z_{\text{LINE}_2} \cdot (I_{R_2} + I_{R_2})}$$

Traveling Wave

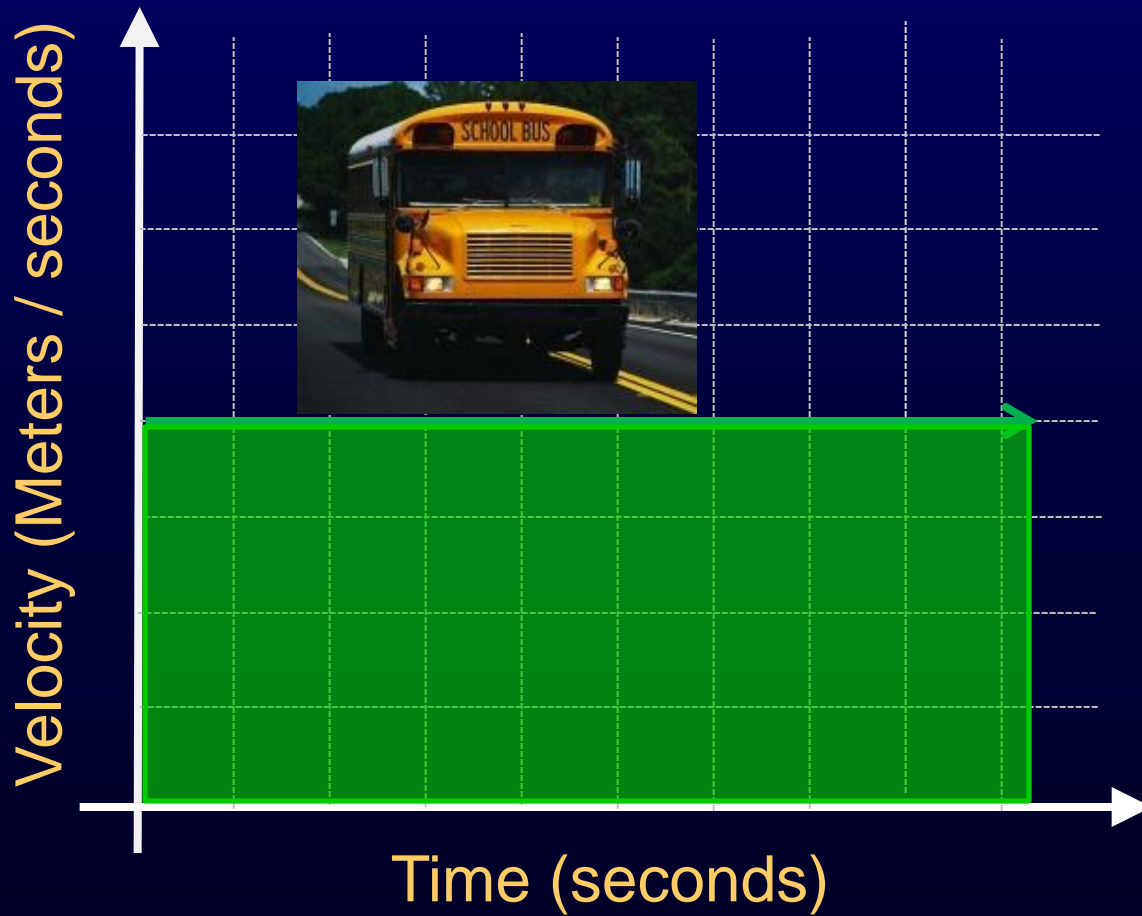
- Can locate faults within 300 m (0.2 miles)
- Works great for series-compensated and parallel lines
- Keeps high resolution regardless of line length

Transients Contain FL Information

High-frequency transients contain precise information about location of the fault



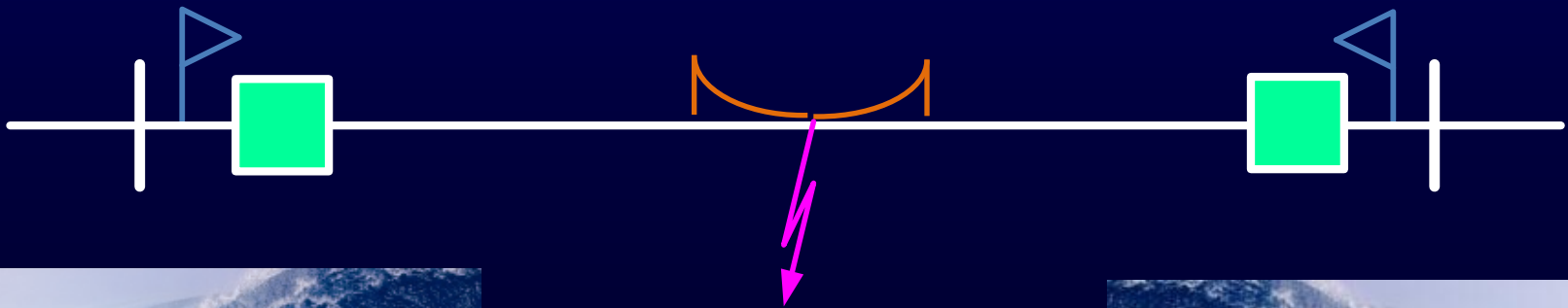
Basic Physics Revisited



Distance =
Velocity • Time

$$s = u \cdot t$$

Theory of Traveling Wave



Calculating the Fault Distance

Find the phase velocity (v_p) of the TW

$$v_p = \frac{1}{\sqrt{\mu_0 \epsilon_0 \epsilon_r}} \quad \epsilon_r \cong 1 \quad v_p \cong 300,000 \text{ km / s} \\ (186,000 \text{ miles / s})$$

Calculate the travel time of the wave in the line

$$\tau_{\text{Line}} = \frac{\text{Line Length}}{v_p}$$

Calculate the distance to the fault

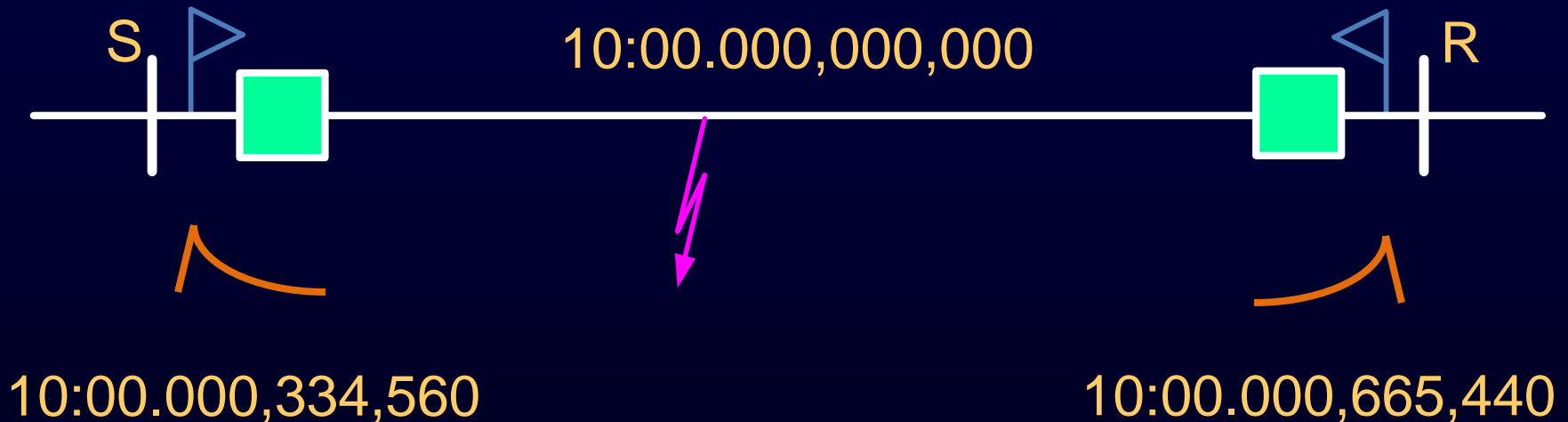
$$F_{\text{LOCATION}} = \frac{L_{\text{LENGTH}}}{2} + \frac{(t_{\text{S_TERM}} - t_{\text{R_TERM}})}{\tau_{\text{LINE}}} \cdot \frac{L_{\text{LENGTH}}}{2}$$

Example – What Is the Distance to the Fault?

Line = 300 km (186 mi)

$$v_p = 300,000 \text{ km / s}$$

$$\tau_{\text{LINE}} = 0.001 \text{ s or 1 ms}$$



Distance From Terminal S

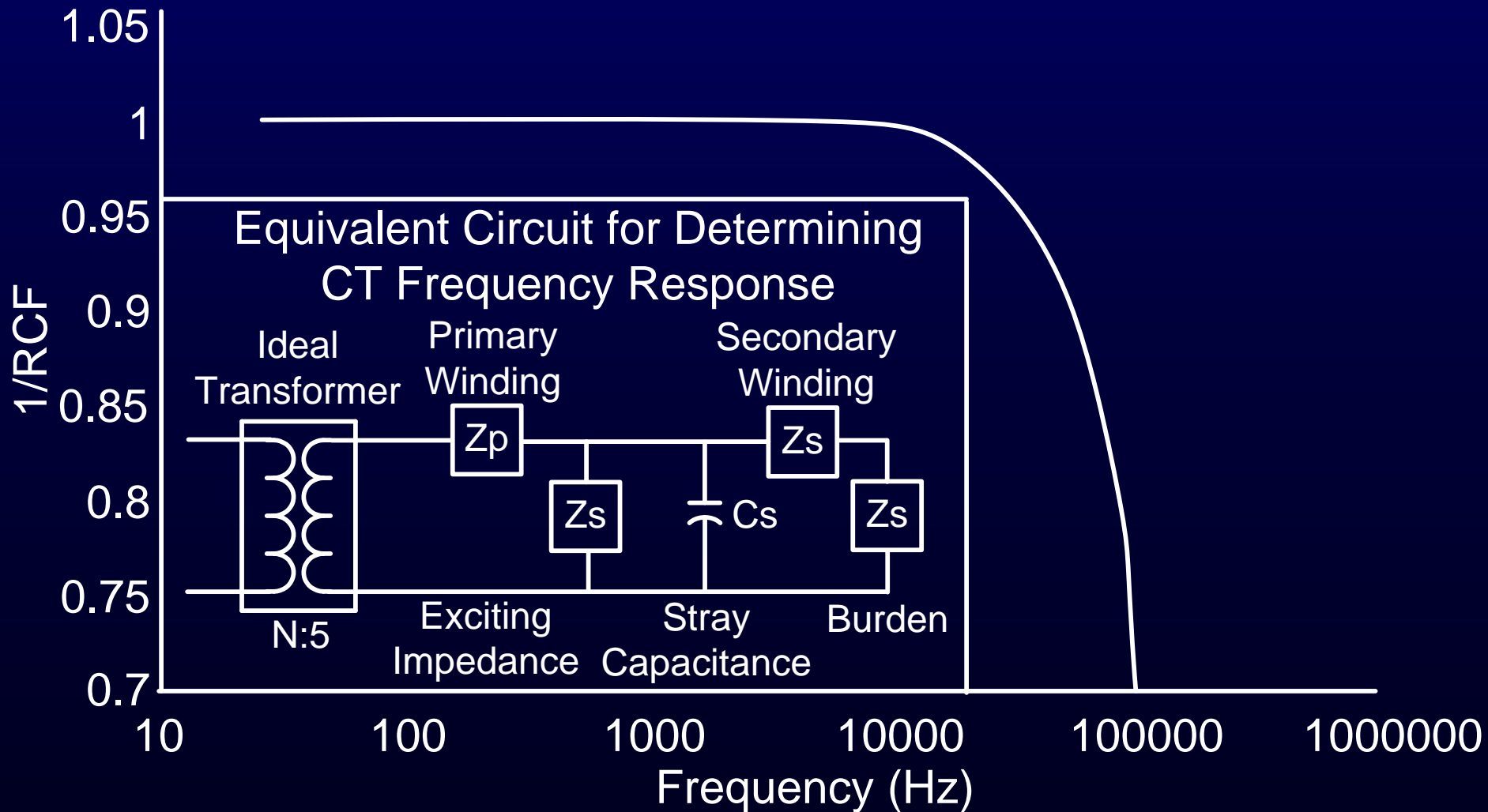
$$\begin{aligned}F_{\text{LOCATION}} &= \frac{L_{\text{LENGTH}}}{2} + \frac{(t_{\text{S_TERM}} - t_{\text{R_TERM}})}{\tau_{\text{LINE}}} \cdot \frac{L_{\text{LENGTH}}}{2} \\ &= 150 + \frac{(334,560 - 665,440)}{1,000,000} \cdot 150 \\ &= 100.368 \text{ km}\end{aligned}$$

Realizing the TW

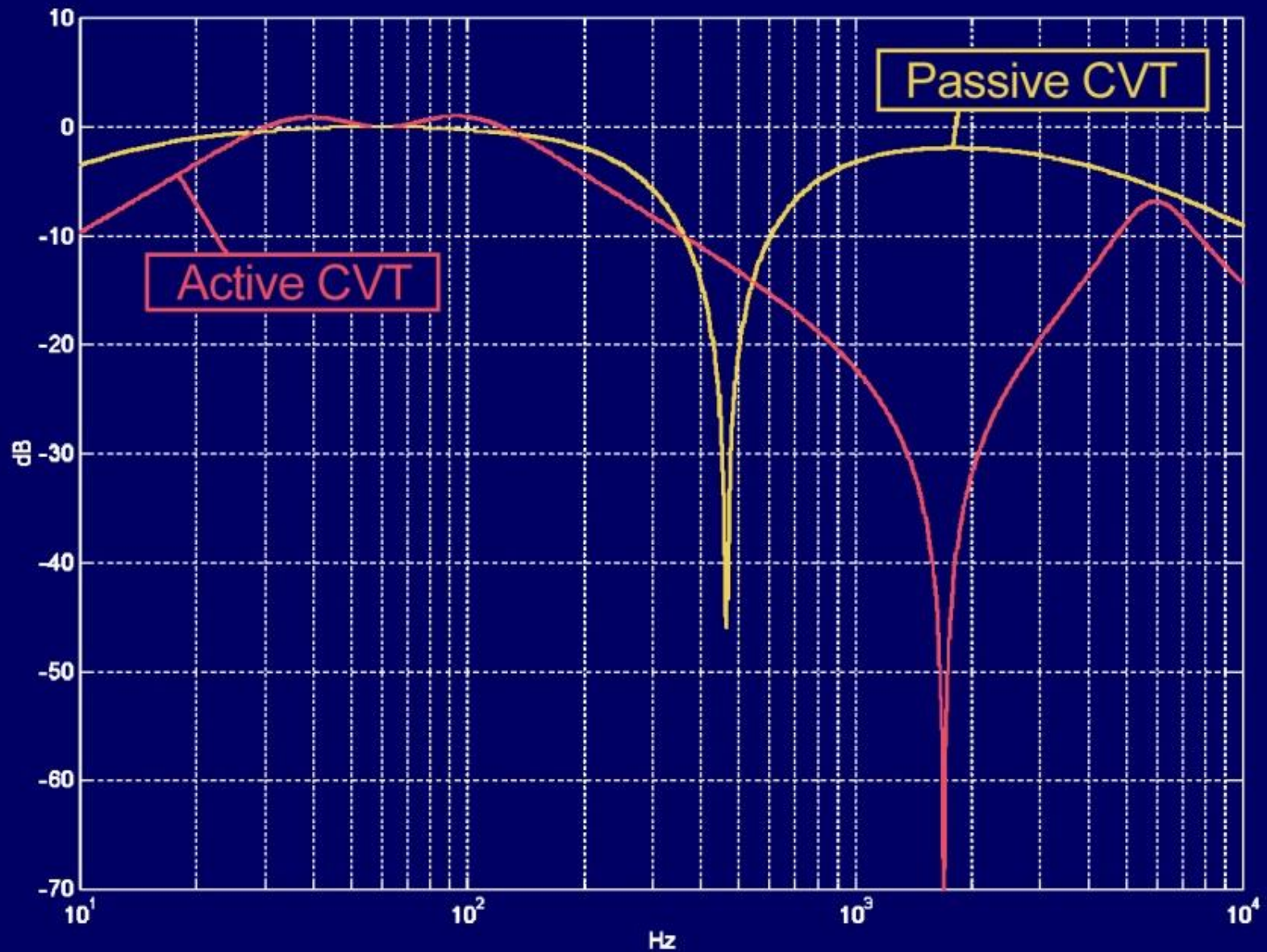


- Six current channels
- Sampling at 1.5625 MHz each
- 12-bit A/D converter

CT Bandwidth Is Adequate to Detect Traveling Waves



Frequency Response of CVT



Clarke Modal Transformations of TW

$$\begin{bmatrix} I_{0TW} \\ I_{\alpha TW} \\ I_{\beta TW} \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 1 & 1 & 1 \\ 2 & -1 & -1 \\ 0 & \sqrt{3} & \sqrt{3} \end{bmatrix} \begin{bmatrix} I_{ATW} \\ I_{BTW} \\ I_{CTW} \end{bmatrix}$$

Extract the aerial mode:

$$I_{\alpha TW} = 1/3 \cdot (2 \cdot I_{ATW} - I_{BTW} - I_{CTW})$$

v_p of aerial mode is $\cong c$ (speed of light)

TW Fault Locator Is Easy to Configure

Enable TW Fault Location (ETWFL)

TWLL

- Line Length

LLUNIT

- Units (miles, km)

SCBL

- Secondary Cable Length

LPVEL

- Line Propagation Velocity

TWATI

- Alternate TW Currents

Determine Line Propagation Velocity (LPVEL)

$$v_p = \frac{1}{\sqrt{\mu_0 \epsilon_0 \epsilon_r}} = \frac{1}{\sqrt{LC}}$$

For a 500 kV line:

$$L_1 = 8.852 \cdot 10^{-7} \text{ H / m}$$

$$C_1 = 1.302 \cdot 10^{-11} \text{ F / m}$$

$$\begin{aligned} v_{p1} &= 2.946 \cdot 10^8 \text{ m / s} \\ &= 0.982 \text{ c} \end{aligned}$$



Questions?