Seminar

# Modeling and Simulation of Dynamical Systems

Presented by the IEEE Control Systems Society Santa Clara Valley

Sunnyvale, 5 February 2011





# Program

Welcome	08:45 – 09:10am	Coffee and bagels, Seminar kickoff at 9:00am
Session 1	09:10 – 10:00am	Mathematical models of dynamical systems Dr. P.K. Menon, Optimal Synthesis
Session 2	10:10 – 11:00am	System Identification - Theory and Practice Dr. Mark B. Tischler, Ames Research Center
Session 3	11:10 – 12:00am	Visualization and Virtual Environments Dr. Hadi Aggoune, Cogswell Polytech. College
Lunch	12:00 – 12:40pm	Sandwiches, sodas, discussions and product demos
Session 4	12:40 – 01:30pm	Applications of Hardware-in-the-Loop Simulators Christoph Wimmer, National Instruments
Session 5	01:40 – 2:30pm	Simulation with Software Tools Elliot English, Dr. Martin Aalund, Dr. Karl Mathia



2

Session 4

# Applications of Hardware-in-the-Loop Simulators

**Christoph Wimmer, National Instruments** 





#### Agenda

- Reason for HIL
- Components of a HIL System
  - Hardware
  - Software
- Summary

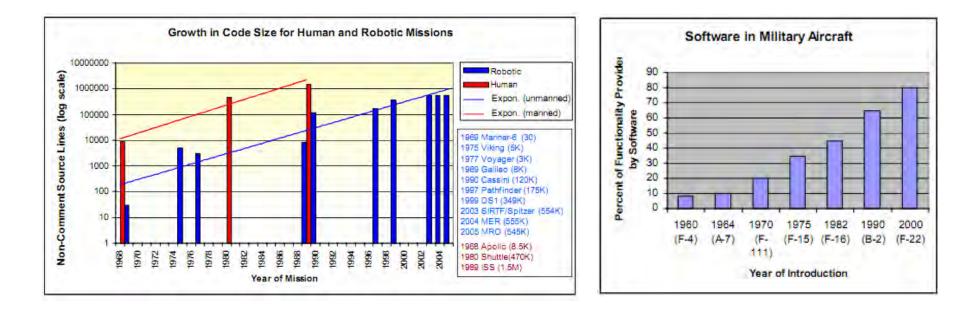




# **Increasing Software Content...**

#### Reality

- Software Growth
- SW enables Functionality



•http://www.nasa.gov/pdf/418878main\_FSWC\_Final\_Report.pdf



CSS

5

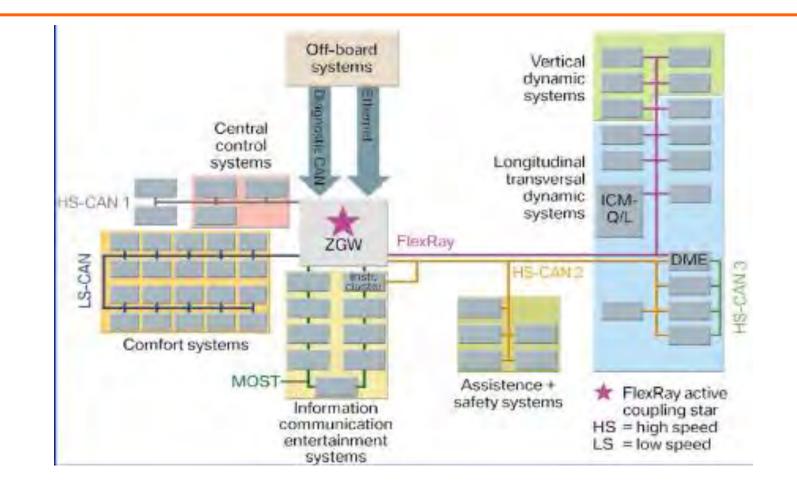


# ComplexityRisk, DamageTime to Market





#### Complexity

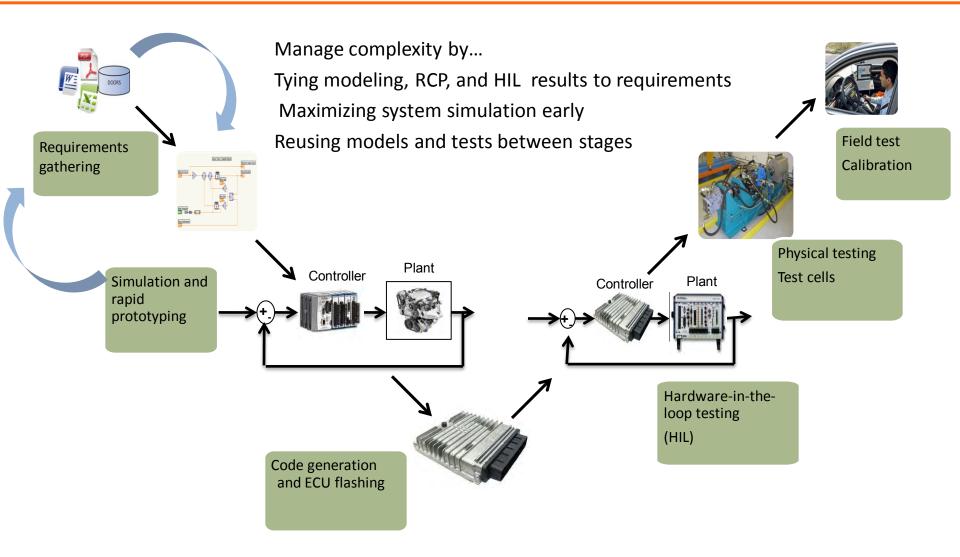


BMW 7 Series: 70 ECUs Lexus 460: 100 ECUs





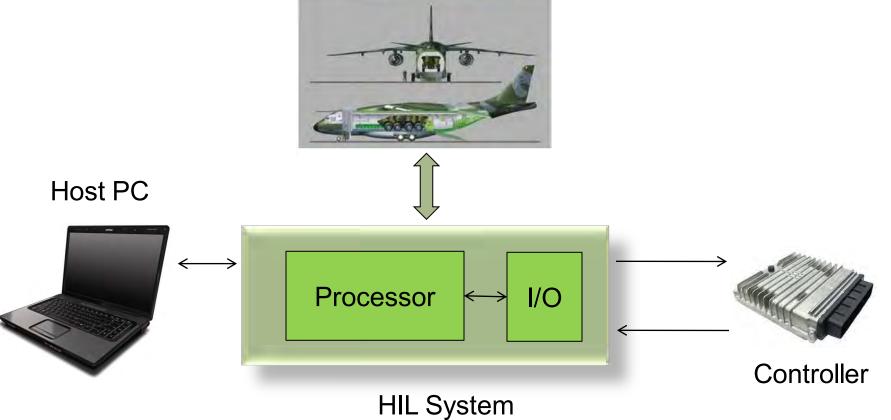
## **Embedded Software Development Process**





## **HIL Definition – Dynamic Test**

#### HIL didn't exist 20-25 years ago Roots in aviation





## **Components of a HIL System**

- A real-time target computer(s) with I/O.
- A host PC with communications link to target computer and diagnostic link to ECU.
- A Graphical User Interface (GUI) application to download and control the real-time process.
- A test automation application to automate all aspects of the test.
- A math model of the plant (i.e. engine or vehicle model).
- Sensor models
- Real or simulated loads
- Fault insertion relay matrix





#### **Aircraft Arrestor System**















# **Hydraulic Control System Testing**



"The out-of-the-box capabilities of NI VeriStand made it practical for us to develop an HIL test system, reducing our total testing cost by more than \$500,000." — Greg Sussman, CLA, Process Automation





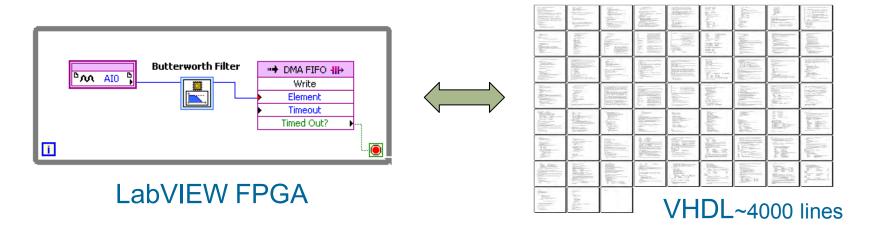
- AI (force), DI (stop), DO (limits)
- Loads (brake motors)
- Power Supplies
- Buses: fiber (ARINC, CAN, ...)
- Sensor Simulation (Encoder, TC, LVDT, ...)
- Fault Insertion Unit



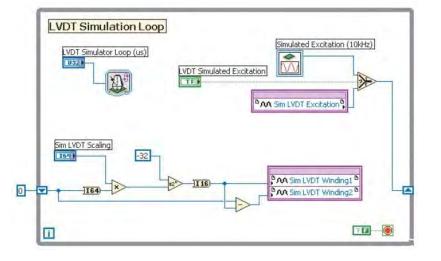


### **FPGA Sensor Simulation**





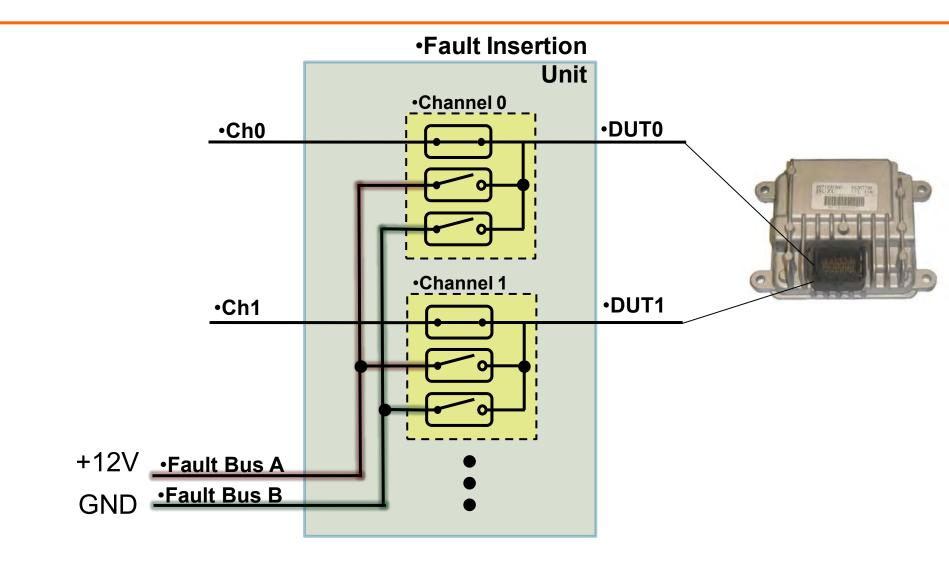
LVDT Simulation







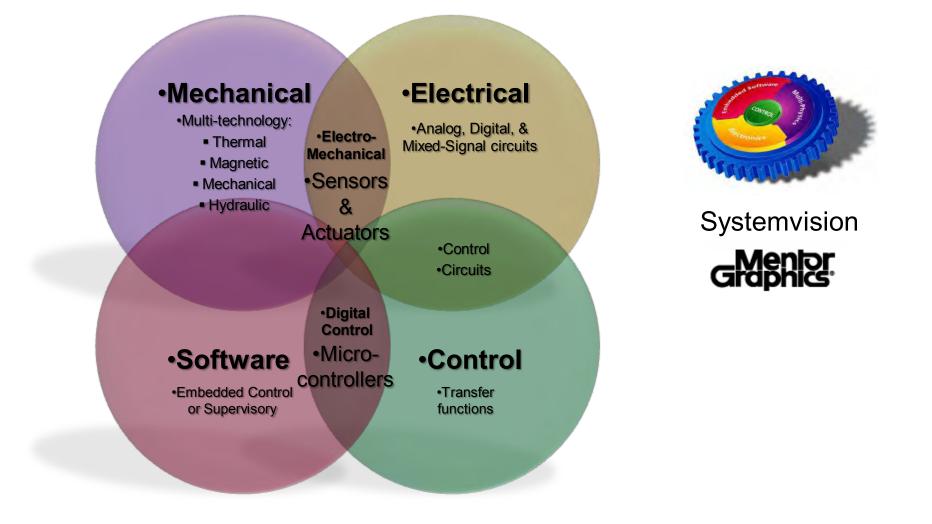
#### **Fault Insertion Unit (FIU)**







## The Challenge: Testing Your Multi-Domain System







## 

Powered by ITI

#### SimulationX Model Libraries

•Domain •SimulationX Model Elements (Samples) Signal Blocks A→D TCP/IP y u 🔤 RTW G(z) У ţ. Import ₩₩<u>i</u> ---2 ctr2 ctrl ctr2 ctrl Mechanics Powertrain ctrl ctr2 Դիլ-Ծծ / \$R / \$S / Electro-FOC  $/s_T$ ctr2 Mechanics ctrl / \$R / \$S / \$T •Magnetics pin2 pinl llтв Pneumatics portA portB portA ctr2 --> •Hydraulics R↓ P↑ ↓S portA2 portA2 portB2 D B B inl -portB portB port/ port/ portA Thermo portA1 portB1 portA1 portB1

•© 2009 ITI GmbH | www.simulationx.com

## **Open Platform**

- The MathWorks, Inc. Simulink<sup>®</sup> software
- NI LabVIEW
- C/C++
- MapleSim models from Maplesoft
- SimulationX from ITI
- Tesis DYNA models
- NI MATRIXx SystemBuild
- Esterel SCADE Suite
- C/C++

- CarSim from Mech Sim Corp.
- GT-POWER engine models from Gamma Technologies Inc.
- AMESim models from LMS
- VI-grade

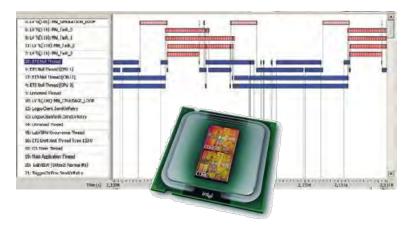


#### **Real-time Multicore Simulation**

Efficiently harness the data and task parallelism provided by the latest processor technologies

Distribute test system tasks across cores to increase system bandwidth

Execute models in parallel on multiple cores to improve performance

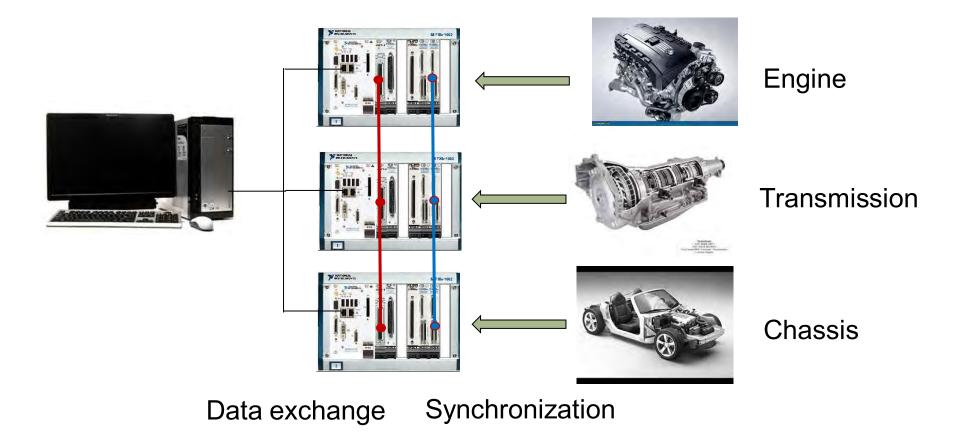


www.ni.com/multicore





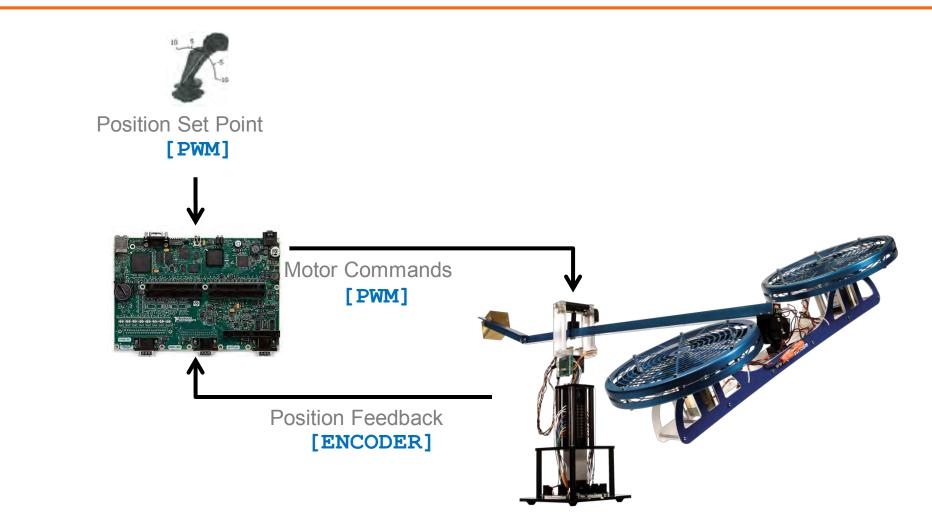
#### **Multi Chassis Simulation**







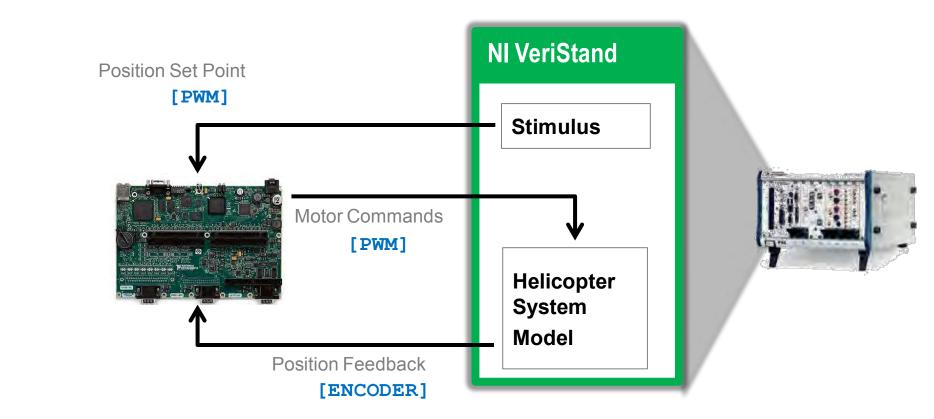
#### **Demo: Helicopter Controller Test System**







#### **Demo: Helicopter Controller HIL Test System**







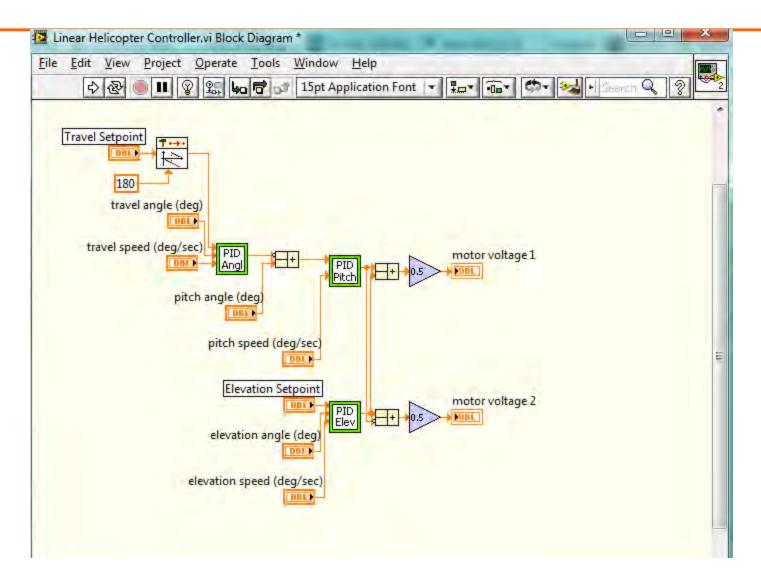
#### **Helicopter Model**

Linear Helicopter Model.vi Block Diagram *	1000	the Calls	
Eile       Edit       View       Project       Operate       Tools       Window       Help         Image: State of the	T 197 197 197 199	• Search	Q 2 24
motor voltage 1 123 motor voltage gain 123 motor voltage 2 123 123 123 123 123 123 123 12		travel angle (deg) pitch angle (deg) elevation angle (deg) vel speed (deg per sec) tch speed (deg per sec) ation speed (deg per sec)	output
N			





#### **Helicopter Controller**



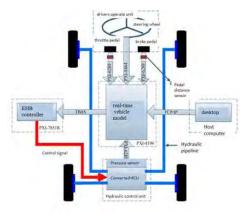




#### Driver-in-the-loop Test Platform for EHB System Using NI PXI

- **The Challenge:** The key to develop an EHB (Electro-Hydraulic-Brake) controller is to know the performance of actuator through extensive testing experiments, reduce the difficulties caused by real road test through effective parameter simulation and software simulation, and use virtual reality technology to develop a hybrid simulation platform where the actual manipulation of the driver in different virtual environment can perform functional verification of EHB rapid prototyping controller and demonstration of product properties.
- **The Solution:** Develop a wheel cylinder pressure measurement and control system with LabVIEW to control the high-speed switching electromagnetic valve of EHB system. Implement data acquisition (DAQ) and communication of steering wheel, electronic throttle, brake pedal and wheel cylinder pressure in HIL test. Integrate the real-time vehicle model generated with DYNAware software to VeriStand software platform
- Products: NI VeriStand, PXI-6289, LabVIEW, PXI-8196 RT, FPGA Module, Real-Time Module, PXI-1042Q, PXI-7851R, PXI-8464/2, PID and Fuzzy Logic





"Using NI software and hardware, we successfully developed a test platform for EHB hybrid simulation."

He Huang - Hefei University of Technology





# **HIL Software**



- Single-point I/O
- Calculated channels
- Stimulus generation
- **Test Automation**
- Data logging
- Alarming



• RT PXI



#### • RT PC



Industrial Controller



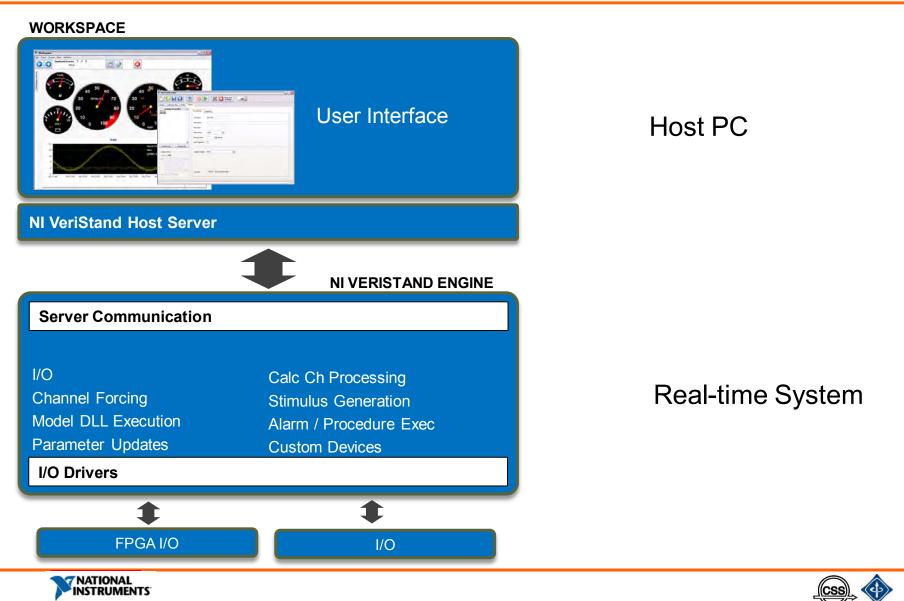
NI CompactRIO



•NI Single-Board RIO

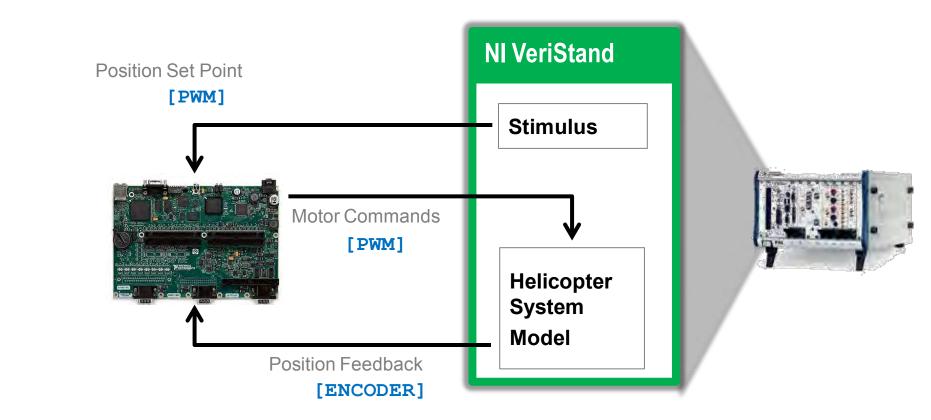
- Run-time editable user interface
- User management
- Multi-chassis synchronization
- Deterministic model execution

#### **NI VeriStand Framework**



27

### Demo 2: Helicopter Controller HIL Test System







# **Lear Electronics**



•Power     •Distribution	Body Electronics	Wireless	Bigh Power
Passive Junction Box Smart Junction Box Solid State Smart Junction Box (𝔅+JB™) Power Distribution Centers Pre- •Fuse Boxes Fuse Systems	Core Body Control Modules Gateway Modules Smart Trailer Tow Module Door Zone Modules Seat Heat Modules Seat Memory Modules	Remote Start / Keyless Entry Systems Car2U <sup>™:</sup> - 2Way RKE System - Universal Garage Door Opener Passive Entry & Start IntelliTire® – Tire Pressure Monitoring System Vehicle Immobilizer Wireless Control Module	DC-AC Inverter High / Low Voltage DC-DC Converter Battery Monitor Battery Charger Integrated Power Module High Voltage Power Distribution Center Charge Cord Set Manual Service Disconnect

$\langle \rangle$	Wiring
Low /	High Voltage Wire
Harne	sses

Alternative Wire Technology

Flex Fold Wire

Signal to High Power Terminals & Connectors

#### Infotainment

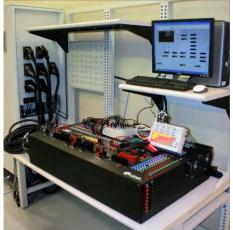
Sound System Tuning Amplifiers – Medium, Premium and Advanced Levels

TV Tuner

#### Connectors

Complete European Terminal & Connector Systems Signal to High Power Application Systems In-line and Board Edge Systems Sealed and Unsealed Systems

Flat Cable Systems



Lear is among the global leaders in electrical distribution and has strong market positions in key electronics products totaling \$1.9B in sales.

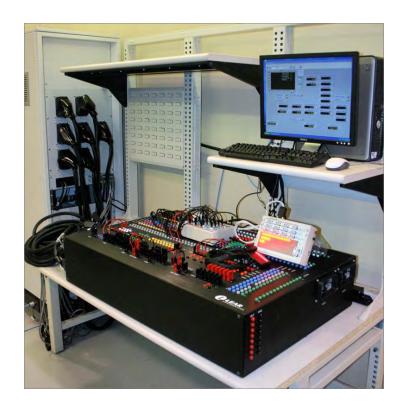




#### Lear Reduces Embedded Software Issues Using the NI HIL Platform

- The Challenge: Maintaining quality and reliability standards amidst the growing complexity of our embedded electronics products while meeting budget and schedule targets.
- The Solution: Adopting a new hardware-in-the-loop (HIL) test platform based on NI VeriStand real-time testing software and PXI hardware that provide the flexibility, efficiency, and intuitiveness necessary to address our current requirements with the ability to scale to future needs as we continue to expand our products.
- Products: Reconfigurable I/O Devices, NI PXI-8512 CAN/HS1, NI VeriStand Full Development System

#### <u>Learn more at ni.com</u>



"NI VeriStand has played a significant role in achieving the quality and reliability standards that have helped us win new automotive business."--Jason G. Bauman - <u>Lear Corporation</u>

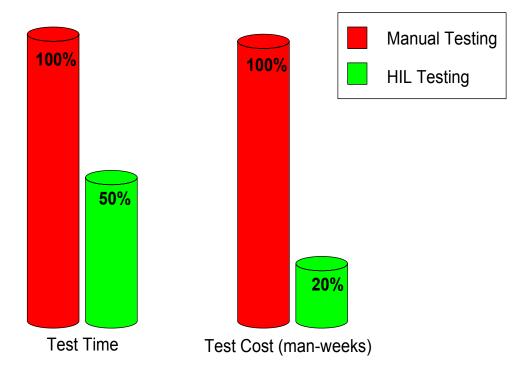




# Lear Systems Validation Results

#### **Testing Efficiencies**

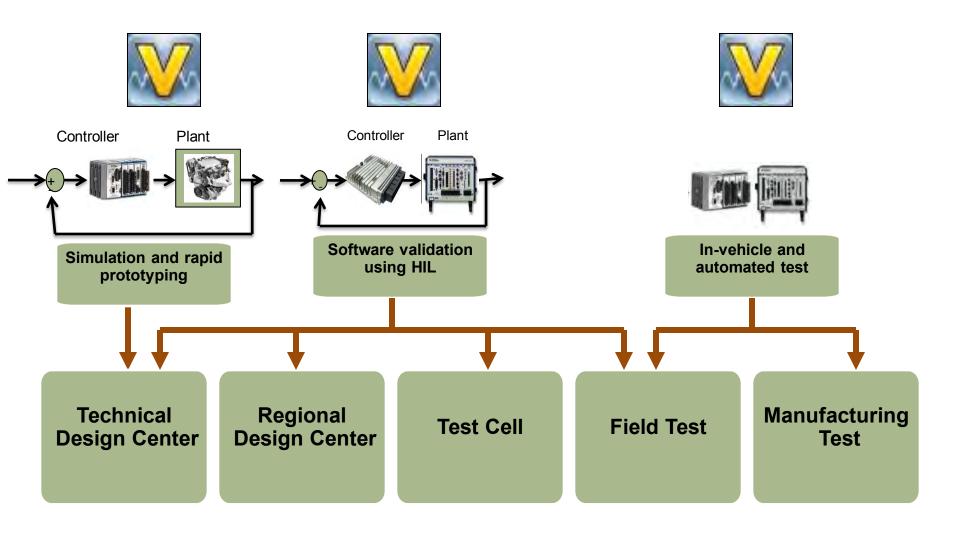
- Test cycle time cut in half
- Test resources reduced by 80% per validation cycle







## **Locations as Part of the Process**







### **HIL System Requirements**

- **Open** hardware & software platform
- Great variety, value, & availability of commercial off-theshelf (COTS) products
- Easily integratable I/O & FPGAs & processing platforms
- Multicore, Multisystem support
- Test platform that extends beyond HIL testing
- Global services, support, & partner expertise





## **Session 5: HIL Simulators**

# **Q & A**





#### **Additional Slides**





# **NI Profile**

Leaders in computer-based measurement and automation

Long-term track record of growth and profitability

More than 5,000 employees; operations in 40+ countries

*Fortune's* "100 Best Companies to Work For" 11<sup>th</sup> consecutive year

More than 500 alliance members worldwide

16% of revenue invested in R&D

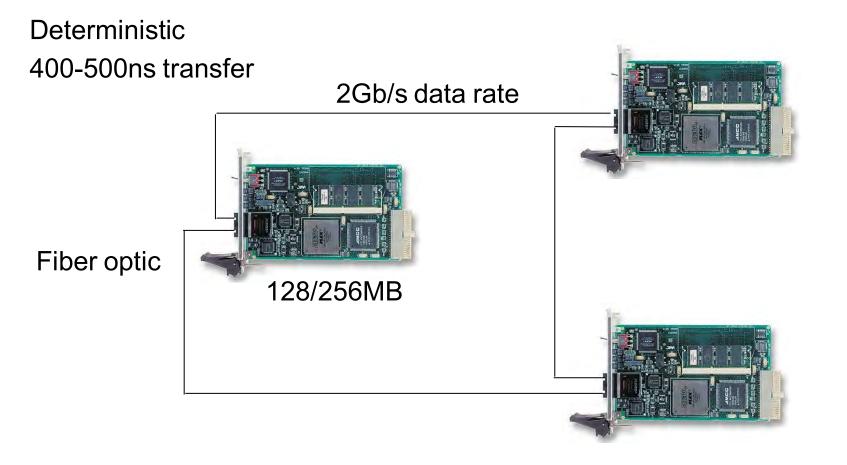
40% (\$50M) of R&D in real-time and embedded products

# •Revenue of

## \$872 Million in 2010



### **Reflective Memory**







[West 2001] Adam West. NASA Study on Flight Software Complexity,

http://www.nasa.gov/pdf/418878main\_FSWC\_Final\_Report.pdf, accessed Feb. 2011

- [Navet 2009] Nicolas Navet, In-Vehicle Networking: a Survey and Look Forward, <u>http://www.slideshare.net/REALTIMEATWORK/invehicle-networking-a-survey-and-look-forward</u> accessed Feb. 2011
- [Wikipedia] Hardwar-in-the-loop simulation, <u>http://en.wikipedia.org/wiki/Hardware-in-the-loop\_simulation</u> accessed Feb. 2011
- [Gomez 2001] Martin Gomez, Hardware-in-the-loop simulation, http://www.eetimes.com/design/embedded/4024865/Hardware-in-the-Loop-Simulation, EE Times accessed Feb. 2011
- [Bico 2009] Samir Bico, Siemens Wind Power Develops a Hardware-in-the-Loop Simulator for Wind Turbine Control System Software Testing, <u>http://sine.ni.com/cs/app/doc/p/id/cs-12344</u>, accessed Feb. 2011



