Design of Grounding Systems

(Impedance and Current Path Control)

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GROUNDING CONSIDERATIONS

- Signal Reference Considerations
- Power Current Paths
- System Structure Ground Considerations
- Safety Concerns
- Testing Configuration Concerns
- High Frequency Specific Problems
- Differential & Common Mode Currents
- Low level Signal Concerns
- Ground as a Shield
- Cable Shielding

GROUND

 Usually the structure of a system, the fundamental electrical reference point for all subsystems and equipment contained therein. May or may not be intentionally current carrying. Used for purposes of safety, EMI and radiation shielding, and overall EMC considerations. Usually common with structure of boxes and equipment.

RETURN

- The path by which currents in the power and/or signal systems <u>returns</u> to the source of that power or signal. Often referred to as power return, signal return, primary power return, secondary power return.
 - Primary power return is the return for power currents from the system main power distribution system (and power returns for items not galvanically isolated from it.)
 - Secondary power return is the return for power currents in circuits galvanically isolated from the main power distribution system, usually on the "secondaries" or outputs of power supplies. Often common with the signal return system, since secondary power usually feeds the IC's, which have common signal and power return pins.

REFERENCE

- The 0 volt reference for any signal. That is, if a signal line is at 0 volts, it is at 0 volts relative to its reference point or line. Note references can be DC, AC or both. CAUTION!!: References at signal sources and signal receiving loads may not be at 0 volts with respect to each other, see COMMON MODE voltage and voltage offset, below. Reference is usually common with the secondary power return and signal return.

SINGLE POINT GROUND

 A condition wherein a power or signal return makes contact with the system ground at only one point. Useful for controlling current paths in primary (main) power distribution. Only valid at low frequencies (less than 10 KHz or so).

MULTI-POINT GROUND

 A condition wherein a power or signal return makes contact with the system ground at more than one point, sometimes at some distance apart.

GALVANIC ISOLATION

A condition in which two circuits or wires within circuits are not connected together. That is, would measure some very high resistance (e.g., 1 Megohm) on a DC ohmmeter, if the ohmmeter was placed between the two points. Can be achieved by two circuits having no common elements (two completely unrelated circuits), or by transformer or optical isolation. (Also by capacitive isolation if capacitors are placed in both signal line and return.) Applicable basically at DC only.

GALVANIC COMPATIBILITY

A condition where the materials forming two conductors can be placed in intimate physical and electrical contact, in the presence of atmospheric moisture, without corrosion of one or both materials taking place. (Two incompatible materials can be made compatible by interposing a plating, shim, etc. of a third material between them, the third material being compatible with each of the two other materials.)

SINGLE-ENDED

A signal transmission method in which the references for both signal source and signal receiver are electrically connected together, desirably with both references being a 0 volts with respect to each other. Often characterized by a signal representing one line on a schematic, whose reference on each end is the signal return and/or secondary power return for the source and signal receiver. Voltage offsets between the references can affect single-ended signals.

DIFFERENTIAL

A Signal transmission method having the total signal as two complementary voltage wires (one goes positive with respect to the reference, while the other is simultaneously going negative the same amount) with respect to the source and receiving end references. Differential signals are "balanced", (e.g., one line at +1 volt, while the other is at -1 volt). Or they can be "offset", (e.g., one line at +3 volts while the other is at +1 volt with a + 2 volt reference offset). The signal receiver ignores the offset and voltages between the source and receiver references, considering only the voltage difference between the two differential lines. CAUTION!!: A reference (return) wire <u>must</u> be sent between the source and receiver. It will normally not work with a true open circuit between the source and receiver references.

10/28/02 wgi

COMMON MODE VOLTAGE

Voltage offset between the source reference (or return), and the receiver reference (or return). May be AC or DC. (Usually used in connection with differential transmission, but applies to single ended, as well). Also, a voltage that appears in the same magnitude and polarity at both receiver inputs (with respect to the receiver reference).

DIFFERENTIAL MODE VOLTAGE

 Voltage between the two signal lines of a differential transmission system (Also called "Normal" mode voltage)

COMMON MODE REJECTION

The ratio of the receiver output for a differential mode voltage, and a common mode voltage. A differential receiver that provides 1 volt output for 1 volt of differential input voltage, but would require 1000 volts of common mode voltage to provide the same 1 volt output would have a common mode rejection of 1000:1, or 60 dB

DIFFERENTIAL MODE CURRENT

 A current that flows in one direction in one wire of a differential pair, and the opposite direction in the other wire. In the return line (reference), the two currents cancel, providing 0 net current. Can be AC or DC.

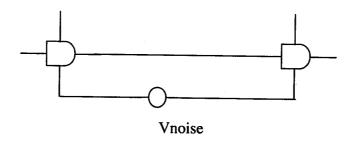
COMMON MODE CURRENT

- A current that flows in the same direction in both wires of a differential pair, and of the same magnitude. Since both currents flow in the same direction, they add at the receiver, producing twice the current in either line of the differential pair. Can be AC or DC.
- Power lines of single-point grounded or isolated power systems can also have differential mode currents (the actual current flowing from the power input, and returning on power return), and common mode currents (currents of the same magnitude and polarity in each power line, returning via the structure, or ground, path)

SAFETY GROUND

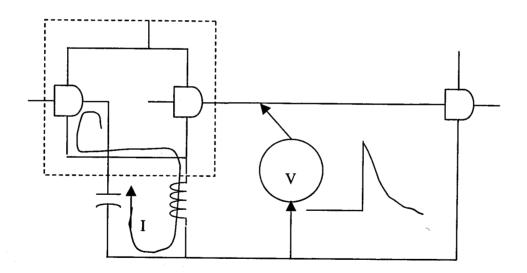
- The safety ground system is that system such that, if a human being touches two different points on the grounding system (e.g., a piece of structure and a box external case), he/she will not be exposed to hazardous voltages.
 - NOTE: Human beings are subject to electrocution by touching two items at voltages equal to or more than 60 volts apart!! A2100 POWER SYSTEM VOLTAGES ARE <u>LETHAL</u> TO HUMANS!!
- Humans or equipment can also be damaged by flying hot metal in an arc formed by separating two conductors that were previously carrying significant current. This condition can exist at voltages as low as 10-12 volts, and currents as low as 0.5 amp.
- COMPANIES <u>AND INDIVIDUAL ENGINEERS</u> ARE SUBJECT TO LEGAL ACTION, IF SOMETHING THEY DESIGNED INJURES OR KILLS SOMEONE, INCLUDING THEIR OWN EMPLOYEES!!! TAKE HEED!! <u>SAFETY IS EVERYONE'S BUSINESS!!</u>

• Voltages between the signal reference ("grounds") of signal sources and loads can cause interference to system functionality (or damage)

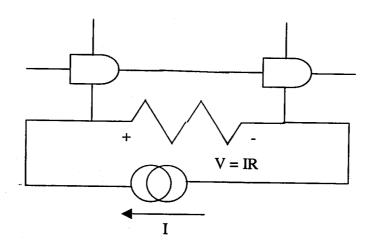


- Magnitude of voltage that will cause problems is circuit dependent
 - Smaller signals potentially more vulnerable
 - Concern also dependent on circuit bandpass (sensitivity may be to noise significantly different in frequency than desired signal)

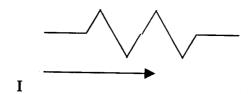
- So how can we get voltages between sources and loads?
 - Magnetic or Capacitive Coupling (discussed later)
 - Currents flowing in the impedance between source & load
 - Circuit's own currents (e.g., "ground bounce")



- So how can we get voltages between sources and loads?
 - Currents flowing in the impedance between source & load
 - Current generated by other circuits
 - Called "Common Impedance" coupling



So how can we get the voltages between source & load small enough?

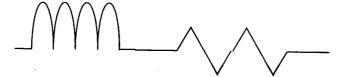


$$V = I \bullet Z$$

- $V \rightarrow 0$ if:
 - $I \rightarrow 0$ or
 - $-Z \rightarrow 0$
 - Or both
- So either prevent "bad" currents from flowing (minimize overall current magnitude), or minimize the impedance
 - What's a "bad" current? Any unnecessary current, particularly if it doesn't support the function of the circuit in question!!

Impedance Minimization

• In low impedance systems (like power lines, signal references), Z is dominated by R and L:



- At low frequencies, the reference is resistive
 - Minimize by making the wire or trace large cross-section area:

$$R = \frac{\rho l}{A}$$

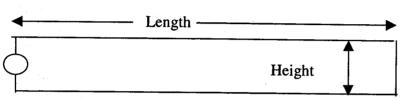
- Or by paralleling a quantity (n) of wires or traces:

$$R_t = \frac{R}{n}$$

• A ground plane is like a large number of parallel wires or traces

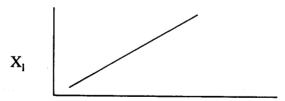
Impedance Minimization

- At high frequencies, impedance is a combination of resistance & inductance
- The current must flow in a closed path that has inductance.



$$L = \mu_r \mu_o 10.16 \cdot 10^{-9} \cdot [l \cdot \ln(\frac{2w}{d}) + w \cdot \ln(\frac{2l}{d})]$$

- μ_r and μ_o are material properties (permeability), μ_r =1 for non-magnetic materials
- 1 is length of the path
- w is width (or height) of the path
- d is diameter of wire (or largest dimension of rectangular wire)
- Inductance has an impedance (reactance) that increases with frequency
 - $X_1 = 2\pi x f x L$



- X_1 delays current in time (phase) compared to voltage so currents are not in phase with applied voltage (usually indicated by symbol j, the complex imaginary symbol) $X_1 = j 2\pi x$ f x L
- Inductance typically begins to dominate in the 1's Khz-10's KHz region

Skin Effect

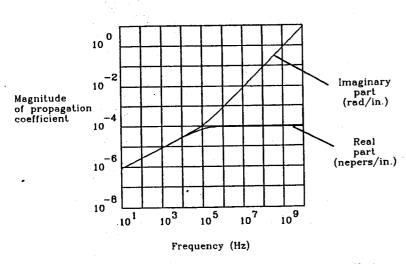


Figure 4.9 Propagation of a cable with fixed series resistance (no skin effect).

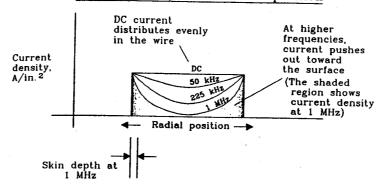
Low-loss region inductance, exceeds resistance; skin effect not significant Skin effect region RC Region resistance exceeds resistance rising as a function of frequency inductance 10 Series inductive 10 reactance (n per in.) Magnitude of reactance 10 -3 (v) Series resistance (n per in.) -5 10 107 103 Frequency (Hz)

Figure 4.10 Series resistance and series inductive reactance of RG-58/U coax versus frequency.

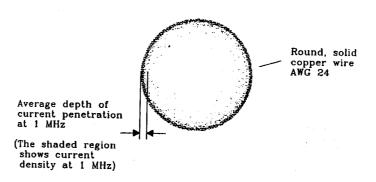
From "High Speed Digital Design", Howard Johnson/Martin Graham, © 1993, Prentice Hall PTR

Skin Effect

Current density versus radial position



Cross section of wire



From "High Speed Digital Design", Howard Johnson/Martin Graham, © 1993, Prentice Hall PTR

Skin Effect

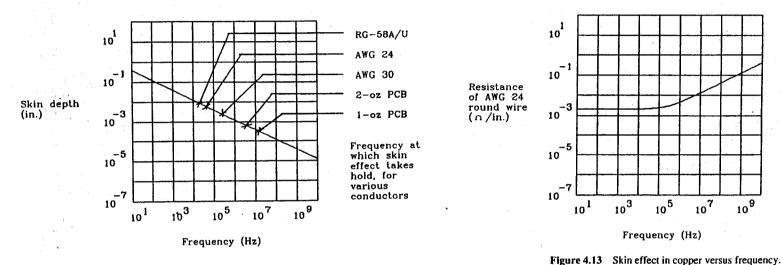


TABLE 4.1 SKIN-EFFECT FREQUENCIES FOR CONDUCTORS

Radius	Skin-effect frequency (KHz)
0.017	21
0.010	65
0.005	260
Copper	Skin-effect
weight (oz)	frequency (MHz)
2	3.5
2	3.5
1	14.0
1	14.0
	0.017 0.010 0.005 Copper weight (oz)

From "High Speed Digital Design", Howard Johnson/Martin Graham, © 1993, Prentice Hall PTR

IMPEDANCE OF STRAIGHT CIRCULAR COPPER WIRES

	AHG#=2,D=6.54mm						A¥C#=10	,D=2.59=	2	AWC #- 22 , D 64				
	freq.	t-la	t=10cm	t=Lm	t=10m	i-la	1=10cm	L=la	£=10m	t-lca	1=10cm	t-la	£=10m	
1	1000	3.23	31.4	527	5.50=	32.7 _u	327 <u>u</u> 328u	3.28m	32.8=	57 911 52 9u	5.29m	53.0=	529m	
-	20Ez	5.14u	52.0u	532u				1			5.30m	53.0m	530m	
1	308x	5.15u	52.8u	555u	5.94m	32.8u	328u	3.28m	32.9m	529u 530u	5.30m	53.0	530m	
ı	50Hz 70Hz	5.20u 5.27u	55.5u 59.3u	624u 715u	7.16m 8.68m	32.8u	329u 330u	3.30m 3.33m	33.2m 33.7m	530u	5.30=	53.0=	530=	
		<u> </u>				30.0	222	 	34.6	530u	5.30m	53.0m	530m	
7	100Hz	5.41u	66.7µ	877u	11.2=	32.9u	3321	3.38	1 -	I .	l .	1		
1	200Hz	6.20u	99.5u	1.51=	20.6=	33.2u	345u	3.67=	39.6■	530u	5.30ma	53.0m	530=	
.	300H≖	7.32u	137u	2.19m	30.4m	33.7u	365u	4.11m	46.9m	530u	5.30mx	53.0ma	531=	
1	500H.z	10.1u	219u	3.59€	50.3m	35.3u	425u	5.28ma	64.3m	530u	5.31m	53.2=	533a	
l	700Hz	13.21	303u	5.01m	70.2m	37.7u	500u	6.66m	84.8	530u	5.32m	53.4m	537≖	
١,	lkHz	18.1u	429u	7.14m	100=	42.2u	632u	8.91m	116=	531u	5.34=	53.9ma	545ma	
ı	2kHz	35.2u	855u	14.2m	200m	62.5µ	1.13m	16.80	225ma	536u	5.48ca	56.602	589 a	
١.	Jene	52.5u	1.28m	21.3	300m	86.Ju	1.65m	25.0m	336m	545u	5.71m	60.9	656ma	
1	SkHz	87.3u	2.13m	35.60	500m	137u	2.72=	41.5m	559ma	571u	6.39ma	72.9m	835m	
4	7kHz	122u	2.9800	49.812	700a	189u	3.79ma	58.1m	783ma	609u	7.28mg	87.9ma	1.04ព	
]	10kHz	174u	4.26	71.2m	1.00Ω	268u	5.41m	82.9	1.110	681u	8.89ma	113∞	1.39Ω	
1	20kHz	348u	8.53ma	142=	2.000	533u	10.8mm	165a	2.230	1.00m	15.2=	207 ma	2.63Ω	
١	30kHz	523u	12.8m	21.3m	3.00Ω	799u	16.2m	248=	3.350	1.39ma	22.0ma	305∞	3.91Ω	
ı	SUKEz	871µ	21.3m	356a	5.000	1.33m	27.0ma	414a	5.580	2.20ma	36.1m	504m	6.48Ω	
١	70kHz	1.22m	29.8m	498ma	7.000	1.86m	37.8ma	580ma	7.82Ω	3.04m	50.2m	704m	9.06Ω	
Ī	100kHz	1.74=	42.6m	712m	10.0Ω	2.66m	54.0m	828a	11.10	4.31m	71.6m	1.00Ω	12.90	
I	200kHz	3.48m	85.3m	1.420	20.00	5.32ma	108m	1.650	22.3Ω	8.59ma	142m	2.00Ω	25.80	
ı	300kHz	5.23=	128m	2.130	30.00	7:98m	162m	2.480	33.50	12.8m	214m	3.01Ω	38.70	
I	500kHz	8.71m	213m	3.560	50.0Ω	13.3≈	270a	4.140	55.8Ω	21.4m	357ma	5.01Ω	64.60	
	700k#z	12.2m	298ma	4.98₽	70.00	18.6ma	378m	5.800	78.2Ω	30.0mg	500ma	7.02Ω	90.4Ω	
ľ	lMHz	17.4m	426 a	7.120	100Ω	26.6m2	540m	8.280	1110	42.8m	714m	10.00	1290	
1	21:fHz	34.8m	853m	14.20	200Ω	53.2m	1.080	16.50	223Ω	85.7m	1.420	20.00	258Ω	
١	MEz	52.3m	1.280	21.30	3000	79.8m	1.62Ω	24.80	335Ω	128m	2.140	30.19	387 ณ	
١	SMHz	87.1m	2.130	35.60	500Ω	133=	2.70Ω	41.40	558Ω	214m	3.570	50.1Q	646Ω	
ı	7HHz	122=	2.980	49.8Ω	700Ω	1860.	3.780	58.00	782Ω	300≖	5.00Ω	70.2Ω	9040	
t	10ME	174=	4.260	71.20	1.00₺Ω	266a	5.40Ω	82.80	1.1112	428m	7.140	100Ω	1.29kn	
	20MEs	348m	8.53Q	142Ω	2.00kg	532m	10.8Ω	1650	2. 23kΩ	857m	14.20	200Ω	2.58140	
١	30MEz	523m	12.80	2130	3.00₺0	798=	16.2Ω	2480	3.35kg	1.28Ω	21.40	3010	3.87120	
ľ	50HH±	871m	21.30	356Ω	5.00kg	1.330	27.0Ω	4140	5.5820	2.140	35.70	501Ω	6.46kn	
	7 OHEL 2	1.220	29.80	498Ω	7.00kg	1.86Ω	37.8Ω	2802	7.82kΩ	3.00Ω	50.0Ω	7 02 Ω	9.04 14.0	
	100MEz	1.740	42.6Ω	712Ω	10.0kΩ	2.66Ω	54.00	8280	11.1kΩ	4.28Ω	71.40	1.00143	12.9kn	
•	200 .08 z	3.480	85.3Q	1.421Ω	20.0kg	5.320	1080	1.65kg	22.3kg	8.57Ω	1420	2.00kg	25.8140	
	300 . 01.z	5. 230		2.13k0	30.0೬Ω	7.980	1620	2.48 <u>to</u>	33.5kg	12.80	2140	3.01kg	38.7140	
	500HI	8.710	2130	3.56kg	50.0kg	13.30	2700	4.1410	55.8160	21.40	357Ω	5.01kn	64.6km	
	700me	12.20		4.98kg	70.0kg	18.60	3780	5.80%	78.2kΩ	30.00	500ก	7.02%0	90.4₺Ω	
	1Cas	17.40		7.1210	. 27 2	26.60	3400	8.28kg		42.80	7140	10.010		

^{*} AWG = American Wire Gage

Non-Valid Region for which $\pm \ge \lambda/4$

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⁼ wire diameter in mm

⁼ wire length in cm or m
= microhms

⁼ milliohms

IMPEDANCE OF PRINTED CIRCUIT BOARD WIRING

		v=l==, t=0.03==					~3 = ,	c=0.03=	2	₩10mm, t=0.03mm				
	FREQ.	2-10-	£=30mm	1-100-	1=300mm		L-30	1-100-	1-300=		1-100-	£=300mm		
	10Hz 20Hz	3.74m	17.2m 17.2m	57.4m 57.4m	172= 172=		5.74m 5.74m	19.1m	57.4m		5.74m 5.74m	17.2m		
	308z	5.74m	17.2=	57.4m	172=	l	5.74=	19.1=	57.4		5.74	17.29		
	SOHE	5.74	17.2=	57.4m	172m		5.74m	•	57.4m	•	5.74m	17.2m		
Ļ	70Hz	5.74=	17.2=	37.4	172		3./48	13.15	37		3.74	17.2=		
1	100Hz	5.74m	17.2	57.4m	172=		5.74=	1	57.4ea	ĺ	5.74	17.2m		
1	2008±	5.74=	17.2m	57.4=	172m		5.74=	19.1m	57.4=	1	5.74m	17.2=		
ı	300H± 500H±	5.74m	17.2m	57.4m	172= 172=	'	5.74m	19.1m	57.4m		5.74m 5.75m	17.2m		
	700H±	5.74	17.2a	57.4=	172=		5.74	19.12	57.4=		5.75a	17.2m		
H					4.20							 		
	lkHz	5.74=	17.2=	57.4=	172m		5.74		57.5± 57.6±		5.76m	17.30		
	2kHz 3kHz	5.74m	17.2m	57.4m 57.5m	172m 172m		5.75m 5.76m	19.1m 19.2m	57.8mm		5.81m 5.89m	17.5m 18.0m		
	SkHz	5.75m	17.2	57.5m	172=		5.78m	19.3m	58.4=		6.15a	19.2m		
	7kHz	5.75m	17.2m	57.6	173m		5.82=	19.5mm	59.4m		6.52=	21.0m		
	lOkfiz	5.76m	17.3m	57.9=	174m		5.89 a	20.0=	61.4m		7.23m	24.4m		
	20kHz	5.81m	17.5m	59.2m	180-		6.32=	22.4≡	72.1m		10.5=	38. ⇐		
1	30kHz	5.89m	17.9=	61.4	189=		6.97m	26.0=	87.1m	-	14.4	54.7m		
,	Okiz	6.14m	19.2	67.9m	215m	·	8.74m	35.lm	123a		22.7m 31.3m	88.3m		
L	70kHz	6.51=	21.0a	76.6=	250=		10.5m	45.5m	163a	•	31.36	122a		
	LOOK#2	7.21=	24.3=	92.5=	311m		14.3m	62.0m	225m		44.4	174=		
	COOKHE	10.4=	38.5=	155=	545m	·	25.9m	119=	440a	ı	88.2=	346m		
	OOkHz	14.3m	54.4m	224= 367=	795m 1.30Ω		39.9m 66.1m	177m 295m	657m 1.090		132m 220m	519m 866m		
	OOLE	31. l=	121=	510m	1.820		92. 4m	413=	1.522		308m	1.216		
١,	MHz	44.0m	173m	727=	2.590	Ì	בונו	590m	2.180	-	440m	1.730		
	20Hz	87.5	344	1.450	5.180		263m	1.170	4.360		880m	3.462		
1	RE.	131=	516m	2.179	7.760		395≖	1.760	6.548		1.322	5.190		
1	20Hz	21.8=	861m	3.620	12.90		659ma	2.940	10.90		2.200	8.660		
Ľ	MET:	305m	1.202	5.070	18.10	,	922=	4-120	15:20		3.080	12.12		
	LOME	437m	1.72Ω	7.25Ω	25.80		1.310	5.890	21.80		4.400	17.3Ω		
	20HHz	874	3.440	14.5Ω 21.7Ω	51.7Ω 77.6Ω	J	2.63Ω 3.95Ω	11.7Ω 17.6Ω	43.6Ω 65.4Ω	-	8.80G 13.2D	34.6G 51.9Ω		
1	300:Elz	1.310	5.160 8.610	36.20	1290	']	6.59Ω	29.40	109Ω		22.00	86.60		
	7 OHLE	3.050	12.00	50.70	1810	4	9.220	41.20	1520		30.80	1210		
	LOOME 2	4.37Ω	17.20	72.50	2580		13.10	58.9Ω	218Ω		44.00	173Ω		
1	200912		34.40	1450	517Ω	1	26.30	1170	436Ω	1	88.00	3460		
	300MEz	13.10	51.60	2170	77 6Ω		39.50	1760	مغضتنا		1320	51912		
	SOOMH:	21.80	86.10	3620	1.29₺Ω		65.90	2940	1.0910		2200	8660		
L	700HEz	30.50	1200	5070	1.8110		92.20	4120	1.52kΩ		3080	1.2110		
	CEE	43.70	1720	7250	2.58kΩ		1310	589Ω	2.18½0		4400	1.7310		
		87.40		1.45₩Ω 2.17₩Ω	5.17½Ω 7.76kΩ			1.17½Ω 1.76½Ω	4.36kΩ		880Ω 1.32½Ω	3.46kΩ 5.19kΩ		
	CEF	2180		3.6250	12.9kΩ	1		2.94162	10.91		2. 2010	8.66kn		
	CEL:		1.2016	5.0720	18.1㎞	1	9220	4.1210	15.2½Ω		3.081-0	12.1kG		
	OCE		1.72kΩ		25.8140	4	1.31kΩ	5.89kQ	21.862		4.40₺Ω	17.3kΩ		

^{*} Wiring dimensions are width x thickness in mm

10/28/02 wgi u = microrms

^{1 =} wiring length in mm
m = millionms

METAL GROUND PLANE IMPEDANCE IN OHMS / SQUARE

COPPER, COND-I, PERM-I							STEEL, COND17, PERM-300						
Freq.	r=.03	r=.1	t3	t=1	₹#3	t=10	t=.03	t=.1	t=.3	t=1	t+3	t=10	
108x	574w	172u	57.4u	17.2u	5.74u	1.75µ	3.36=	1.01=	338u	1012	38.5u	40.36	
	574u	172u	57.4u	17.2v	5.75u	1.832	3.38m	1.01=	338u	1024	49.5u	56. Su	
20Hz	574u	1722	57.4u	17.22	5.75u	1.95u	3.38=	1.01=	338u	103u	62.Ju	69.31	
30Hz	574u	1728	57.4u	17.2u	5.76u	2.30v	3.38=	1.01=	338u	106u	86.2u	89.6	
50R± 70H±	574u	172v	57.40	17.2u	5.78u	2.7lu	3.38m	1.01=	338u	110u	105u	106 u	
		. 20	57.4u	17.2u	5.82u	3.35u	3.38m	1.01=	338u	1180	127u	126 :	
100Ez	574u	172u	57.4u	17.2u	6.04u	5.16u	3.38c	1.01m	340u	157u	179น	179u	
2008z	574u	172u		17.2u	6.38 _u	6.43u	3.38=	1.01=	342u	199u	219u	219u	
300H2	574u	172u	57.4u		7.36u	8.27u	3.38=	1.01=	350:	275v	283u	2830	
500Hz	574u	172v	57.4u 57.4u	17.3u 17.3u	8.55u	9.77y	3.38=	1.01=	362u	335v	335u	3350	
700Hz	574u	172u	37.49	27.30							400		
1kHz	574u	172u	57.4u	17.5u	10.4u	11.6u	3.35m	1.01m	385u	403u	400u 566u	4000	
ZENZ	574u	172u	57.5u	18.Ju	16.1u	16.3u	3.38=	1.02=	495u	566u		366 u	
JkHz	574u	172u	57.5u	19.5v	20.Ju	20.24	3.38e	1.03=	623u	693u	6940	6946	
5kBz	574v	172u	57.6u	23.0u	26.2u	26.lu	3.38	1.06m	862u	896u	896u	396 u	
7kBz	574u	172µ	57.8u	27.ly	30.%	30.94	3.3┺	1.10m	1.05	1.06m	1.06m	1.06	
	574u	172u	58.2µ	33.5v	36.9u	36.9u	3.38=	1.15	1.27m	1.26m	1.26m	1.26	
10kHz	5740	172u	60.4y	51.6u	52.2u	52.2u	3.40m	1.57m	1.79=	1.79m	1.79m	1.79	
20k##	574u	172u	63.8y	64.Ju	63.9v	63.9u	3,42=	1.99m	2.19=	2.19m	2.19m	2.19:	
30FH=		173u	73.62	82.7µ	82.60	82.6u	3.50m	2.75	2.53m	2.83ma	2.83m	2.53	
50kHz	574u 574u	173u	85.5u	97.7u	97.7u	97.7u	3.632	3.35	3.35m	3.35=	3.35m	3.35	
70kBz	37-0							4.03e	4.00=	4.00m	4.00a	4.00	
100kHz	574u	175u	104u	116u	116u	1160	3.85m		5.66=	5.66m	5.66m	5.66	
200k#z	575u	183u	1614	165u	165u	165u	4.95m	5.66m	6.94æ	6.940	6.94	6.94	
300k##	575u	195u	203u	202u	202u	202 _b	6.23m	6.93=		8.96a	8.96E	8.960	
500k#±	576u	230-	2624	261u	261u	261u	8.62=	8.96m	8.96%	10.6	10.68	10.6	
700kBz	578u	271u	309 ₁ :	309u	309u	309u	10.5=	10.62	10.60	10.00	1 10.00		
IME	582:	335v	369:	369u	36 9u	36 9 ⊌	12.7=	12.6m	12.6m	12.6	12.6m	12.6	
ZMHz	604u	516u	522:	5224	5220	522u	17.9≡	17.9=	17.9≘	17.9m	17.93	17.9	
2011 2011	638u	6430	6390	639∿	639∪	639u	21.9m	21.9m	21.9m	21.9=	21.94	21.9	
	7366	827u	826:	826u	826u	826u	28.3m	28.3	28.3	28.3	28.3=	28.3	
SME z 7ME z	8554	977u	977u	977u	977u	977u	33.5€	33.5	33.5≡	33.5	33.52	33.5	
	1 2/-	1.16m	1.16=	1.160	1.160	1.16m	40.0m	40.0m	40.0E	40.0≘	40.0=	40.0 -	
1000tz	1.04	1.65m	1.65=	1.65=	1.65	1.65m	56.6m	56.6mm	56.6	56.6	56.6m	56.5	
200011	1.61=		2.02	2.02=	2.02	2.02=	69.4	69.40	69.4	69.4	69.4	69.4	
30M31:	2.03=	2.02	2.61m	2.61=	2.61=	2.61=	89.5mm	89.6m	89.6m	89.6m	89.6m	89.61	
50001z	2.62m 3.09m	2.6lm 3.09m	3.09	3.09=	3.09m	3.09≡	106m	10 6 m	10 6 m	106m	10 6 m	106=	
70MEz	 				1 (2	3.69m	126=	126m	12 6 0	126m	1260	126=	
1002912	3.69=	3.69=	3.69m	3.69=	3.69m 5.22m	5.22=	179m	179m	179	179e	179m	179m	
2001012	5.22=	5.22=	5.22=	5.22=		6.39m	219	219=	2190	219a	219m	219=	
300MLz	6.39	6.39m	6.39m	6.39=	6.39m	8.26m	283m	283m	283=	253m	253=	283=	
50074H.#	8.26m	8.26m	8.26m	8.26m	8.26m	9.77=	335=	335=	335=	335e	335m	335€	
700HBz	9.77m	9.77m	9.77=	9.77m	9.77=	7.//=					!		
1081	11.6	11.60	11.60	11.5=	11.6=	11.6m	400m	400m	400m	400a	400m 566m	400m 566m	
ICHI	16.5	16.5	16.5m	16.5=	16.5=	16.5m	566m	366m	566m	6940	694=	69412	
3CH 2	20.2	20.2	20.2=	20.2=	20.2	20.2	694	694	694	1	L	596m	
5CE2	26.1=	26.1=	26.lm	26.13	26.1=	26.1=	896m	8962	896=	8962	1.06.	1.06	
7GHz	30.9=	30.9	30.9=	30.900	30.90	30.9≡	1.062	1.065	1.06.	1.06.	1.262		
/ GRI	,	36.9■	36.90	36.9=	36.9≡	36.9m	1.265	1.260	1.265	1.265	1 i D	1.26	

t is in units of

NOTE: Do not use table at frequencies in MHz above $15/l_m$ since the separation distance in meters, l_m , of two grounded equipments will exceed 0.05 λ where error becomes significant.

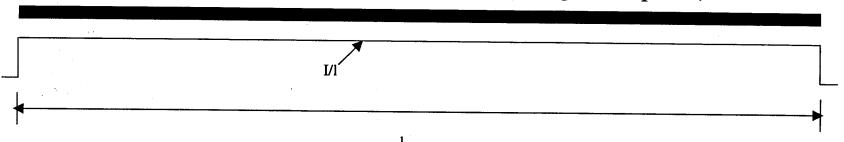
μ = microhms

m = milliohms

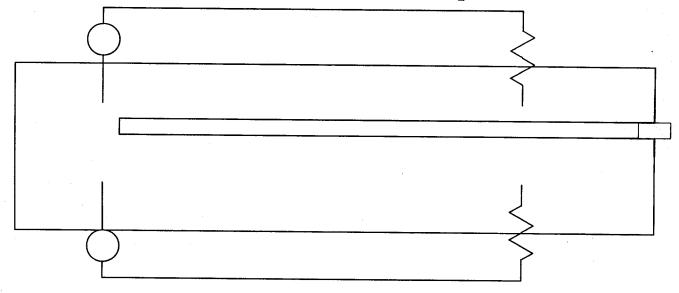
 $[\]Omega = ohms$

Keeping Out "Bad" Currents

• At low frequencies Current distributes approximately uniformly along a group of parallel wires or a wide trace (e.g., a ground plane)

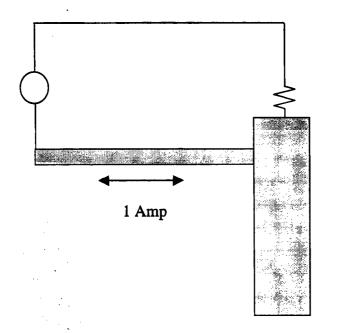


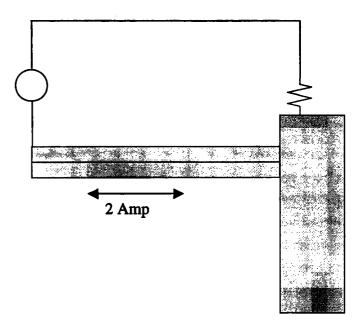
• Only way to prevent current flow is to interrupt conductor



Choices of Ground Approaches

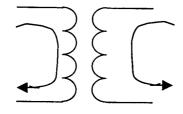
• Which of these is a better design choice?



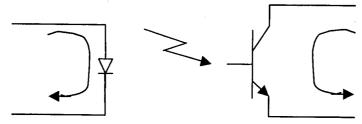


Keeping Out "Bad" Currents

- How else can I keep undesired low frequency currents out of a path?
 - Transformer coupling:
 - Requires either AC signal or conversion to AC & back



- Opto-isolation
 - Poor current transfer ratio, non-linear, high life/radiation drift



• Note: High frequencies can couple around the isolation if not careful

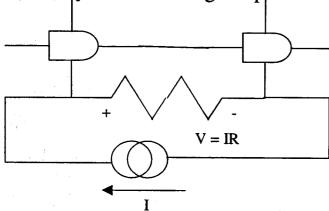
NSIDERATIONS

low frequency AC) are large and

wer System tend to be concentrated box power supplies ically tolerate sizable voltage drops s >= 2% of distribution voltage) nited bandwidth and lots of filtering dary) power/signal references ed (notable exceptions--high power ge ASIC or FPGA) rate significant voltage differences n very wide bandwidth ndary (load) power/signal grounding lifferent "needs"

GROUNDING CONSIDERATIONS

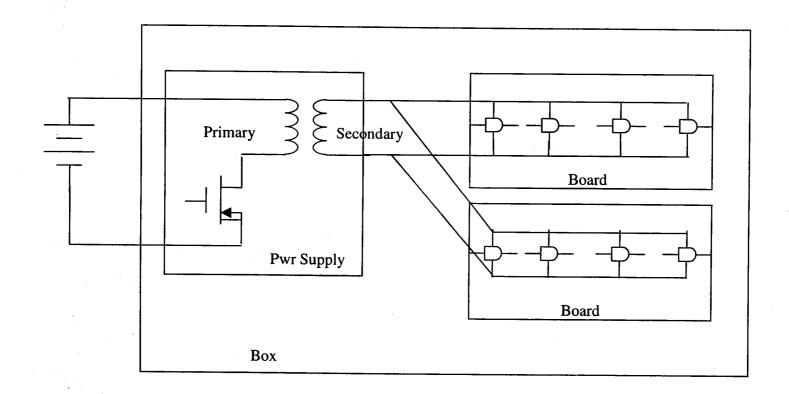
- Secondary (load) power and signal circuits cannot be isolated from each other
 - Ground pins are shared between power to IC and signal reference
- Signal circuits cannot tolerate stray voltages between source and load
 - Stray currents in high impedance ground paths cause voltage errors



- This kind of coupling of circuits is called "common impedance coupling"
- Message--
 - Keep impedances in load power/signal references low (at AC and DC)
 - Keep unnecessary large currents out of signal ground references
 10/28/02 wgi

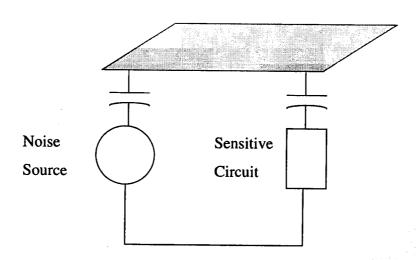
So How to handle Input Power vs. Secondary Power/Signals?

• Use transformer isolated DC/DC converters as power supplies



Handling Secondary Power/Signal Returns

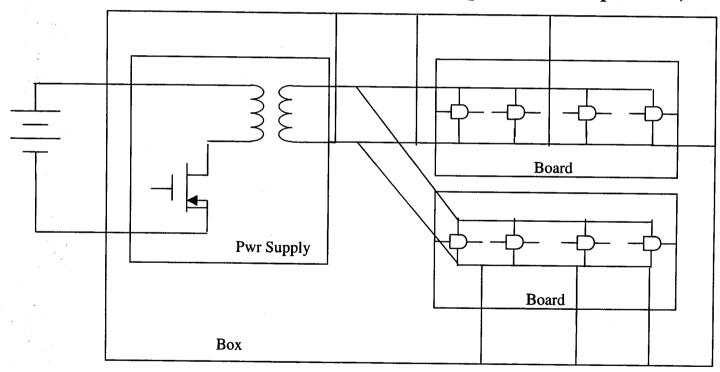
- But secondary (load side) power & signal returns often have to handle high frequency currents (so low impedance is important).
- And box chassis, if not at the same potential as the signal reference is a noise coupling mechanism.



• So how do I deal with this situation?

Handling Secondary Power/Signal Returns

- Tie the secondary power returns to box chassis ("ground") in a manner effective at high frequencies
 - Tie at every conceivable point (use ground planes where possible)

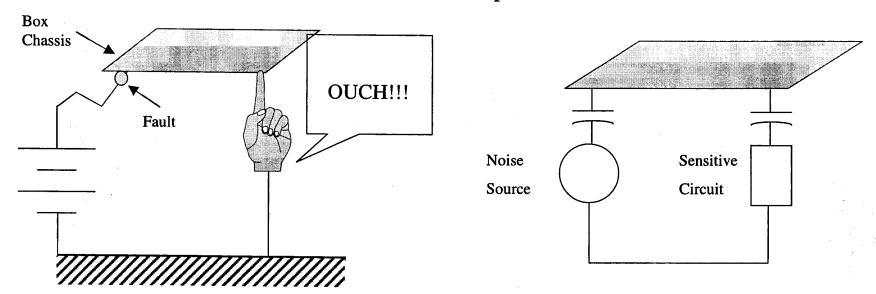


Primary/Secondary Relationships (Primary Grounding)

- But can I let the primary power system float with respect to chassis?
 - NO!!!!!
 - Safety and EMI Considerations indicate can't do that
 - What happens if I get 50, 100, 300, 1000 volts between primary/secondary?
 - » Something eventually blows up, arcs over, etc.
 - I could get hit by lightning or Electrostatic discharge
 - I may need to sense the primary power system with a piece of secondary side electronics
 - DC/DC Converters generate lots of high frequency EMI

GROUNDING CONSIDERATIONS

- Box/System Chassis Ground is <u>Always</u> part of your circuit.
 - If it floats it can be a hazard, or an EMI problem

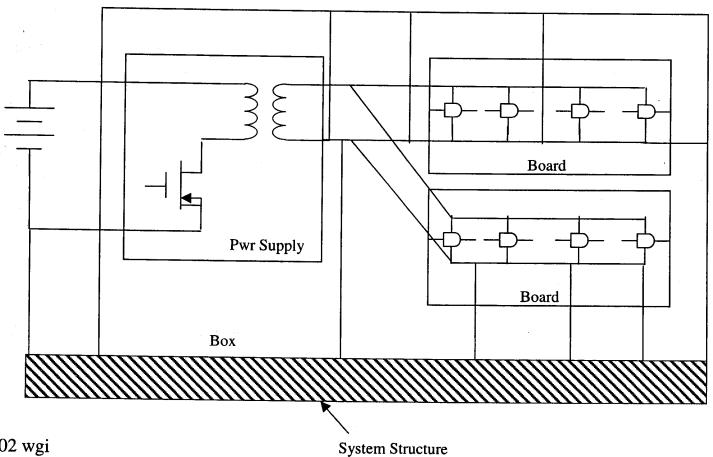


• Message--Make the chassis a known potential with respect to your circuit

(Preferably a ground reference voltage)

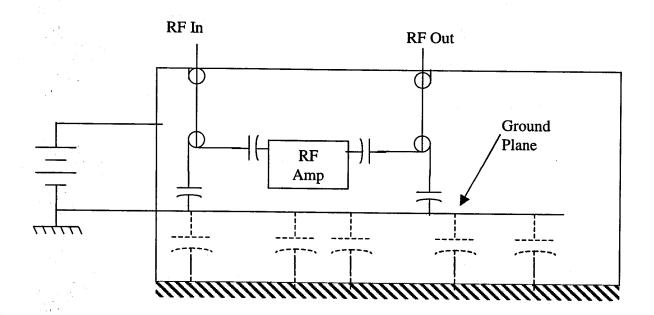
Chassis Ground tie the power system only at the source

"Single-point power grounding" concept



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Single Point Power Input Ground on RF Amplifier



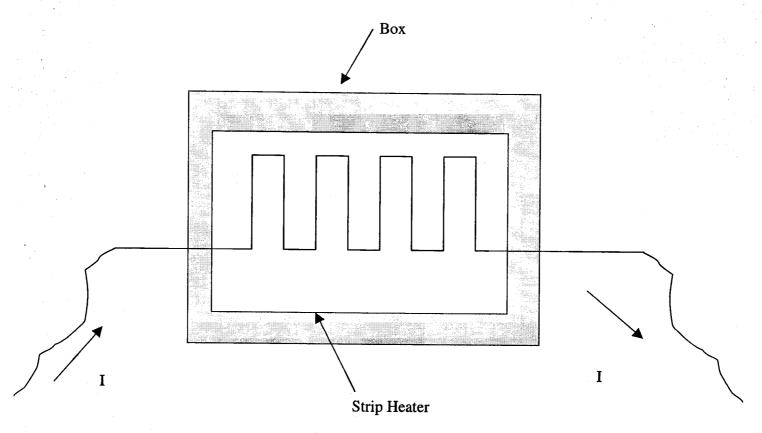
Another Reason for Single Point Grounding

• Current carrying paths that do not route with their returns generate stray magnetic fields:



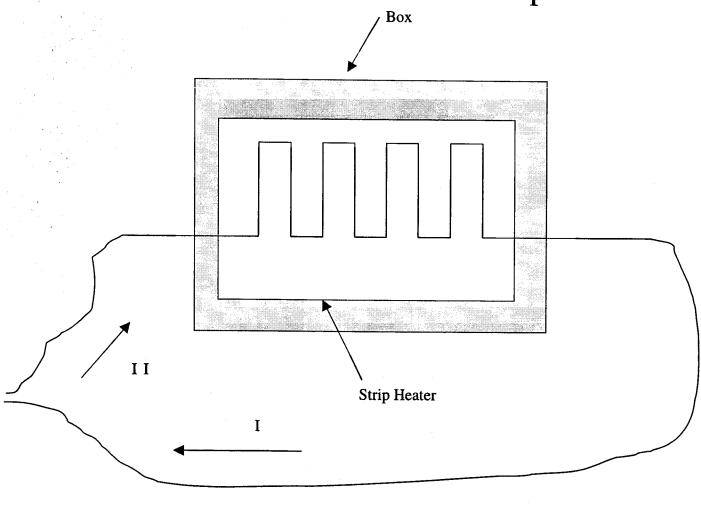
- Message--Route wires that carry significant current (like DC power) together (Desirably as twisted Pairs)
 - Don't share Power lines or Power returns between units

Heater Power Lines



• Un-cancelled Magnetic Fields make this a bad design approach

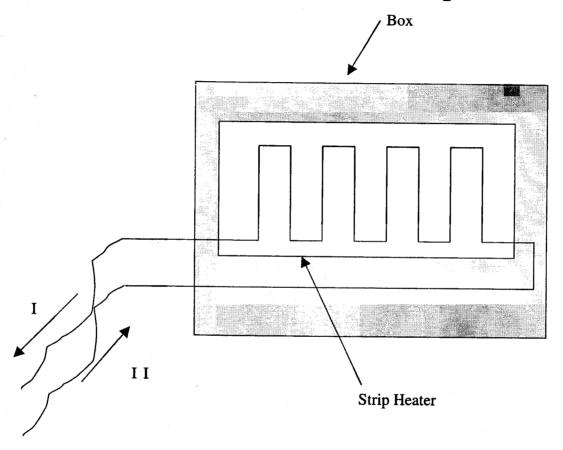
Heater Power Lines Concept #2



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• Better—but still large un-cancelled loop

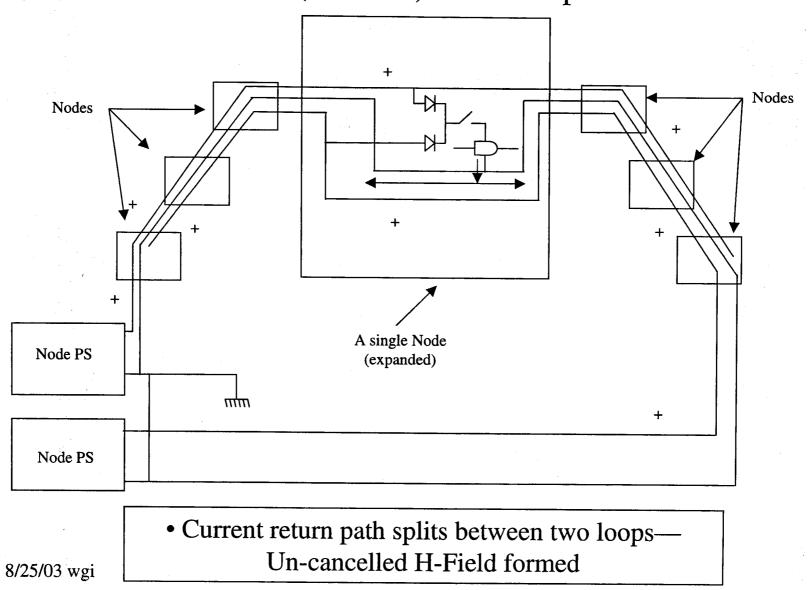
Heater Power Lines Concept #3



• Looping power line back immediately adjacent to heater and routing lines together provides efficient H-Field cancellation

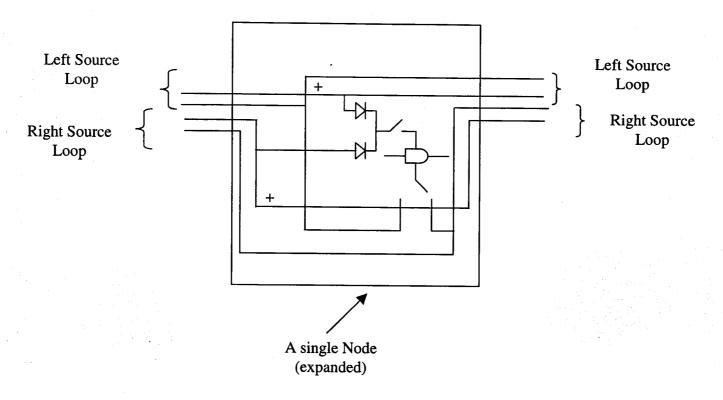
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IEEE-1394 (Firewire) Node Loop Power



25 0

IEEE-1394 Split Returns Solves Problem

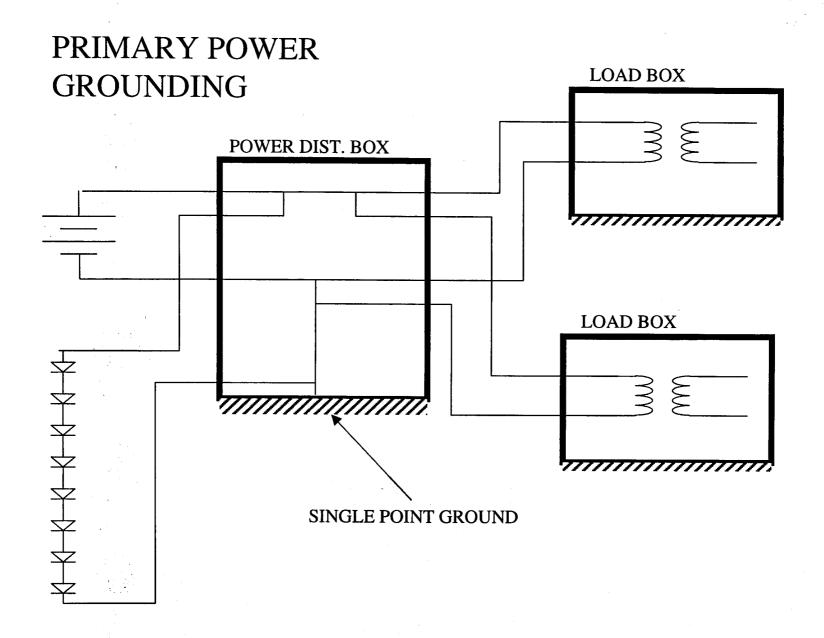


• Several possible methods exist to split returns

Solid State or electromechanical switches at source or at node

Isolated converter inputs

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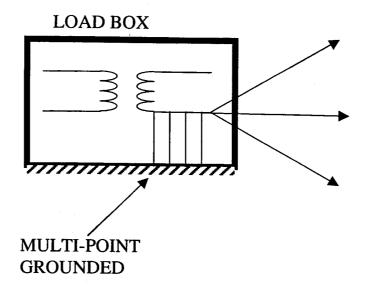
Multi-Point Grounded Power

- Can I successfully build a system that grounds power input lines to the system structure (chassis) at both sources and loads?
 - Yes, it can be done. And at least one major aerospace company does it.
 - The fact that the large power currents flow through the same paths as the signal circuit references <u>requires</u> an increased emphasis on return-to-box structure, box structure to system structure, and system structure resistance because of "common impedance" coupling between power currents and signal circuits
 - The grounding system in this case cannot take advantage of the larger voltage drops possible in the power return system (the signal system can't tolerate it)
 - Most aerospace companies (including LM) almost exclusively use single point grounded power systems

10/28/02-wgi

SECONDARY POWER GROUNDING

(POWER USED INTERNALLY ONLY)

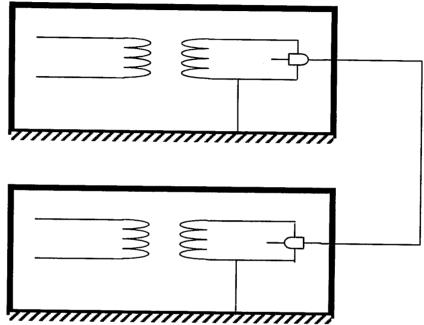


SIGNAL REFERENCES TO OTHER UNITS

(NO POWER TRANSFER)

(OTHER BOXES DESIGNED SAME WAY)

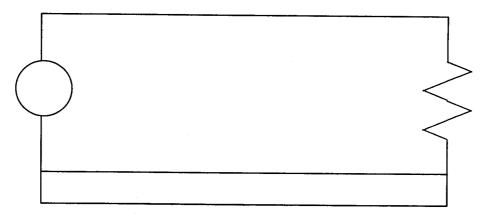
But Signal Circuits Have to Communicate between boxes



- Note: We normally don't want to depend upon the system structure to pass current. Always include a wire path.
- If the signal return system in both boxes is multipoint grounded to box chassis, and the boxes are grounded to system structure, doesn't that create the <u>dreaded</u> "GROUND LOOP"?

GROUNDING CONSIDERATIONS

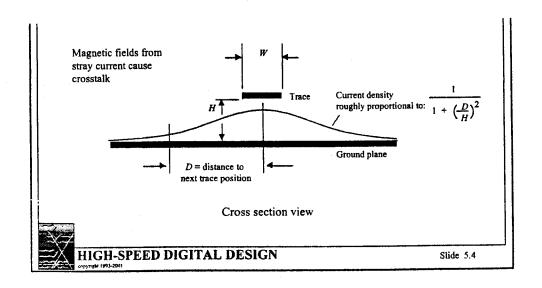
- Ground "Loops" are not always bad!!!
 - They can be good if they lower the impedance of the associated circuit
 (A Ground plane on a board or a conductive box chassis is the ultimate in a, usually good, ground loop)



 Ground loops are bad if they allow large currents to flow through undesired paths (like sensitive signal circuits) or generate large magnetic fields

Ground Loops are not always Bad

- If the big power currents are kept out of the ground loop the small signal currents don't create a lot of potential difference
- If the structure is a good ground plane (highly conductive, large cross-sectional area) there's not a lot of impedance there.
- At high frequencies the currents don't flow out everywhere
 - they concentrate in the ground underneath the associated signal line

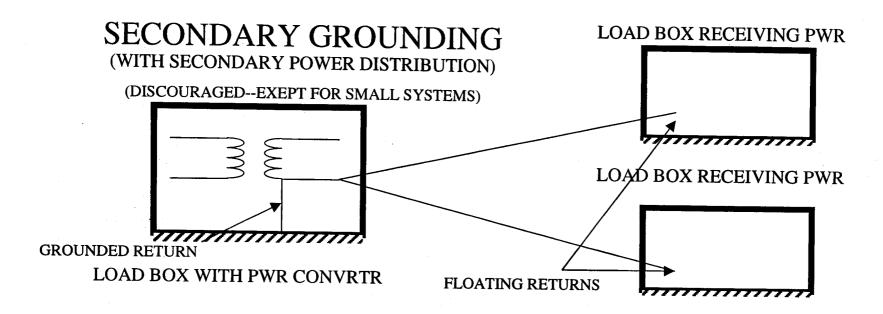


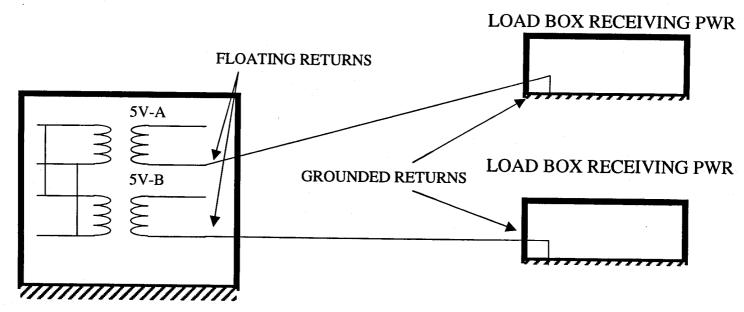
Handling "Bad" Chassis Paths

- OK, I've got a nonconductive structure, like composite or fiberglass, now what?
 - Several options exist:
 - a. If composite, grab conductive fibers in it to use as a ground path
 - Requires non-standard processes, necessitates use of continuous fibers or ways to assure fibers make contact, etc.
 - Not an especially good conductor (high V drop at big currents)
 - b. If supported by a conductive honeycomb structure, make contact to honeycomb via hardware mounting inserts
 - Requires non-standard processes, necessitates assuring continuous contact of honeycomb material, conductive contact to inserts, and conductive inserts
 - c. Put a layer of conductive material on top of it (e.g., "Astrostrike")
 - Signal reference paths do not require Large volumes of conductive materials (a thin, wide plane is adequate at high frequencies)
 - Does require additional processing—Standard processes do exist
 - Requires bonding straps at structure joints to maintain electrical contact

Handling "Bad" Chassis Paths

- OK, I've got a nonconductive structure, like composite or fiberglass, now what? (continued)
 - Several options exist (continued):
 - d. Use bond straps (wide, large surface area flat straps)
 - Necessary for high frequency performance
 - Usually require width >= length/5 for small inductance
 - Still not useful at frequencies $\gg \lambda/20$, because look like transmission line
 - (Long ground wires do not provide low impedance at high frequencies)
 - Requires additional labor at installation & has potential for error
 - Unless large cross-sectional area—not capable of high currents
 - e. Use bonding jumpers (e.g., round wires)
 - Low frequency performance (or safety) only
 - Requires additional labor at installation & has potential for error
 - Unless large cross-sectional area—not capable of high currents





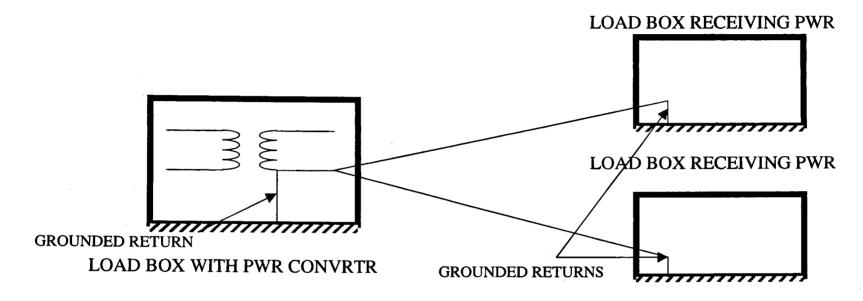
LOAD BOX WITH PWR CONVRTR 10/28/02 wgi



SECONDARY GROUNDING

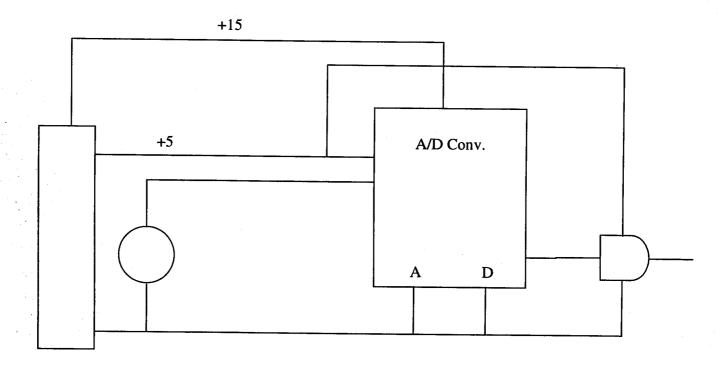
(WITH MULTI-GROUNDED POWER DISTRIBUTION)

(EVEN MORE DISCOURAGED--EXEPT FOR SMALL SYSTEMS)

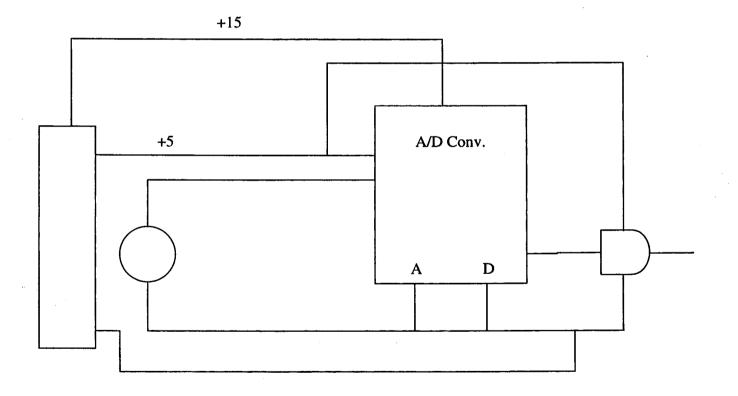


- If necessary to use—limit to use on a single small panel
- Requires adherence to cautions about multigrounded power lines (from slide 27)

• OK, I've got a 16 bit high speed A/D converter in my digital box, and the digital system noise from "common impedance" coupling will drive that sensitive analog system nuts, what can I do?

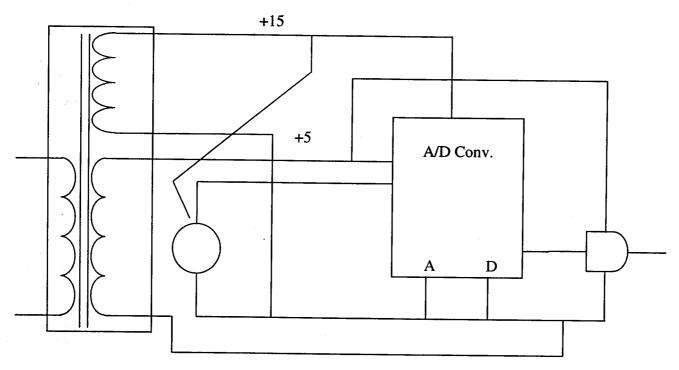


• Use the slotted reference from chart 15:

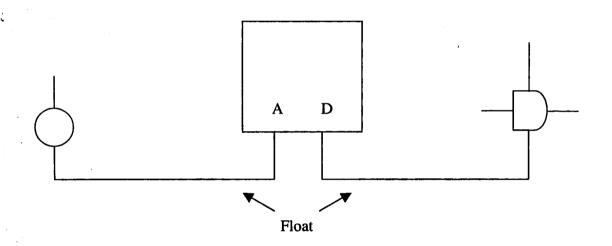


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- OK, but the previous chart still has the noise from the digital power lines imposed on the analog power I/F, what can I do about that?
 - Use transformer-isolated windings for the analog +15 volt power & the +5 volt digital power

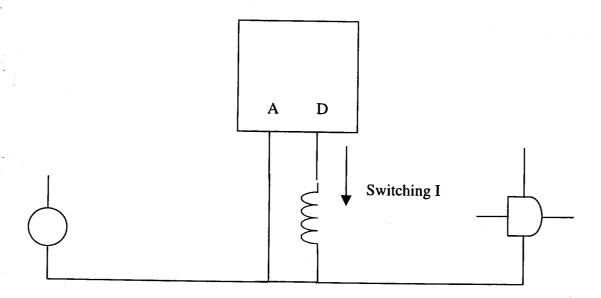


- Incidentally, ever wonder why the A/D has two ground pins (A & D)?
 - It's not so you can do this!!!! (Although you might be able to do it)



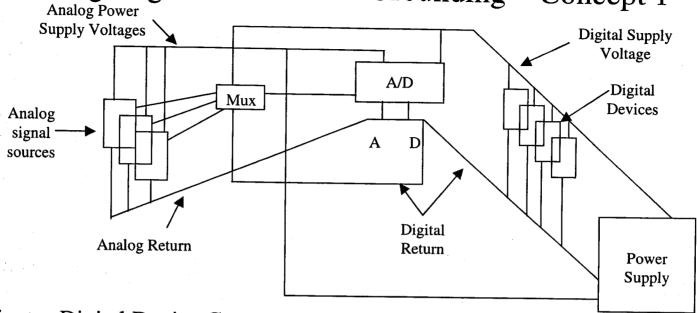
• Risk is that common mode voltages between A & D systems could kill the device or cause noise problems

• Here's why:



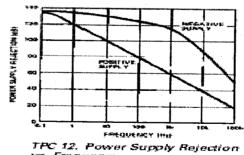
- Ground "bounce" in digital interfaces (chart 4) doesn't appear as noise source between the analog source and the A/D analog input

Analog-Digital Conversion Grounding—Concept 1



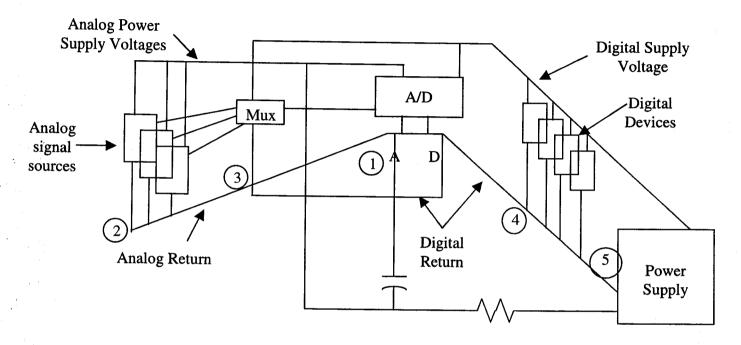
- Eliminates Digital Device Currents in paths between sources & A/D
 - Digital currents still affect analog device power supply voltage interfaces

• Often acceptable since analog device power supply rejection is good—be careful, may only be good at low frequencies



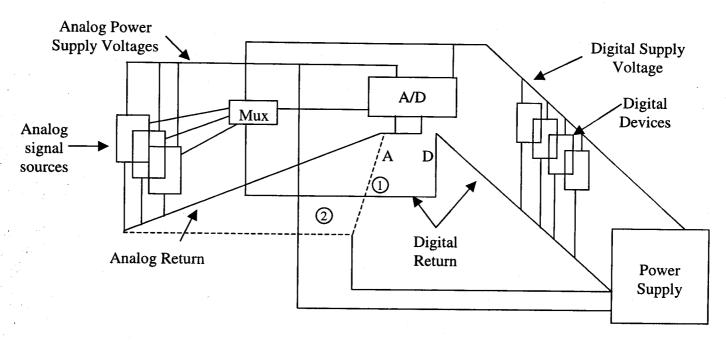
 Analog power currents create offsets in A/D inputs—Make analog return large area and paths short in length 8/08/03 wgi

Analog-Digital Conversion Grounding—Concept 2



- Adding filtering can help reduce digital noise on analog device lines
 - NOTE: Capacitor grounding is best done to point 1 above
 - Also note that local device bypass capacitors ground to point above.
- Digital noise still appears as common mode noise on analog signal and power interfaces

Analog-Digital Conversion Grounding—Concept 3



- Eliminates effect of digital devices on analog signal and power interfaces
- May eliminate or minimize analog device power supply currents on analog signals—(tie point 1)
- Possible Problem: A/D Digital currents may flow in analog paths (tie point 2)—is time correlated to A/D converter operations

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Sensitivity to Ground Offsets and Noise—A/D Conversion

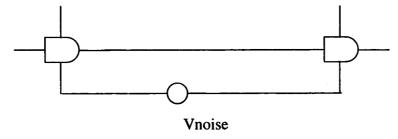
- Sensitivity of A/D conversion process increases significantly as number of bits increases:
 - For a 5 volt full scale signal:

Number of Bits	Value of LSB	
8	19.5 mV	
12	1.22 mV	
16	76.3 uV	
20	4.77 uV	
24	0.3 uV	

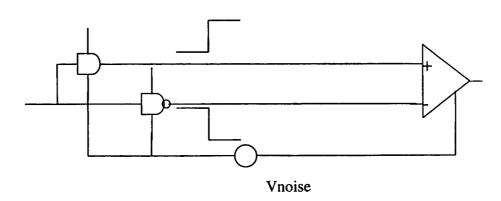
- Effect of ground offsets and noise can be reduced by:
 - Locating the A/D converter right next to the analog source
 - Reducing impedance of the ground path
 - Reducing the current flowing in the ground path
 - Employing differential transmission methods

Single-Ended vs. Differential Transmission

- Single ended (trace over ground) transmission is sensitive to ground voltage offsets and noise, and crosstalk from other lines.
 - Wide bandwidth of digital circuits means they are sensitive to frequencies far below (maybe above) the signal you are transmitting (including DC)
 - Analog circuits often sensitive to small magnitudes of noise

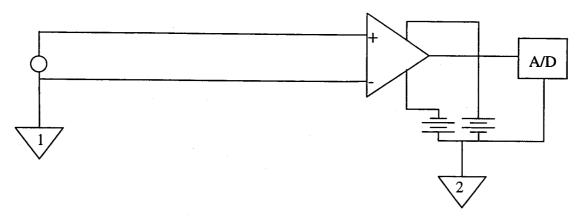


• Differential transmission reduces these concerns.

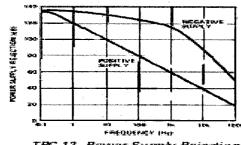


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Using Differential Interfaces to Reduce Offsets & Noise

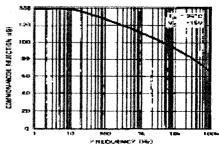


- Ability of this configuration to help depends on:
 - Common Mode Rejection Ratio of Differential Amp
 - Power Supply Rejection Ratio of Differential Amp
 - Magnitude and Spectral Content of Common mode or Power Supply voltage



TPC	12.	Power	Sugary	Rejection
we. F	reg	uency		

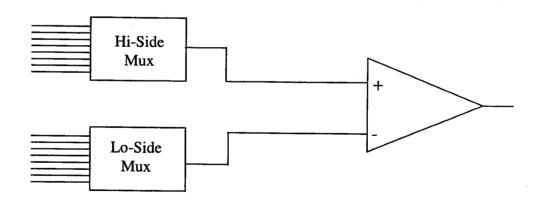
		Common Mode or
		Power Supply
		Rejection Ratio for
Number of Bits	Value of LSB	1 V source
8	19.5 mV	34 dB
12	1.22 mV	58 dB
16	76.3 uV	82 dB
20	4.77 uV	106 dB
24	0.3 uV	130 dB



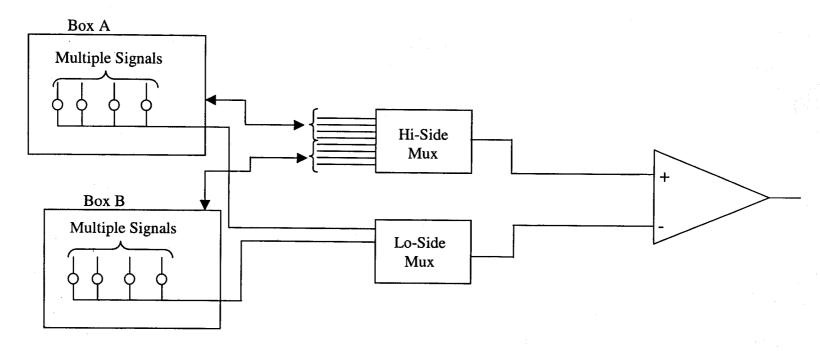
TPC 6. Common-Mode Rejection vs. Frequency

Issues with Differential Interfaces on Multiplexed Inputs

- Using one differential amplifier per input on multiplexed inputs requires many amplifiers, a sizeable real-estate and power penalty
- Similar, but somewhat less of a problem if one differential amplifier is used with both high side and low side multiplexers
 - Lots of multiplexers required (2 x number of inputs)
 - Multiplexers are smaller and consume less power than amplifiers



Reducing the Impact with "Pseudo-Differential" Interfaces

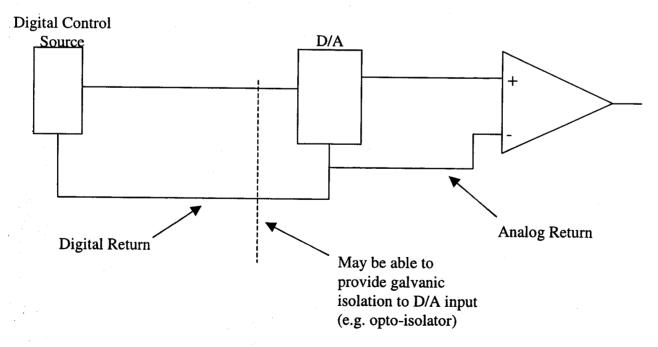


- Quantity of Lo-Side Multiplexers can be reduced many-fold by combining returns and using "Pseudo-Differential" Connections
 - Sometime a single "box" may contain two or more different ground domains (e.g., unregulated power return and analog signal return)—
 In such cases use separate lo-side mux for each different return

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D/A Grounding considerations

- Locate the D/A as close as possible to the analog system it serves.
 - Return the D/A return(s) to the analog ground
 - Reduces return voltage between the D/A and the analog system
 - Possible problem: Introduces D/A digital power and signal currents into the analog system return
 - Advantage: D/A digital I/F typically are small currents—not driving long lines or high fanout

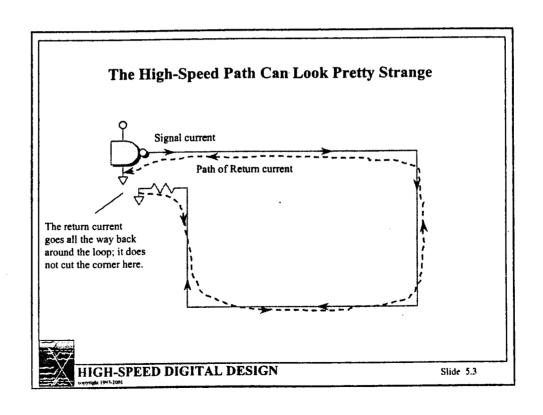


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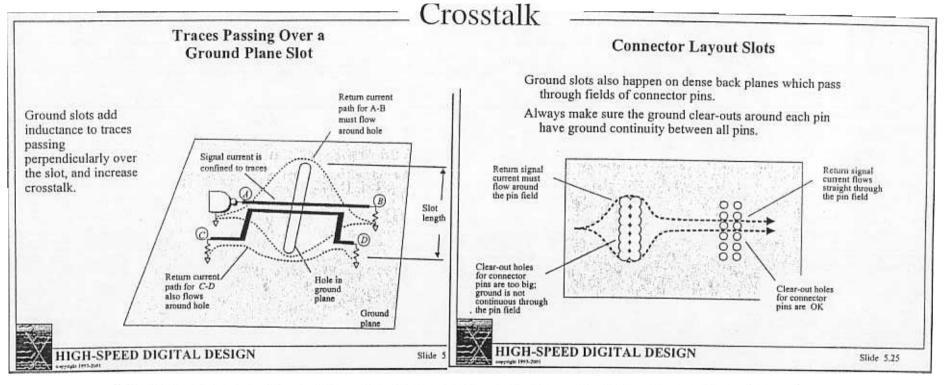
• If must separate D/A and analog system—use differential interface

Effects of Ground Slots at High Frequencies

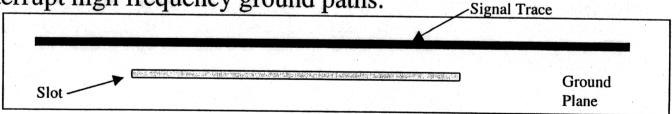
• Inductive effects causing concentration of current paths make the return current follow the outgoing path.



Slots in Groundplane can cause Impedance Discontinuities &

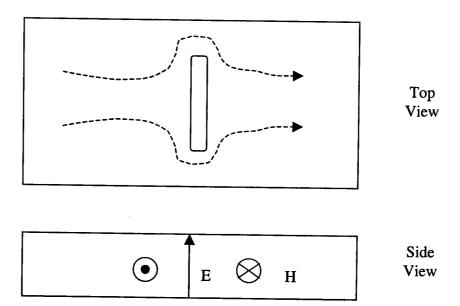


If ground plane is to be broken or slotted, make sure slots do not interrupt high frequency ground paths.



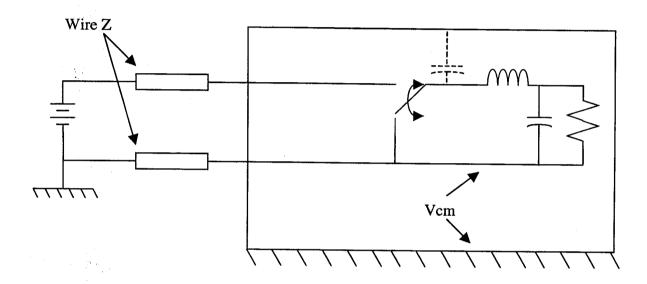
Another Effect of Slots

- A resonant slot in the plane (at high frequencies) can set up a high-Q resonant cavity
 - High electric and magnetic fields inside
 - Potent noise source for any circuit between planes



- Only way to stop is to have ties between the planes at small intervals
 - (<=3 inches is resonant at about 300 MHz)

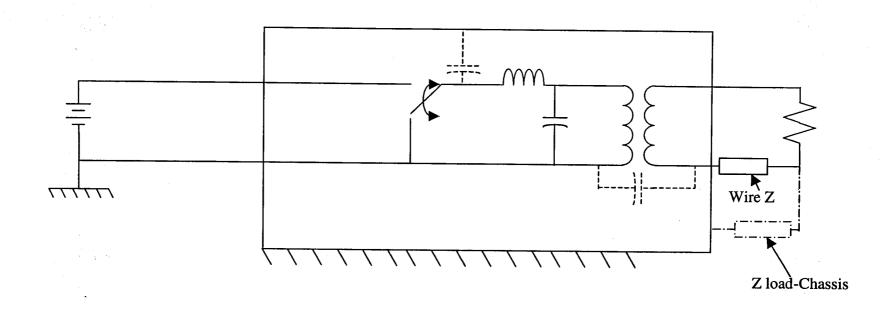
Generation of Common-Mode Voltages/Currents in Power Supplies



- Capacitance to Structure causes currents in input positive line when switch goes high and in input negative line (return) when switch goes low
 - Noise current in input lines causes EMI to the system and other loads
- Because these currents flow through the wiring impedance, this generates common mode voltages for the load

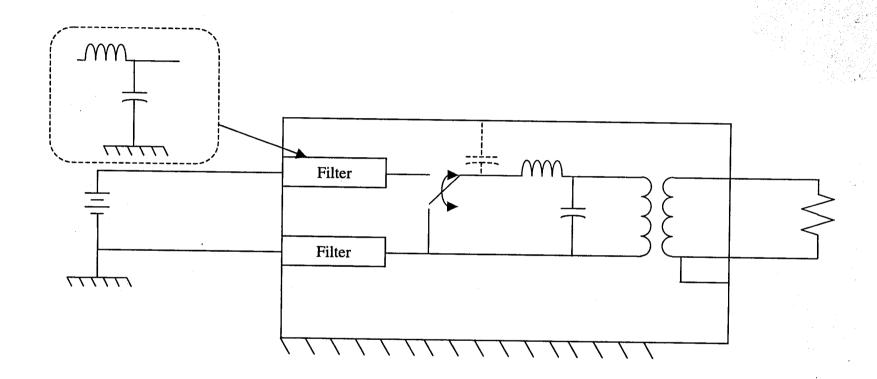
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Transformer Isolation may not eliminate the noise applied to the load



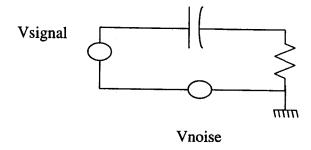
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Solution for Common Mode Noise



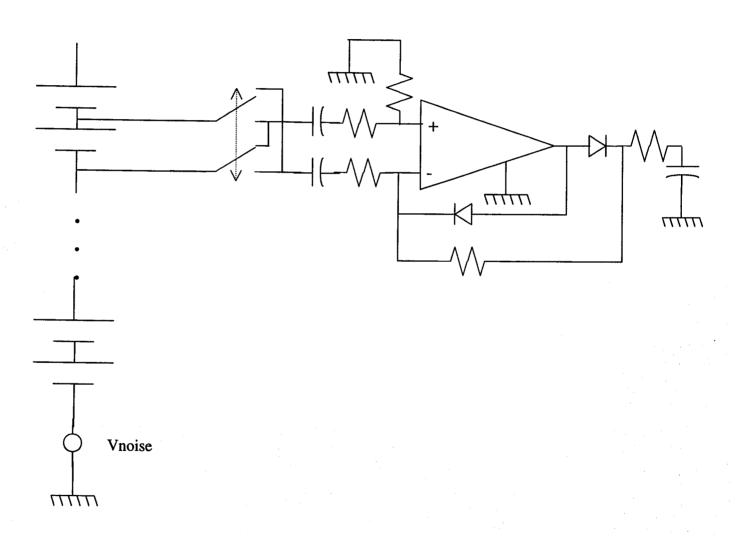
Charge-Coupled Devices Do Not Correct Grounding Problems

• Does capacitive coupling in a circuit eliminate ground voltage difference concerns?



- Only works for low frequency noise voltages
 - (Measured noise dependent upon how far below the cutoff frequency of the circuit the noise frequency is)

Charge-Coupled Devices Do Not Correct Grounding Problems



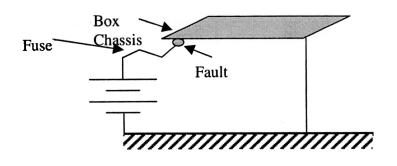
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GROUNDING SYSTEM FAULT PROVISIONS

- Faults to box structure require the structure path to be capable of large currents
 - Efficient power distribution requires low resistances in cabling to boxes (typically 2% of voltage dropped at maximum box load and minimum bus voltage--0.5 VDC for 28 volt systems, 1/2 of that in plus lead)

(Translation--Max. fault can be big, up to 500 Amp for 250W, 30V load!)

- Fault protectors typically sized for 2-3 times maximum current (they only clear the fault, they don't limit the current!!)
 - Typical protectors blow in something like 5 seconds at 2x protector rating
 - · We want the fault protector to open, not the structure path or wire



- Conductive, metallic structures usually have no problem safely passing fault currents
- Composite structures often have difficulty passing fault currents.--may need supplemental fault current wire grid.

WIRE RATINGS FOR FAULT GROUND PROVISIONS

Approximate Fusing Currents of Copper Wire:

	DIA. (IN.)	RESISTANCE (milli-ohms/ft)	FUSING CURRENT (AMPS)
20	0.032	10	58
16	0.05	4	117
12	0.08	1.6	235
8	0.128	0.62	472
6	0.162	0.4	668
0	0.324	0.1	1900

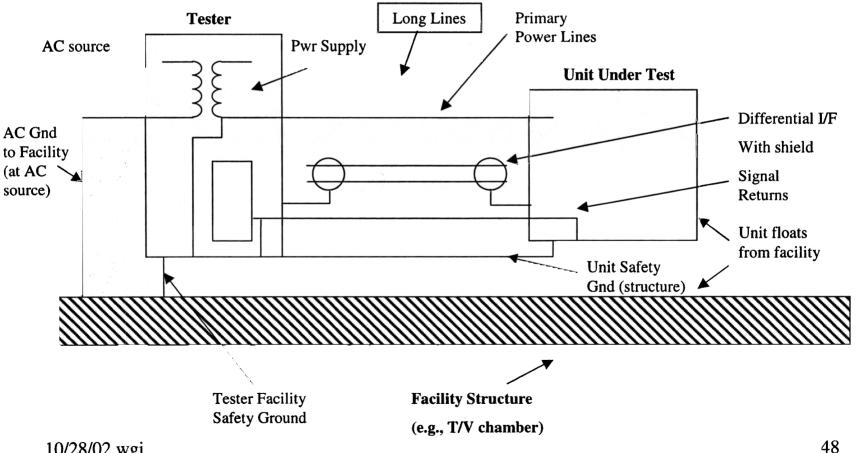
 Must also be concerned about voltage which can occur along structure path at high fault currents

A large fault current through the structure can create a voltage between source box and load box that exceeds the voltage capability of the devices on the load interfaces

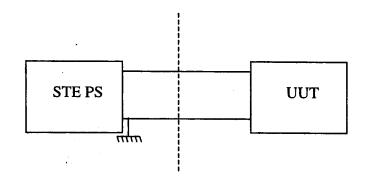
- Differential devices help (because of CMRR)
- Must be careful or voltage can exceed device absolute maximum damage ratings

How to Configure Testing Systems

Ground paths between test consoles & units under test major concerns

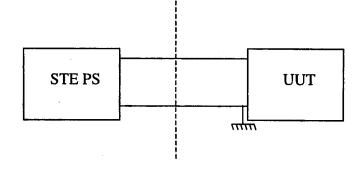


Testing Grounded EPS Boxes vs. Other Boxes



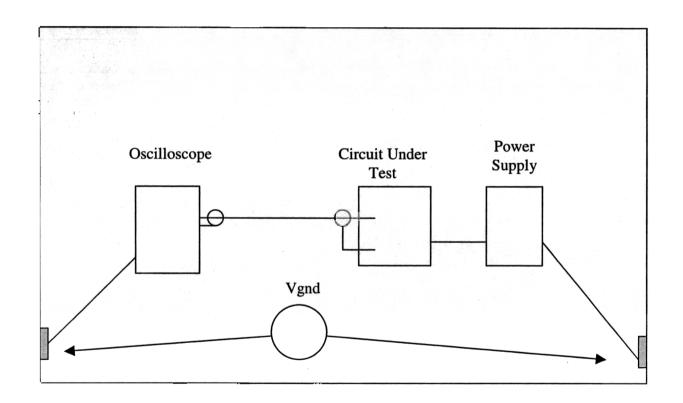
• Other Boxes-

Ground return at power source



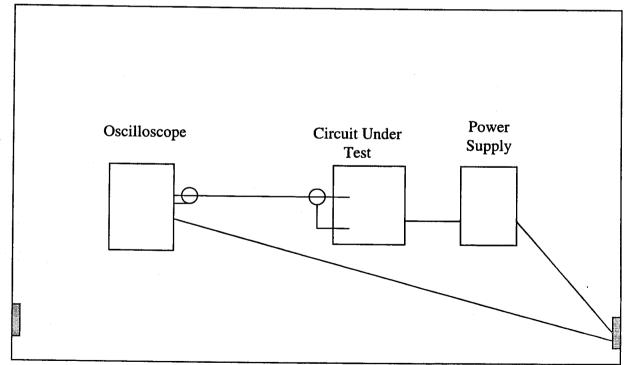
• Grounded EPS Boxes— Ground return at UUT, float at source

Testing Problems (AC Power System Ground Noise)



Avoiding Test Ground Noise Problems

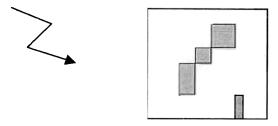
- Could use a differential input 'scope amplifier
- Could put the 'scope on an isolation transformer (safety?)
- Here's another way:



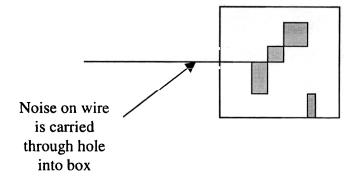
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Grounds as a Shield

• A circuit totally contained within a conductive "box" is shielded from the outside world (even if things inside float from the box)

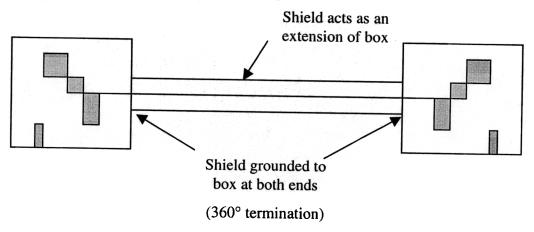


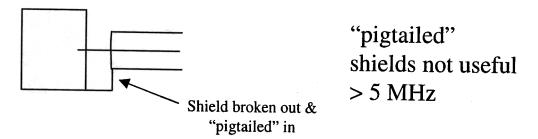
Wires that penetrate the box degrade shielding



Wire Shields

 Adding a double end grounded shield to wires (with good peripheral terminations) extends box shielding.

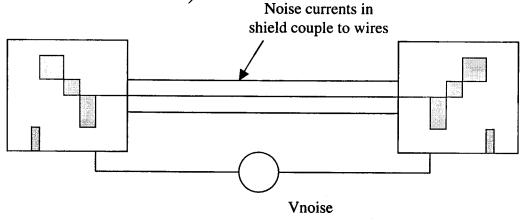




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Wire Shields

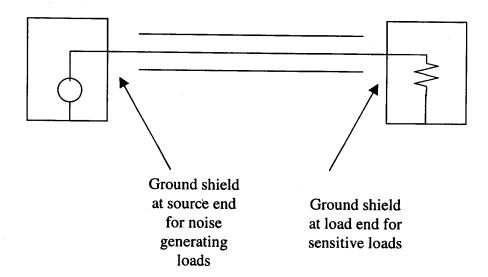
- Usually double-end grounded shields preferred (work at low and high frequencies)
- Sometimes boxes not at same low frequency potential, or low frequency contained common mode currents couple to shields (creating structure currents)



• In such cases, a single-ended shield ground may be preferable

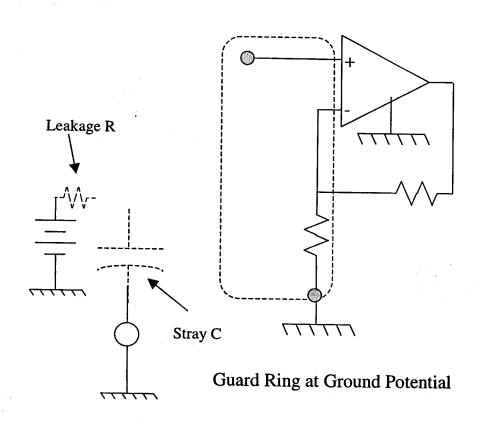
Wire Shields

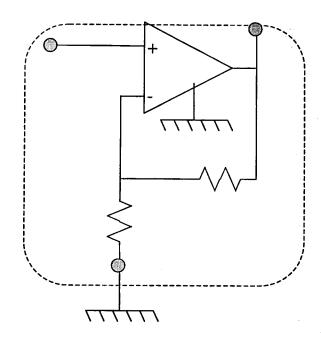
• If single end grounding of shields desirable:



- This type of shielding will not work at high frequencies
 - May need two shields, inner single end grounded, outer double grounded

Guard Rings



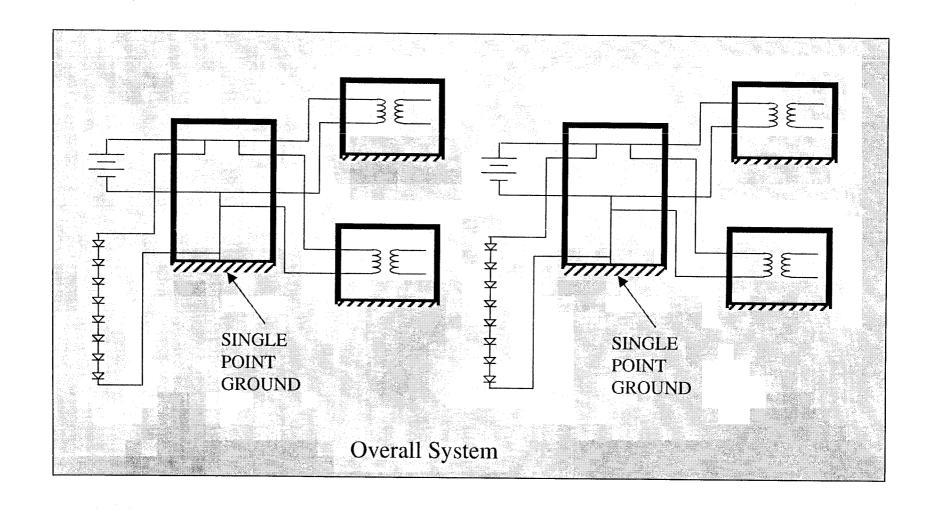


Guard Ring not at Ground Potential

Note: Guard Rings must appear on all board layers

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Is this a violation of Single Point Primary Power Grounding?



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Please Don't Do This

