

AMD OpenVX open-source on GitHub

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AGENDA

- Design Goals
- Performance Optimization
- ▲ Graph Optimizer
- OpenCL Code Generator
- Prototyping Tools (RunVX and GDF)
- Examples

AMD OpenVX Design Goals

▲ High performance on x86 CPU (SIMD) and GPU (OpenCL)

- Open Source
- Microsoft Windows, Linux, Apple Mac
- Provide tools for easy testing and prototyping
- Full Khronos Conformance
- OpenCV interop

PERFORMANCE OPTIMIZED FOR X86 CPU AND GPU AMD

- ▲ 200+ kernels hand-optimized for x86 with SIMD assembly instructions
- ▲ 200+ kernels hand-optimized with OpenCL for AMD GPUs
- OpenCL code generator for functions such as convolutions

AMD GRAPH OPTIMIZER

- The entire graph is analyzed for optimization opportunities prior to graph execution, such as
 - Merging of kernels to save bandwidth
 - Elimination of unused code
 - Prefetching of data into high speed local memory in the GPU
 - Optimum kernel selection

• Example with skin tone detection follows

EXAMPLE: SKIN TONE DETECTION

Kovac's original model:

(R,G,B) is classified as skin if:

R > 95 and G > 40 and B > 20 and

max{R,G,B} - min{R,G,B} > 15 and

|R-G| > 15 and R > G and R > B

Kovac's simplified model: (R,G,B) is classified as skin if:

R > 95 and

G > 40 and

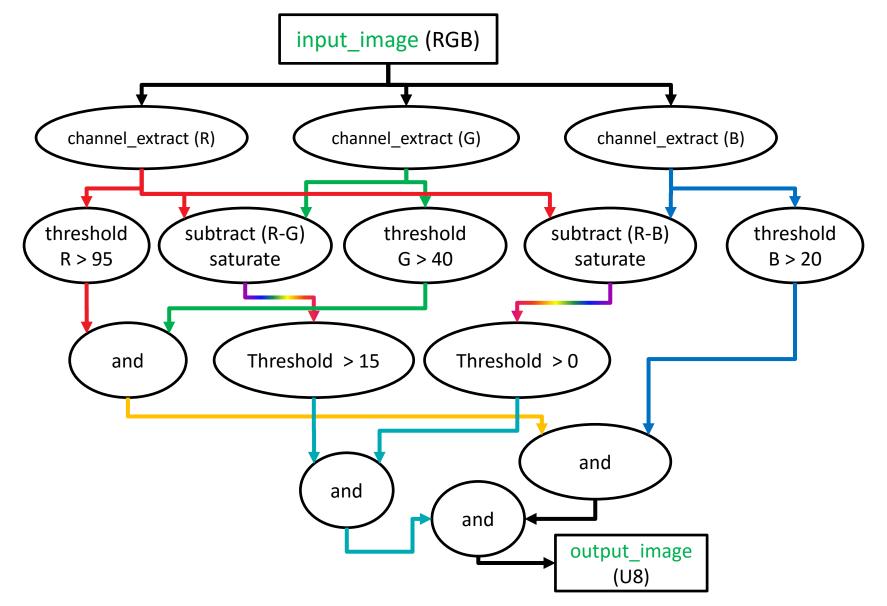
B > 20 and

R–G > 15 and

R–B > 0

SKIN TONE DETECTION GRAPH





SKIN TONE DETECTION GDF

node channel extract input image !CHANNEL R node channel extract input image !CHANNEL G node channel extract input image !CHANNEL B node subtract R G **!SATURATE RmG** node subtract R B **!SATURATE RmB** node threshold R thr95 R95 node threshold G thr40 G40 node threshold B thr20 B20 node threshold RmG thr15 RmG15 RmB0 node threshold RmB thr0 node and R95 G40 and1 node and and1 B20 and2 node and RmG15 RmB0 and3

output image

Color key

R

G

В

gdf keyword OpenVX node names Inputs Outputs Parameters

node and and2 and3

SKIN TONE DETECTION

OPTIMIZED GRAPH

[Optimized Graph] node ChannelExtract_U8U8U8_U24_Pos0 R G B input_image node Sub_U8_U8U8_Sat RmG R G node Sub_U8_U8U8_Sat RmB R B node Threshold_U1_U8_Binary R95 R thr95 node Threshold_U1_U8_Binary G40 G thr40 node Threshold_U1_U8_Binary B20 B thr20 node Threshold_U1_U8_Binary RmG15 RmG thr15 node Threshold_U1_U8_Binary RmB0 RmB thr0 node And_U1_U1U1 and1 R95 G40 node And_U1_U1U1 and2 and1 B20 node And_U1_U1U1 and3 RmG15 RmB0 node And_U1_U1U1 and3 RmG15 RmB0 node And_U8_U1U1 output image and2 and3

Optimized Color key

gdf keyword Optimized node names Inputs Outputs Parameters

When this is executed on the GPU, all these nodes are fused into one OpenCL kernel, eliminating 90%+ of the bandwidth

[Merged Graph]
node merge_on_gpu output_image input_image (note: not all details shown)

PLUG-IN YOUR OWN OpenCL CODE GENERATOR

Do you have an algorithm that maps well onto GPUs?

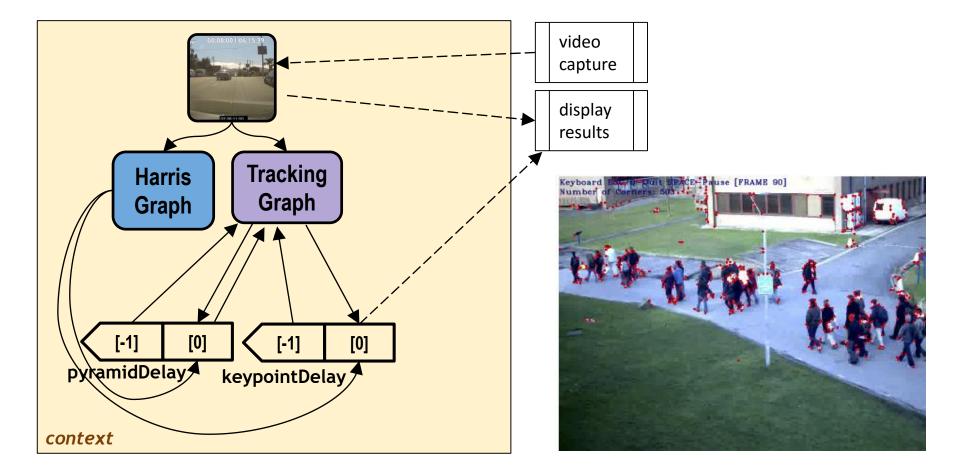
Create your own OpenVX kernel by just providing an OpenCL code generator

```
vx_status VX_CALLBACK user_kernel_opencl_codegen (
    vx_node node,
    char opencl_kernel_function_name[64],
    std::string& opencl_kernel_code,
    std::string& opencl_build_options,
    vx_uint32& opencl_build_options,
    vx_size opencl_global_work[],
    vx_size opencl_local_work[],
    ...
```

The remainder is managed by the AMD OpenVX framework

GRAPH DESCRIPTION FORMAT FOR QUICK PROTOTYPING **AMD**

You can quickly prototype complex application scenarios using few lines of text...



Data Objects and I/O

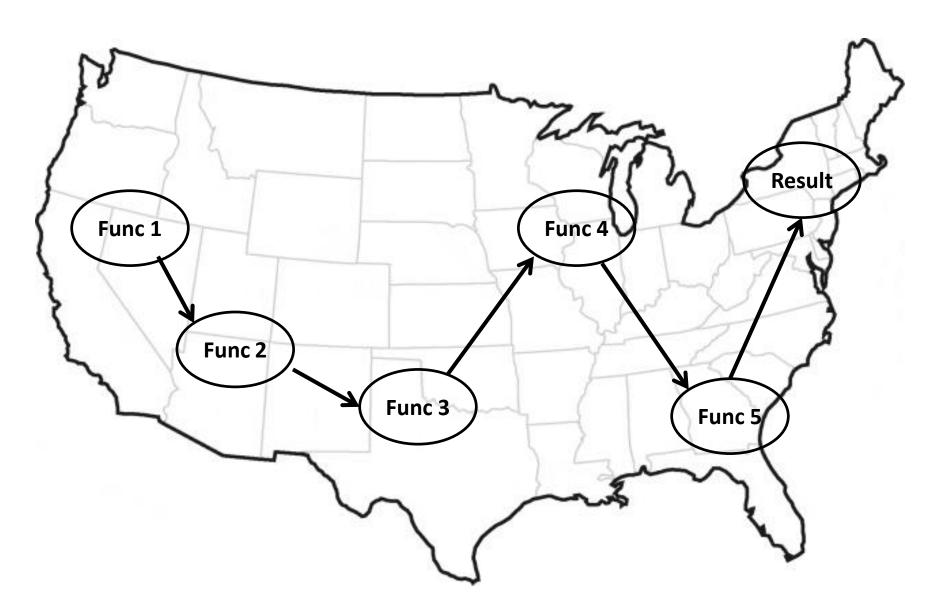
data *input* = image:768,576,RGB2 read *input* PETS09-S1-L1-View001.avi view *input* feature-tracker-window

For the full GDF: visit amdovx-core/runvx on GitHub

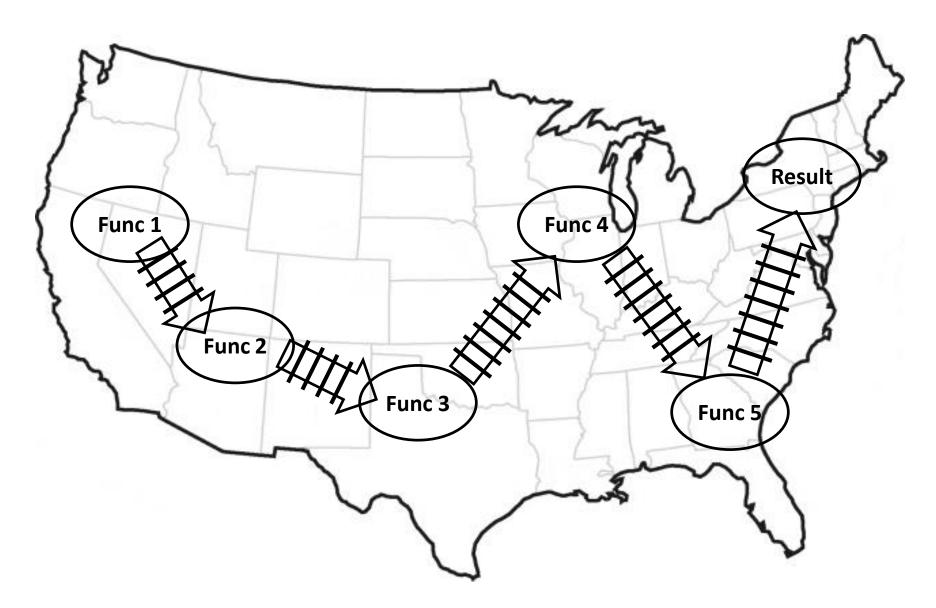
```
data iyuv = image-virtual:0,0,IYUV
```

•••

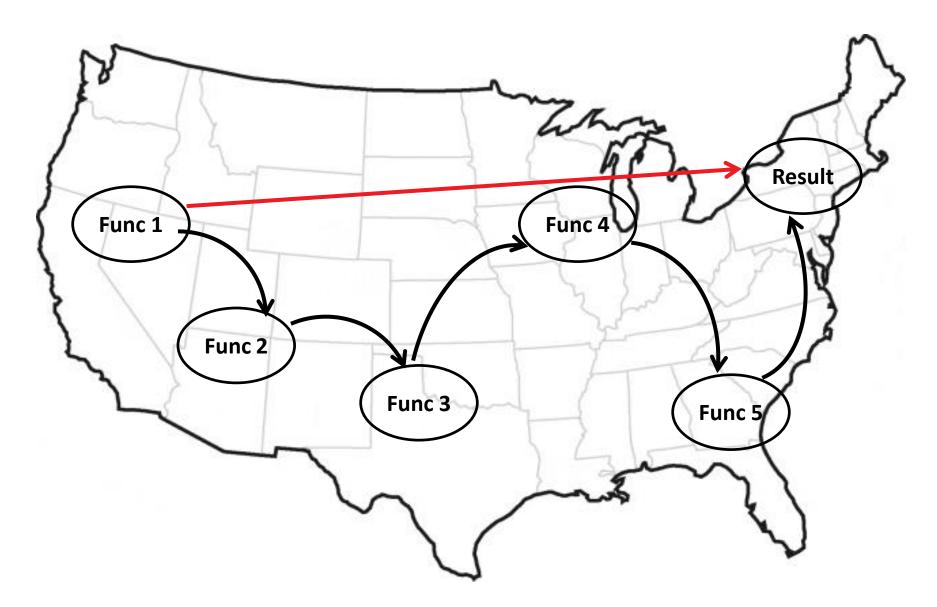
Summary: The OpenVX Advantage



The OpenVX Advantage



The OpenVX Advantage



Summary

Download and use the code – Link at the AMD GPUOpen web site <u>http://gpuopen.com/compute-product/amd-openvx/</u>



▲ Join github, then go to these links:

https://github.com/GPUOpen-ProfessionalCompute-Libraries/amdovx-core

https://github.com/GPUOpen-ProfessionalCompute-Libraries/amdovx-modules

Support: Report any problems on the github "issues" tab



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