

## The Large Signal Microwave Characterization and Design Challenge



#### **Centre for High Frequency Engi**

School of Engineering Cardiff University Cardiff, Wales, UK Website: www.engin.cf.ac.uk/chfe



Prof. Paul J Tasker tasker@cf.ac.uk



IEEE MTT-S Distinguished Microwave Lecturer 2008-2010

#### - RF I-V Waveform Measurement & Engineering



## **Centre for High Frequency Engineering**

- Who are we?
- Founded in 1997
- Significant funding from Government and Industry
- Staff & Students
  - 4 academics
  - 1 professorial fellow
  - 2 research associates
  - 20+ research Students
  - dedicated Technical Support
- Strong industrial links
  - Tektronix, Agilent, Freescale, CREE, RFMD, Nokia, Ericsson, EADS, Astrium, ...
  - Research is 50% funded by industry
- Also EPSRC, DTC, FP7, EUREKA





Prof. P Tasker Prof. A Belcher

Prof. A Porch







**Prof. S Cripps** 









## Centre for High Frequency Engineering

- What do we do?

*Mission statement:* to innovate and establish scientifically robust nonlinear characterisation, analysis and design methodologies at high-frequencies

Motivation behind lectures

**Core capability and development:** RF Waveform Measurement and Engineering

•Topic of the lectures

- **Measurement:** The ability to observe and quantify the time varying voltage  $V_n(t)$  and current  $I_n(t)$  present at all terminals of the Device Under Test (DUT): thus involves all frequencies including DC, IF and RF.
- **Engineering:** The ability to modify in a quantified manner the time varying voltage  $V_n(t)$  and current  $I_n(t)$  present at the terminals of the Device Under Test (DUT): thus involves all frequencies including DC, IF and RF.



#### **Motivation and Background**

Consider the Design and Optimization of the Highly Efficient Linear RF Power Amplifier



## Lack of single measurement techniques that can successfully tackle all relevant technology areas!

In coherent links between the area resulting in significant and relevant loss of information when moving from one area to another



#### **Motivation and Background**



Current and voltage waveforms have the potential to interlink the entire design and development chain!

However, it is a new approach and as such requires (1) new measurement systems, (2) new data analysis tools, and (3) design techniques



#### **RF I-V Waveform Measurement & Engineering**

- Lecture : 10.00am 11.00am
  - <u>CW Measurement System Realization</u>
- Lecture 2: 11.00am 12.00pm
  - Role in Supporting Non-Linear CAD Design
- Lecture 3: 1.00pm 2.15pm
  - Role in Transistor Characterization and Amplifier Design
- Lecture 4: 3.00pm 4.00pm
  - Emerging Multi-Tone Systems



#### **RF Waveform Measurements and Engineering**

- a powerful tool and concept



unifying link between device technology, circuit design & system performance

Fundamental Circuit theory	Nonlinear device modeling	Power amplifier design	Lineariser design	Amplifier & Lineariser production	Amplifier & Lineariser testing
		Waveform	Engineering		



#### Summary



Current and voltage waveforms have the potential to interlink the entire design and development chain!

However, it is a new approach and as such requires (1) new measurement systems, (2) new data analysis tools, and (3) design techniques

## **Thank You**



#### **RF IV Waveform Measurement and Engineering** - CW Measurement System Realization -



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**Contact information** 

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### **History of RF I-V Measurements**

- Development of the Non-Linear Network Analyzer
- Historically has had many names;
  - NLVNA: Non-Linear Vector Network Analyser
  - LSNA: Large Signal Network Analyser
  - ANA: Absolute Network Analyser
  - Vector(ial) Component Analyser



#### Era of the MTA (Microwave Transition Analyser)

- Kompa et al (1990)
- Tasker et al (1994)
- Verspecht et al

1990



#### Return of the DSO

- Tektronix DSA
- Williams et al

2010

#### Waveform Measurement

First realization of calibrated waveform measurement solutions

1980

- Time Domain Sipila et al (1988)
- Frequency Domain: Lott U (1989)



First wave of Commericalization (LNSA)

Agilent & Maury Microwave Corporation





## **History of RF I-V Measurements**

2000

- Era of commercialization and industrial acceptance

#### Second Wave of Commercialization

- Agilent: PNA-X
- NMDG/Rohde & Schwarz
- VTD (Verspecht-Teyssier-DeGroot)

**Waveform Measurements** 

Mesuro/Tektronix

1990

Era of the MTA (Microwave Transition Analyser) Kompa et al (1990) Tasker et al (1994)



2010

#### Agilent PNA-X: Frequency Domain



#### Mesuro/Tektronix: Time Domain

#### Waveform Measurement System

Simplified Architecture with active harmonic load pull

2 Channel Arbitrary Waveform Generator - Tektronix 7102 First wave of Commercialization (LNSA) Agilent & Maury Microwave Corporation 4 channel Sampling Oscillosco High-power High-power Broadband Broadband Microway Microwave Load-pull PA Driver PA High Power DUT High Power Bias-T Bias-T Waveform Engineering CREE Directiona **Tektronix**<sup>•</sup> mesurc Enabling Innovation

Key Parallel Development

1980

First Realization of calibrated waveform measurements

Time Domain Sipila et al (1988)

Frequency Domain: Lott U (1989)



## **Objective of RF I-V Measurement Systems**

- has to enable Waveform Engineering in Design

• Their measurement domain is to go beyond s-parameters

## RF I(I) & V(t) Waveform Measurement

• Their application domain is to go beyond linear design

## RF I(I) & V(†) Waveform Engineering



### **Outline:**

#### - CW Measurement System Realization

- RF I-V Measurement Solution
  - Architecture and Receivers
  - Error Models and Calibration
- RF I-V Engineering Solutions
  - Active Open Loop Architecture
  - ELP Concept









## **Non-Linear Vector Network Analyzer**

- Basic Architecture with RF Test-set

- Time domain variant requires a four channel receiver with each channel receiving either incident or scattered travelling voltage signals.
  - Frequency domain, PNA-X, variant requires a five channel receiver and a reference signal.
- Utilized directional couplers for detection/separation of travelling voltage signals.
- Source switch for redirection of stimulus signal.
  - Alternatively utilize two sources, PNA-X or Tektronix AWG.
- All instruments and components are computer controlled allowing for automated measurements



Measures RF a<sub>n</sub>(t) and b<sub>n</sub>(t) time varying Voltage Travelling Signal Waveforms



## **Time Domain Systems:**

- Sampling Receivers

#### • Key component is a broadband receiver

• Time domain sampling based





Agilent: Microwave Transition Analyzer (MTA) Principle is based on sampling over many cycles  $\begin{array}{c} & |A| \\ & 2 \cdot f_0 \\ & f_0 \end{array}$ 

Signals must be repetitive and on a specific frequency grid

Samples RF Voltage Waveforms v<sub>n</sub>(t)



## **Non-Linear Vector Network Analyzer:**

- Sampling based Architecture

- Measurement architecture is almost identical to conventional Network Analyzer
- RF hardware between DUT and the sampling receivers.
  - Introduces Systematic Errors
- Measured a<sub>n</sub>(t) and b<sub>n</sub>(t) time varying voltage travelling signal waveforms will be erroneous.
  - Error Correction Model
  - Vector Calibration



Measurements System needs to be vector calibrated



#### **Non-Linear Vector Network Analyzer:** - Error Model

- Error Correction Flow Graph
  - 8 Term Error Model
    - Similar to that utilized by VNA
  - All terms required
  - Independent of switch match
    - no transformation to a reference impedance
  - Independent of direction of energy flow



- Simple de-embedding algorithm
  - $b_1 = (b_0 \varepsilon_{00} a_0) / \varepsilon_{01}$
  - $a_1 = ((\epsilon_{01}\epsilon_{10}-\epsilon_{00}\epsilon_{11})a_0+\epsilon_{11}b_0)/\epsilon_{01}$
  - $b_2 = (b_3 \varepsilon_{33} a_3) / \varepsilon_{32}$
  - $a_2 = ((\epsilon_{32}\epsilon_{23}-\epsilon_{33}\epsilon_{22})a_3+\epsilon_{22}b_3)/\epsilon_{32}$

Require a calibration procedure: going beyond s-parameters



## **Ratio Calibration:**

- VNA 10 Term Error Model





..... measure s-parameters 10



### **Ratio Calibration:**

- VNA 10 Term Error Model



- Equivalent to VNA
  - Ratio measurements as a function of frequency



..... measure s-parameters 11



#### **Relating VNA and NLVNA Error Models** - step 1



Reformulate Error Model: Isolate correction and Impedance transformation



#### **Relating VNA and NLVNA Error Models** - step 1

#### Transformation of Error Model

- Utilize measurement of  $b_3/a_3$  ( $\Gamma_3$ ) during forward THRU calibration
- Utilize measurement of  $b_0/a_0$  ( $\Gamma_0$ ) during reverse THRU calibration
- Mathematical Conversion
  - Forward Model
    - $\epsilon'_{22} = \epsilon_{22} + \epsilon_{10} \epsilon_{32} / (1 \epsilon_{33} \cdot \Gamma_3)$
    - $\epsilon_{10} \epsilon'_{32} = \epsilon_{10} \epsilon_{32} / (1 \epsilon_{33} \cdot \Gamma_3)$
  - Reverse Model
    - $\varepsilon'_{11} = \varepsilon_{11} + \varepsilon_{01} \varepsilon_{10} / (1 \varepsilon_{00} \cdot \Gamma_0)$
    - $\epsilon_{01} \epsilon'_{23} = \epsilon_{01} \epsilon_{23} / (1 \epsilon_{00} \cdot \Gamma_0)$



Reformulate Error Model: Isolate correction and Impedance transformation



# **Relating VNA and NLVNA Error Models** - step 2



**Un-normalize and Combined Error Model** 



#### **Absolute Calibration:**

- Determine  $\varepsilon_{10}$  or  $\varepsilon_{23}$ 



- Additional calibration steps
  - $\epsilon_{10}$  un-normalization
    - MAG: Attach a power meter to Port 1
    - PHASE: Attach a phase meter to Port 1
    - PHASE: Inject a known signal into Port 1
  - $\epsilon_{23}$  un-normalization
    - MAG: Attach a power meter to Port 2
    - PHASE: Attach a phase meter to Port 2
    - PHASE: Inject a known signal into Port 2
- Phase Meter !!!!!!!
  - Requires the utilization one of the samplers
- Phase Signal !!!!!!!
  - Requires a spectrally rich signal with a known phase relationship





### **Absolute Calibration:**

- NLVNA 8 Term Error Model



#### Waveform Measurements



## **RF I-V Waveform Measurement System**

- Review of Fundamental Architecture





## **NLVNA Goes Beyond S-parameter:**

- Waveform Measurement



- HFET Transistor
  - Power Sweep @ 1.8 GHz



- Measures magnitude and phase of all the frequency components present in the terminal travelling waveforms
  - Power response
  - Spectral distortion
- Data Transformations
  - Frequency to Time Domain
    - Waveforms
  - a & b waves into v & i waves

$$\bigvee_{b_1}^{a_1} \xrightarrow{b_2}_{a_2} \bigvee_{a_2}^{b_2} \bigvee_{a_2} \bigvee_{a_$$



## **NLVNA Waveform Measurement:**

- Performance Extraction



- HFET Transistor
  - Power Sweep @ 1.8 GHz



- Data Transformation. Non-Linear Performance Evaluation
  - Gain and Gain Compression AM-AM
  - Output Power
  - Phase Response AM-PM
  - Spectral growth
- Direct Observation
  - Mode of Operation
  - Breakdown/Reliability



Are Waveform Measurements Sufficient?



### Linear versus Non-Linear Circuit Design

- the need for waveform engineering

- Linear System
  - characterized by s-parameters
    - allow impedance transformation
    - cascading of networks



S-parameters are also a design tool in Linear CAD

- Non-Linear System
  - characterized by waveforms
    - includes spectra growth (harmonics & inter-modulation)
    - cannot perform impedance transformation
      - Performance is influenced by measurement environment

#### Need to Engineer as well as Measure Waveforms



# NLVNA needs a waveform engineering extension to become a productive design tool

- Non-Linear Vector Network Analyzer Limitations
  - Determines non-linear behaviour only into its fixed "nominal 50 ohms" impedance environment
  - Circuit design requires knowledge of on-linear behaviours into an arbitrary impedance environment





## **Engineering the Stimulus Voltage Waveform**

- The concept of open-loop active "load-pull"
- "load-pull" requirement: Modify Reflected Travelling Wave



- Passive System
  - Performance limited by losses in measurement system
    - Couplers, bias-tees, fixture

- Active System
  - Amplify signal to overcome losses
    - Closed loop stability issues





## **Engineering the Stimulus Voltage Waveform**

- multi-harmonic open-loop active "load-pull"



Digital World reaches RF



#### **RF I-V Waveform Measurement & Engineering System**

- Review Fundamental Architecture





#### **RF I-V Waveform Measurement & Engineering System**

- Emerging Commercial Architectures



Demonstrated at IMS 2009 with Tektronix



### **Further Considerations and Developments**

- higher power and/or higher thru-put

- Packaged Devices
  - Requirement for waveform de-embedding
- High Power Devices
  - Requirement for impedance transformation
- High Thru-put
  - Requirement for "closed loop" active load-pull



## **De-embedding Requirements:**

- Packaged 20W Si LDMOS Device





#### **System Impedance Issue:** - Band Limited Waveform Engineering R<sub>opt</sub> >> Z<sub>o</sub> System Impedance << Z<sub>o</sub> System Impedance $\mathsf{R}_{\mathsf{opt}}$ 12 60 60 <u>></u>10 50 Curren 50 Voltage (V 3 urrent Voltage ( 40 8 40 30 6 30 $\widehat{\geq}$ 20 20 2 0 Ο 0 2.0 2.5 0.5 2.0 2.5 0.5 1.5 0.0 1.0 1.5 0.0 1.0 Engineered Time (ns) Time (ns) **Current Waveform** "Engineered" "Engineered" Voltage Waveform Voltage Waveform 50 -20 -Voltage (dBmV) (dBmV) -30 -60<sup>1</sup> 30 -40 · 50 -50 40 -60 · 10 4 5 Freg (GHz) 30-/oltage ( -10 20-10 -30 7 ر 0 0 2 5 6 Ŕ 3 5 6 Ż Ŕ 2 9 4 Freq (GHz) Freq (GHz) High Power Characterization Environment 28


# **Waveform Engineering Issues**

- Active load pull at high powers?

- High  $|\Gamma| = \sqrt{P_{LP}/P_{Gen}}$  requires both values to be almost equal
- High dissipated power  $P_{Dis} = P_{Gen} P_{LP}$  requires a difference
- Both requirements can be only satisfied by a rise of P<sub>LP</sub> and P<sub>Gen</sub>

#### Example:

Load-pull of a 100 Watt device with  $1\Omega$  output impedance in a 50 $\Omega$  system results in the following signal levels:

$$P_{LP} = 1.2 \text{ kW} \quad P_{Gen} = 1.3 \text{ kW}$$
$$VSWR = 50 \quad V_{Max} = 1.4 \text{ kV}$$

#### Prohibitive!



• VSWR: Voltage Standing Wave Ratio



- Solution is a low impedance measurement system

- Build a low-impedance measurement system
  - This is the preferable option but is impractical
- Use of broad impedance transformers
  - Significantly reduced VSWR
  - Maintain integrity of waveforms
  - Resonance free environment over large bandwidth
  - Can employ well established TRL calibration techniques.





- Solution is a low impedance measurement system





- Measurement of a Freescale 100 W LDMOS Device



Only 120 Watts required to probe the optimum load when using 50 to 7.15 impedance transformer





- Critical High power measurement set-up components





# Alternative Active Load Pull Solutions

bro

Pr

Of

 $\checkmark$ 

- address the issue of measurement thru-put



#### Active Open-Loop Load-Pull **System**



#### A traditional *passive load-pull system* can:

at loads independent of power output of DUT

tability & measurement artefacts due to od/ hpedance variations

omplex challenge to independently set harmon

TGanowertake the advantages and calibrate at different frequencies of both of these load setting

#### The active optech niques Proach:

- Sets bermonic impedances independent of each  $\checkmark$ ot
  - a conditional stability
  - not require calibration or preracterisation
  - May take considerable time to iterate to each load



## **Alternative Active Load Pull Solutions**

- developed Envelop Load-Pull System



Can emulate loads that are outside the Smith chart



### **Envelope Active Load Pull Solutions**

- calibrated electronic load-pull system



After calibration

Load Setting Verification

#### Calibration Advantages & Assessment

 The accuracy of the loads set after calibration is independent of the number of data points captured, providing that there are at least 3 points in the set.

No. of Cal Points	Percentage Difference in Loads Set		
	Fundamental (F <sub>o</sub> )	Second Harmonic (F <sub>2</sub> )	Third Harmonic (F <sub>3</sub> )
12	0.0236 %	0.0344%	0.0335%
20	0.0237 %	0.0348%	0.0338%



## **Alternative Active Load Pull Solutions**

- developed Envelope Load-Pull System

#### **Example:**

The third harmonic load was swept around the edge of the Smith chart with 8 equi-spaced impedances, whilst sweeping the fundamental load in a 4x4 grid.









# **Fully Functional NLVNA: Integrated System**

- Waveform Measurement and Engineering



- Investigating and optimizing amplifier modes of operation
  - Development of Class J
- Investigating and optimizing Transistor performance
  - Fan Diagrams
- Behavioural Characterization/Modelling
  - Data Lookup Models

$$\bigvee_{b_1}^{a_1} \xrightarrow{b_2} \bigvee_{a_2}^{b_2} \bigvee_{a_2} \bigvee_{a_2} \bigvee_{a_2} \bigvee_{a_2} \bigvee_{a_2} \bigvee_{a_2} \bigvee_{a_2} \bigvee_{a_2} \bigvee_{a_2} \bigvee_{a_$$



### RF IV Waveform Measurement and Engineering - Role in Supporting Non-Linear CAD Design -



### Centre for High Frequency Engineering

School of Engineering Cardiff University

#### **Contact information**

Prof. Paul J Tasker – *tasker@cf.ac.uk website*: www.engin.cf.ac.uk/chfe



# **Non-Linear CAD Models:**

- state function based formulation

- Time domain formulations
  - Physics Based State function formulation: I & Q
    - Four quasi-static I and Q surface functions
      - Advanced formulations include time delays

$$i_{gs}(t) = I_{g}(v_{gs}(t), v_{ds}(t)) + \frac{\partial Q_{g}(v_{gs}(t), v_{ds}(t))}{\partial t}$$
$$i_{ds}(t) = I_{d}(v_{gs}(t), v_{ds}(t)) + \frac{\partial Q_{d}(v_{gs}(t), v_{ds}(t))}{\partial t}$$



This fundamental formulation is followed by all analytical models and the Root lookup table model



## **Non-Linear CAD Models:**

- behavioral "black box: based formulation

- Frequency or Time domain formulations
  - Behavioral based formulation
    - Many different formulations
      - Analytical or experimental data based

$$i_{ds}(t) = \alpha_0 + \alpha_1 v_{gs}(t - \tau_1) + \alpha_2 v_{gs}(t - \tau_2)^2 + \alpha_3 v_{gs}(t - \tau_3)^3 + \dots$$
$$b_2(\omega) = f(a_1(\omega), a_1(2.\omega), \dots, a_1(n.\omega), a_2(\omega), a_2(2.\omega), \dots, a_2(n.\omega))$$



#### Generally focus on describing a specific behavior



# **RF I-V Waveform Measurement & Engineering**

- role in CAD modelling
- State Function I(V) Q(V) Non-Linear Models
  - Directly Measures Model related parameters I & V
    - I-Q function Extraction
      - Data Lookup Model Generation
    - Analytical Model validation and Optimization

### • Behavioural "Black Box" Non-Linear Models

- Directly Measures Non-Linear Behaviour
  - Directly Import into CAD Tool
    - Data Lookup behavioural model
  - Indirectly Import into CAD Tool
    - Formulated behavioural models (Volterra)
    - Emerging non-linear parameter equivalent to linear s-parameters (Xparameters)



# **Non-Linear CAD Models:**

- state function based formulation

- Requires measurement of the state functions: I & Q
  - DC I-V provides Current State Function
    - Static measurements: trapping and thermal issues
  - S-parameters measure differential of state functions
    - Trapping and thermal issues

$$i_{gs}(t) = \mathbf{I}_{g}(\mathbf{v}_{gs}(t), \mathbf{v}_{ds}(t)) + \frac{\partial \mathbf{Q}_{g}(\mathbf{v}_{gs}(t), \mathbf{v}_{ds}(t))}{\partial t}$$
$$i_{ds}(t) = \mathbf{I}_{d}(\mathbf{v}_{gs}(t), \mathbf{v}_{ds}(t)) + \frac{\partial \mathbf{Q}_{d}(\mathbf{v}_{gs}(t), \mathbf{v}_{ds}(t))}{\partial t}$$



Ideally require direct dynamic measurement of state functions



- indirect extraction from bias dependent s-parameters





- direct extraction from RF I-V Waveforms

dd [mA] Current I

Gate



resulting from an applied and measured terminal voltage and we reverse process and determine state functions?

YES: Solutions in both the time and frequency domain.



- direct extraction from RF I-V Waveforms





- direct extraction from RF I-V Waveforms



- Extraction of state functions for all measured values of Vgs(t)
- Only one large signal measurement needed
- Model extraction or model validation



- direct extraction from RF I-V Waveforms





- direct extraction from RF I-V Waveforms



• Extracted Fully Dynamic Intrinsic I and Q Surfaces of a pHEMT transistor

Morgan et al, IMS 2001



## **Waveform Measurement and Engineering**

- are we looking at the device or the system?





# **Waveform Measurement and Engineering**

- are we looking at the device or the system?

- "Forward and Reverse Looking" Measurements
  - separation in the frequency domain
    - fundamental
      - Input Impedance S<sub>11</sub>(b<sub>1</sub>/a<sub>1</sub>)
    - harmonics
      - source Impedance  $(a_1/b_1)$







"Reverse Looking"

# Waveform Measurement and Engineering

- are we looking at the device or the system?

- "Forward and Reverse Looking" Measurements
  - separation in the time domain
    - Load Impedance  $(a_2/b_2)$  when current generator is active
    - Device Impedance  $(b_2/a_2)$  when current generator is in-active





# **RF I-V Waveform Measurement & Engineering**

- role in CAD modelling
- State Function I(V) Q(V) Non-Linear Models
  - Directly Measures Model related parameters I & V
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      - Data Lookup Model Generation
    - Analytical Model validation and Optimization



# **Transistor RF I-V Waveforms**

- Verification of non-linear CAD models



Measure:  $V_1(t)$ ,  $V_2(t)$  and  $I_1(t)$ ,  $I_2(t)$ 



Import Measured  $V_1(t)$  and  $V_2(t)$  into the simulator

- Control mode of excitation
  - Similar to circuit operation
  - Maximize coverage of output I-V space, state variable space.



Compare Simulated  $I_1(t)$ ,  $I_2(t)$  with Measured  $I_1(t)$ ,  $I_2(t)$ 



### **Transistor RF I-V Waveforms**

- Verification/Optimization of non-linear CAD models

Provides insight to why and where the model is failing to accurately predict non-linear behavior



More robust and useful than what is typically done: simply comparing simulated and measured Power performance

Some divergence at pinch-off



### **Transistor RF I-V Waveforms**

- Verification/Optimization of non-linear CAD models



• Result, in this case, show that the LDMOS model used is not accurately modelling the variation of output capacitance as a function of gate bias.



# **RF I-V Waveform Measurement & Engineering**

- role in CAD modelling
- State Function I(V) Q(V) Non-Linear Models
  - Directly Measures Model related parameters I & V
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    - Analytical Model validation and Optimization
- Behavioural "Black Box" Non-Linear Models
  - Directly Measures Non-Linear Behaviour
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# **Review Linear Design Situation**

- back to basics: s-parameters behavioral models





# **Consider Non-Linear Design Situation**

- large signals: waveform based behavioral models



CAD Design Enabling Tool

 utilize measured waveform data tables in RF CAD Tools



Cannot simply transform waveforms to any arbitrary impedance environment

Can measure as a function of input and/or output fundamental and harmonic load impedances: CAD interpolation and extrapolation



- Direct Waveform Look-up (DWLU) Data Model





- DWLU Data Model Implementation

Data Import Unit constructed in Agilent ADS using FDD & DAC





- DWLU Data Model Utilization



**DWLU Accurately regenerates RF waveforms** 



- DWLU Data Model Utilization





**DWLU** Accurately interpolates RF waveforms



- Parameter Based Data Models: Formulation Concepts

- Non-linear Data look-up
  - Direct looks up measured waveform data
    - Stored in the frequency domain
- Non-linear Data Formulation: Parameter look-up
  - Transform waveform data into "circuit parameters"
    - Equivalent functionality to linear data formulation: s-parameters
      - Circuit analysis and design formulation
      - Travelling wave a-b rather than I-V formulations
    - Agilent Solution: X-parameters
      - Natural extension of linear s-parameters data-set to non-linear dataset
    - Cardiff Formulations
      - Natural extension of X-parameters. Cardiff "Mixing" Formulation for load-pull contours: contains higher order mixing terms


- Formulated Based Data Lookup Models FDLU



Good accuracy for different drive power levels



- Parameter Based Data Models: Formulation Concept
- "Circuit" Formulation Requirement: *remove direct reference to load* Component dependency: *f*(|a<sub>1</sub>|,|a<sub>2</sub>|,(Q/P))



Linear System uses s-parameters: 1st order system



$$b_{1} = \{S_{11} \cdot |a_{1}| \cdot P + S_{12} \cdot |a_{2}| \cdot Q\}$$
  
$$b_{2} = \{S_{21} \cdot |a_{1}| \cdot P + S_{22} \cdot |a_{2}| \cdot Q\}$$



- Parameter Based Data Models: Formulation Concept
  - Use of s-parameters in non-linear design: "Hot" S-parameters
    - Wrong functionality:
      - model circular function
      - measurement elliptical functionality

$$b_{1} = \mathbf{P} \cdot \left\{ \mathbf{S}_{11} \cdot \left| \mathbf{a}_{1} \right| \cdot \left( \frac{\mathbf{Q}}{P} \right)^{0} + \mathbf{S}_{12} \cdot \left| \mathbf{a}_{2} \right| \cdot \left( \frac{\mathbf{Q}}{P} \right)^{1} \right\}$$
$$b_{2} = \mathbf{P} \cdot \left\{ \mathbf{S}_{21} \cdot \left| \mathbf{a}_{1} \right| \cdot \left( \frac{\mathbf{Q}}{P} \right)^{0} + \mathbf{S}_{22} \cdot \left| \mathbf{a}_{2} \right| \cdot \left( \frac{\mathbf{Q}}{P} \right)^{1} \right\}$$





Parameter dependency: S<sub>m,n</sub>(|a<sub>1</sub>|,|a<sub>2</sub>|)



- Parameter Based Data Models: Formulation Concept
- Non-Linear System: *include mixing components* 
  - Weakly Non-Linear System: 3<sup>rd</sup> order: relates to S&T Parameters (X-parameters)

$$b_{1} = \left\{ X_{12}^{T} \cdot |a_{2}| \cdot \frac{P^{2}}{Q} + X_{11}^{S} \cdot |a_{1}| \cdot P + X_{12}^{S} \cdot |a_{2}| \cdot Q + X_{11}^{T} \cdot |A| \cdot \frac{Q^{2}}{P} \right\} \xrightarrow{2.\omega_{1} - \omega_{2}} \xrightarrow{2.\omega_{2} - \omega_{1}} b_{2} = \left\{ X_{22}^{T} \cdot |a_{2}| \cdot \frac{P^{2}}{Q} + X_{21}^{S} \cdot |a_{1}| \cdot P + X_{22}^{S} \cdot |a_{2}| \cdot Q + X_{21}^{T} \cdot |A| \cdot \frac{Q^{2}}{P} \right\} \xrightarrow{P \quad Q} \xrightarrow{P \quad Q} \xrightarrow{Q.Q/P}$$

For small perturbation reduces to three parameters: X-parameters

$$b_{1} = P \cdot \left\{ X_{12}^{T} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{-1} + X_{11}^{S} \cdot |a_{1}| \cdot \left(\frac{Q}{P}\right)^{0} + X_{12}^{S} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{1} + X_{11}^{T} \cdot |a_{1}| \cdot \left(\frac{Q}{P}\right)^{2} \right\}$$
  

$$b_{2} = P \cdot \left\{ X_{22}^{T} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{-1} + X_{21}^{S} \cdot |a_{1}| \cdot \left(\frac{Q}{P}\right)^{0} + X_{22}^{S} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{1} + X_{21}^{T} \cdot |a_{1}| \cdot \left(\frac{Q}{P}\right)^{2} \right\}$$

Parameter dependency: X<sub>m,n</sub>(|a<sub>1</sub>|)

Allow  $\omega_1 = \omega_2$ 



- Parameter Based Data Models: Formulation Concept
- 3rd Order Mixing Model: S&T-parameters (X-parameters)
  - Significantly improved functionality:
    - model is now an elliptical function
    - measurement elliptical functionality
  - Next Step
    - Compute local X-parameters
      - function of load
    - Allow for full amplitudes dependence
    - Increase order of mixing

$$b_{1} = P \cdot \left\{ X_{12}^{T} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{-1} + X_{11}^{S} \cdot |a_{1}| \cdot \left(\frac{Q}{P}\right)^{0} + X_{12}^{S} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{1} + X_{11}^{T} \cdot |a_{1}| \cdot \left(\frac{Q}{P}\right)^{2} \right\}$$
  
$$b_{2} = P \cdot \left\{ X_{22}^{T} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{-1} + X_{21}^{S} \cdot |a_{1}| \cdot \left(\frac{Q}{P}\right)^{0} + X_{22}^{S} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{1} + X_{21}^{T} \cdot |a_{1}| \cdot \left(\frac{Q}{P}\right)^{2} \right\}$$

$$0.65$$
 -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0.60$  -  $0$ 



- Parameter Based Data Models: Formulation Concept
- Non-Linear System: *include mixing components* 
  - Strongly Non-Linear System: n<sup>th</sup> order: relates to C&U Parameters (R-parameters)

$$b_{1} = P \left\{ S_{11} \cdot |a_{1}| \cdot \left(\frac{Q}{P}\right)^{0} + S_{12} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{1} \right\}$$

$$b_{2} = P \left\{ S_{21} \cdot |a_{1}| \cdot \left(\frac{Q}{P}\right)^{0} + S_{22} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{1} \right\}$$

$$b_{2} = P \left\{ S_{21} \cdot |a_{1}| \cdot \left(\frac{Q}{P}\right)^{0} + S_{22} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{1} \right\}$$

$$b_{1} = P \left\{ X_{12}^{T} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{-1} + X_{11}^{S} \cdot |a_{1}| \cdot \left(\frac{Q}{P}\right)^{0} + X_{12}^{S} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{1} + X_{11}^{T} \cdot |a_{1}| \cdot \left(\frac{Q}{P}\right)^{2} \right\}$$

$$b_{2} = P \left\{ X_{22}^{T} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{-1} + X_{21}^{S} \cdot |a_{1}| \cdot \left(\frac{Q}{P}\right)^{0} + X_{22}^{S} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{1} + X_{21}^{T} \cdot |a_{1}| \cdot \left(\frac{Q}{P}\right)^{2} \right\}$$

$$b_{1} = P \left\{ R_{1,2} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{-2} + R_{1,1} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{-1} + R_{1,0} \cdot |a_{1}| \cdot \left(\frac{Q}{P}\right)^{0} + R_{1,1} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{1} + R_{1,2} \cdot |a_{1}| \cdot \left(\frac{Q}{P}\right)^{2} + R_{1,3} \cdot |a_{1}| \cdot \left(\frac{Q}{P}\right)^{3} \right\}$$

$$b_{2} = P \left\{ R_{2,2} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{-2} + R_{2,1} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{0} + R_{2,1} \cdot |a_{2}| \cdot \left(\frac{Q}{P}\right)^{1} + R_{2,2} \cdot |a_{1}| \cdot \left(\frac{Q}{P}\right)^{2} + R_{2,3} \cdot |a_{1}| \cdot \left(\frac{Q}{P}\right)^{3} \right\}$$



- Parameter Based Data Models: Cardiff Formulation
  - Modelling with Extracted Fundamental  $R_{m,n}$  components:  $g(|a_1|, |a_2|)$ 
    - Accurate reproduction of measured b<sub>2</sub> contours (load-pull contours) with 7<sup>th</sup> order (Q/P) phase model
    - Avoids any implicit load based lookup

$$b_{m} = P.f(|a_{1}|,|a_{2}|,(\frac{Q}{P})) = P.\sum_{n=-(N-1/2)}^{n-(N+1/2)} \left\{ R_{m,n}(\frac{Q}{P})^{n} \right\}$$
Parameter
dependency:
 $R_{m,n}(|a_{1}|, |a_{2}|)$ 
The order model: R-parameters
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Collapse large data lookup to small (6\*12 or 8x12) R<sub>m.n</sub> parameter lookup

-0.2

-0.3

measured b2 — modelled b2



- Parameter Based Data Models: Cardiff Formulation
- Cardiff "Circuit" Parameter Formulation
  - Generalized to n<sup>th</sup> order in terms of the relative phase component (Q/P)

$$b_{m} = P.f\left(|a_{1}|,|a_{2}|,\left(\frac{Q}{P}\right)\right) = P.\sum_{n=-\binom{N/2}{2}-1}^{n=\binom{N/2}{2}} \left\{ R_{m,n}\left(\frac{Q}{P}\right)^{n} \right\} \text{ where } R_{m,n} = g(|a_{1}|,|a_{2}|)$$

- Determination of parameters  $R_{m,n}$  requires measurements at constant  $|a_1|$  and  $|a_2|$  while sweeping relative phase component (Q/P), normalized to optimum load: easy to achieve with active load-pull





- Parameter Based Data Models: Cardiff Formulation
- "Circuit" Formulation that is an extension of linear s-parameters
  - remove direct reference to load
  - Formulation dependency:  $f(|a_1|, |a_2|, (Q/P))$ 
    - Function dependency: *f*(|a<sub>1</sub>|,|a<sub>2</sub>|)



$$\mathbf{b}_{m} = \mathbf{P}.f\left(|\mathbf{a}_{1}|,|\mathbf{a}_{2}|,\left(\frac{\mathbf{Q}}{\mathbf{P}}\right)\right) = \mathbf{P}.\sum_{n=-\binom{N/2}{2}-1}^{n=\binom{N/2}{2}} \left\{ R_{m,n}\left(\frac{\mathbf{Q}}{\mathbf{P}}\right)^{n} \right\}$$

Parameter dependency:  $R_{m,n}(|a_1|, |a_2|)$ 



- Parameter Based Data Models: Cardiff Formulation
  - Magnitude Function Fitting to Extracted Fundamental  $R_{m,n}$  components:  $g(|a_1|, |a_2|)$ 
    - $\mathsf{R}_{\mathsf{m},\mathsf{n}} = \alpha_0 + \alpha_1 |\mathbf{a}_2| + \alpha_2 |\mathbf{a}_2|^2 + \alpha_3 |\mathbf{a}_2|^3 + \alpha_4 |\mathbf{a}_2|^4 + \alpha_5 |\mathbf{a}_2|^5 + \alpha_6 |\mathbf{a}_2|^6 + \alpha_7 |\mathbf{a}_2|^7$
    - Only 20 relevant coefficients
      - Accurate reproduction of measured b<sub>2</sub> contours (load-pull contours) with 7<sup>th</sup> order model





7<sup>th</sup> order model: R-parameters



- Parameter Based Data Models: CAD Implementation

Schematic of ADS Simulation





# **RF I-V Waveform Measurement & Engineering**

- role in CAD modelling
- State Function I(V) Q(V) Non-Linear Models
  - Directly Measures Model related parameters I & V
    - Analytical Model validation and optimization
    - I-Q function Extraction
      - Data Lookup Model Generation

#### Behavioral "Black Box" Non-Linear Models

- Directly Measures Non-Linear Behaviour
  - Directly Import into CAD Tool
    - Data Lookup behavioural model
  - Indirectly Import into CAD Tool
    - Formulated behavioural models (Volterra)
    - Emerging non-linear parameter equivalent to linear s-parameters (Xparameters)

# PRIFYSGO

#### **RF IV Waveform Measurement and Engineering** - Role in Transistor Characterization and Amplifier Design -



#### Centre for High Frequency Engineering

School of Engineering Cardiff University

**Contact information** 

Prof. Paul J Tasker tasker@cf.ac.uk website: www.engin.cf.ac.uk/chfe



**IEEE** IEEE MTT-S Distinguished **Microwave Lecturer** 2008-2010



# **RF Waveform Measurement and Engineering**

- powerful dynamic transistor characterization tool

- Basic Concept
  - Use RF Waveform Measurement and Engineering Systems to investigated both the transistors dynamic I-V (Current-Voltage) plane and its Q-V (Charge-Voltage) plane
    - Both qualitative and quantitative
    - Alternatives: DC I-V, Pulsed I-V, bias dependent s-parameters
- Applications
  - Technology Evaluation
    - Observe and quantify its dynamic large signal response
  - Technology Optimization
    - Link technology design to system performance
  - Technology Modelling
    - support the development of CAD tools
  - Circuit Design Tool
    - Support the development of Power Amplifiers



### **RF Waveform Measurement and Engineering**

- powerful dynamic transistor characterization tool

- Transistor Characterization: Case Study
  - Use RF Waveform Measurement and Engineering Systems to investigated general performance of Transistor Technology
    - Current Limits, Modes of Operation, RF Cooling



- Detailed Insight into Dynamic Behaviour Limitations
  - Measure Input voltage and current waveforms
    - function of input drive level



- Detailed Insight into Dynamic Behaviour
  - Gate Diode: Forward Diode
     Conduction and Reverse
     Breakdown
  - Gate Capacitance
- Relevant information for both
  - Device Engineer
  - PA Circuit Designer

AlGaAs/InGaAs HFET @ 4 GHz



- Detailed Insight into Dynamic Behaviour Limitations

• Measure Output voltage and current waveforms



- function of input drive level
- Detailed Insight into Dynamic Behaviour
  - Drain Current Saturation: Knee Region and Breakdown
  - Gate-Drain Trans-capacitance
- Relevant information for both
  - Device Engineer
  - PA Circuit Designer

#### AlGaAs/InGaAs HFET @ 4 GHz



- Detailed Insight into Dynamic Behaviour Limitations



@ 4.0 GHz

Dynamic Transfer Characteristic Measurements

- Device Response
  - Waveform Shapes
  - Insight provided by eliminating time axes
    - Effects of dynamic transfer characterisation clearly observed
      - DC/RF Dispersion
    - Effects of Delay/Trans-capacitance clearly observed

• I-Q Extraction





- Detailed Insight into Dynamic Behaviour Limitations



Dynamic Breakdown in Low Noise AlGaAs/InGaAs HFET's

- Device Response
  - Waveform Shapes
  - Insight provided by eliminating time axes
    - Effects of dynamic gate-drain breakdown clearly observed



- Detailed Insight into Dynamic Behaviour Limitations



Device Response

- Waveform Shapes
- Insight provided by eliminating time axes
  - Effects of dynamic RF cooling clearly observed
- Linked with pulsed RF I-V technique

RF Cooling in Handset PA AlGaAs/InGaAs HBT's



### **Measured RF I-V Waveforms**

– Unifying Analysis Tool





# Measured RF I-V Waveforms

– General purpose Analysis Tool

Output Power versus Input Power and Base Bias Voltage



2<sup>nd</sup> Harmonic Output Power versus Input Power and Base Bias Voltage



Experimental Emulate the affect of varying external parameters: In this case input drive level and input DC bias voltage

Note, have all information on magnitude and phase of all voltage and current Fourier components

#### Efficiency versus Input Power and Base Bias Voltage



3<sup>rd</sup> Harmonic Output Power versus Input Power and Base Bias Voltage



GaAs HBT Performance as a function of Load Impedance



# **RF Waveform Measurement and Engineering**

- powerful dynamic transistor characterization tool

- Transistor Characterization: Case Study
  - Use RF Waveform Measurement and Engineering Systems to investigated factor limiting the observed power performance of the emerging GaN Transistor Technology
    - Current Collapse, Knee Walkout, Poor Pinch-off



- visualizing the DC-RF Dispersion Problem

Commonly observed that the RF Power Performance of the GaN transistor was less than predicted (DC I-V & s-parameters)



Approach: Drive the GaN transitor in to compression while measuring RF Output V & I Waveforms (840MHz)







Waveforms show compression at RF Boundaries differs from the DC Boundaries, hence clearly identifying source of the problem: knee walkout or current collapse



- visualizing the DC-RF Dispersion Problem
- Measured drain current with fundamental load-pull only
  - Complex load-lines are more difficult to interpret: cause concern in extracting boundaries





- Measured drain current with 3-harmonic load-pull
  - Simple load-lines are easy to interpret: no ambiguity in extracting boundaries





• For quantitative results make full use of waveform engineering, however, fundamental alone does provide for qualitative insight.



- visualizing the DC-RF Dispersion Problem
- Investigate factors that influence the knee walkout or current collapse problem: Quiescent Drain Bias Voltage



The Dynamic RF knee boundary shifts as DC drain bias increases

(10, 15 and 20V)

# This limits achievable power densities

Still unclear whether should relate problem to knee walkout or current collapse



# **RF "Fan Diagram": GaN HFET Application**

- evaluation of trapping ("knee walkout") problem





### **RF "Fan Diagram": GaN HFET Application**

- evaluation of trapping ("knee walkout") problem





- Class A RF I-V Waveforms versus Pulsed I-V

- Comparison with pulsed I-V Measurements
  - Determine boundaries by simultaneously pulsing both gate and drain voltage (DIVA System) from quiescent Class A bias point
- 200 RF Dynamic Load Lines Output Current b [mA] 150 DC Quiescent Bias Point 100 Clearly observe both predict very similar "RF knee-50 walkout" as  $V_{D}$  increases 0 10 20 30 40 50 60 0 Output Voltage V<sub>D</sub> [V] 160 l₀[mA] Compressed current waveforms confirm that 120 80 the device is in compression **4**0 200 30 40 0 100 500 600 700 17



- Class B RF I-V Waveforms versus Pulsed I-V

- Comparison with pulsed I-V Measurements
  - Problem in this case is that the quiescent bias point is not on the DC I-V plane: Where do we pulse from?
- Same voltage V<sub>G</sub> bias point



 "RF knee-walkout" is sensitive to mode of operation







# **RF Waveform Measurement and Engineering**

- powerful dynamic transistor characterization tool

- Transistor Characterization: Technology Evaluation and Optimization
  - Poor Pinch-off very similar to knee walkout investigations
  - Reliability and device stress: emerging area.



# **RF "Fan Diagram": GaN HFET Application**

- evaluation of buffer layer design ("soft pinch-off")

- Evaluate Different Buffer Layer Design (Level of Fe Doping)
  - Elimination of soft pinch-off
  - No significant effect at the Knee Region





#### **Transistor RF I-V Waveforms: GaN HFET Application**

- Detailed Insight into Dynamic stress/reliability Limitations

- RF waveforms were periodically sampled 100 times during the 1.5hour RF stress period
- 1.8GHz Large-signal CW ( $\approx$  3dB of gain compression), V<sub>D</sub> = 20V, Class A, Zf<sub>0</sub>  $\approx$  P<sub>OUT</sub>





- Dynamic Input Characteristics
  - Highlights the displacement current through C<sub>GS</sub>
  - A small increase in leakage can be seen at the breakdown end



#### **Transistor RF I-V Waveforms: GaN HFET Application**

- Detailed Insight into Dynamic stress/reliability Limitations



- No change around  $V_T \approx -6V$ 



# **RF Waveform Measurement and Engineering**

- powerful "real time" design tool

- Basic Concept
  - Use RF Waveform Measurement and Engineering Systems to investigated and achieve the required circuit/system performance.
    - Key: Performance is theoretically defined in terms of the voltage and/or current waveforms
    - Alternatives: build and test, CAD tools (requires non-linear model)
- Relevant Circuit Design Problem
  - Those that involve strongly non-linear ('large signal") device operation, not weakly non-linear or linear operation
    - Power Amplifier Design beyond Class A/AB
    - Switching Amplifiers
    - Frequency Multipliers/Dividers



#### **Review PA Design Situation**

- too reliant on Build & Test




### **Review PA Design Situation**

- incorporate Basic Principles: "Waveform Engineering"





# **RF I-V Waveform Engineering**

- insight provided by having measured waveforms

HBT biased to operate in class B, low quiescent current

- Current waveform is half rectified
- Voltage waveform is not sinusoidal

Engineer harmonic impedances: Short second/third harmonic

- Current waveform is half rectified
- Voltage waveform is now sinusoidal



**Design Example: Class B Amplifier Emulation/Measurement** 



# **RF I-V Waveform Engineering**

- insight provided by having measured waveforms

HBT biased to operate in class B, low quiescent current

- Current waveform is half rectified
- Voltage waveform is not sinusoidal

Engineer harmonic impedances: Short/open second/third harmonic

- Current waveform is half rectified
- Voltage waveform is now a square wave



**Design Example: Class F Amplifier Emulation/Measurement** 



- "on-line" direct utilization in amplifier design cycle





- powerful dynamic transistor amplifier design tool

- Transistor Amplifier Design: Case Study
  - Use RF Waveform Measurement and Engineering Systems to investigated how to realize in practice the theoretically predicted high efficiency modes of operation
    - Class B, Class F or their variants



- requires engineer of voltage and current waveforms

#### Simple Theoretical Understanding



Advanced Theoretical Understanding

- Designed in an intelligent manner a class F efficient RF Power Amplifier
  - Maximized Output Power
  - Realized 75% PAE
- Ready for realization



- review of theoretical understanding: Class F

Ideal Class F occurs if the current and voltage waveforms are simultaneously engineered such that:



The voltage waveform contains f<sub>0</sub> and correct proportions of the odd harmonics

If this is achieved there is no overlap between the waveforms, resulting in no dissipated power and 100% efficiency.



- review of practical constraints: System and Circuit Bandwidth

- The achievable efficiency in a real design is constrained by our ability to correctly engineer the ideal waveforms.
  - Circuit Bandwidth
    - In real PA designs harmonic control is commonly limited to 2f<sub>0</sub> and 3f<sub>0</sub> due to the complexity of matching circuits.
    - Following the analysis of Rhodes,\* for a Class F design with harmonics only up to 3f<sub>0</sub> ideally terminated, the maximum achievable efficiency is limited to an upper limit of 90.6% assuming your matching network is lossless!

We can quantify the ability to engineer ideal waveforms by two factors  $\eta_{current}$  and  $\eta_{voltage}$  using the DC and fundamental RF components:

$$\eta_{\text{current}} = i_{\text{RF}} / (\sqrt{2} \times I_{\text{DC}}) \quad \eta_{\text{voltage}} = v_{RF} / (\sqrt{2} \times V_{DC})$$

\* J.D. Rhodes "Output universality in maximum efficiency linear power amplifiers" International Journal of Circuit Theory and Applications, volume 31, 2003, pp.385-405



- review of practical constraints: System and Circuit Bandwidth

Class	η <sub>current</sub>	$\eta_{voltage}$	$\eta = \eta_{\text{current}} \times \eta_{\text{voltage}} \times 100 [\%]$
Α	0.707	0.707	50
В	1.111	0.707	78.5
F (Ideal)	1.111	0.900	100
<b>F</b> (3f <sub>0</sub> )	1.111	0.816	90.6







- review of practical constraints: Transistor Limitations

 A further limitation on achievable efficiency in practical designs arises from features of real transistor characteristics which make a fraction of the dc dissipated power unavailable for conversion to RF power:



We can quantify the ability to engineer ideal waveforms by two factors  $\eta_{current}$  and  $\eta_{voltage}$  using the DC and fundamental RF components:

 $\eta_{\text{current}} = \dot{\mathbf{n}}_{\text{RF}} / (\sqrt{2} \times \mathbf{I}_{\text{DC}}) \quad \eta_{\text{voltage}} = v_{RF} / (\sqrt{2} \times V_{DC})$ 



- review of practical constraints: Impedance Scaling

• Starting with Class B bias for a half rectified current waveform, what is the effect of tuning the second harmonic to a short?





Eliminated 2<sup>nd</sup> harmonic from voltage waveform



- review of practical constraints: Impedance Scaling

- Good short circuits harder to achieve relative to a Small R<sub>opt</sub>
- Makes high efficiency harder to achieve in large devices
- Possible solution include numerous short circuits integrated onto the die to allow subsets of transistor cells to be given a better short...
- Packaging parasitics can form a filter blocking higher harmonics...



Harmonic Termination Ratio: Z @  $2f_0$  normalised by Z @  $f_0$ 



- review of practical constraints: Transistor Transfer Characteristic

- Need to select a suitable drive level for harmonic generation (approaching P1dB)
- Ideally we need to ensure we have separated the harmonics:
  - only odds in the voltage waveform
  - only evens in the current waveform

...but will the practical device allow this!



# **Engineering The Current Waveform**

- Gate bias control to null the odd harmonics

- In class F optimum performance will only occur if the most significant odd harmonics (usually only consider 3f<sub>0</sub>) are not present in the current waveform.
- Using Fourier analysis of the measured current waveforms we can locate this optimal case...



- Practical constraints:
  - Other harmonics are not zero
  - Optimum bias is a function of voltage waveform "shape" and RF drive level



# **Engineering The Voltage Waveform**

- Open tuned 3<sup>rd</sup> harmonic gate bias sweep
- Engineering the voltage waveform to a square wave involves tuning the 3<sup>rd</sup> harmonic to an open and increasing the fundamental load to maintain the same current swing.
  - Note, the optimum Class F behaviour will only occur if the current at 3f<sub>0</sub> remains null.



- Since Class F requires an open termination at 3f<sub>0</sub>, it is impossible to verify this condition has been met by direct measurement of the 3f<sub>0</sub> harmonic current.
  - Consider  $v_{3rd}/v_{fund}$  ratio. Theory predicts 1/6 (=0.167)



# **Engineering The Voltage Waveform**

- Why was extra third harmonic developed?
- Plotting the dynamic load-line for the final design shows the interaction of the waveforms with the knee region.
- Ideal square wave requires all harmonics – we only control the first 3
- Optimal 3 harmonic only voltage waveform has a  $v_{3rd}/v_{fund}$  ratio of 1/6 if the boundary conditions are ideal (vertical)
- However due to the finite on-resistance of the real knee boundary the optimal ratio is higher, at almost 1/4





- The final experimentally engineered "class F" waveforms achieved a drain efficiency value of 75%,
- This is extremely high given the boundary conditions and drain bias of the real device used.



- "on-line" direct utilization in amplifier design cycle

Simple Theoretical Understanding: Provides If not How and Why



Advanced Theoretical Understanding: Must provide How and Why



developing theoretically based but practically relevant waveform engineering design methodologies 41



#### Apply Waveform Design Methodology - 5W Si LDMOS into Class F Emulation/Design

Engineered and Measured Intrinsic Waveforms: Design Aid



#### High Power Class F Design

#### 5W Si LDMOS @ 900 MHz

- Class F clearly achieved
- High Power 36.0 dBm (4W)
- High Efficiency 77.2%

#### 5W Si LDMOS @ 2100 MHz

- Class F clearly achieved
- High Power 35.9 dBm (4W)
- High Efficiency 77.1%



# **Apply Waveform Design Methodology**

- 10W GaN HFET & 5W Si LDMOS into Inverse Class F

Engineered and Measured Intrinsic Waveforms: Design Aid



#### 5W Si LDMOS @ 900 MHz

- Inverse Class F clearly achieved
- High Power 37.3 dBm (5.4W)
- High Efficiency 73%

- Inverse Class F clearly achieved
- High Power 40.8 dBm (12W)
- High Efficiency 81.5%



#### **12W Inverse class-F Amplifier Realisation**

- right first time design using CREE 10W device





- *'Right first time'* waveform based design through the realisation of a high-performance inverse class-F PA
- Impressive efficiency of 81% at high output powers
- High Power achieving 12W form a 10W device





- powerful dynamic transistor amplifier design tool

- Investigation of "New Design Space"
  - Use RF Waveform Measurement and Engineering Systems to stimulate new theoretically investigations in alternative high efficiency modes of operation
  - Move beyond the discrete design point thinking to design continuum thinking
  - The Class B to Class J Continuum
    - New Theory
    - Improved Bandwidth



- provides for new theoretical insight

- Consider the Class B and Class J Mode of operation
  - Both have a half rectified current waveform
  - Both have the same theoretical power and efficiency values
  - But have very different voltages waveforms
    - Different fundamental and 2nd harmonic reactance's





- Rhodes<sup>\*</sup> provide some mathematical insight
  - Optimum fundamental reactance is mathematical defined by harmonic reactive terminations

\* J.D. Rhodes "Output universality in maximum efficiency linear power amplifiers" International Journal of Circuit Theory and Applications, volume 31, 2003, pp.385-405



- provides for new theoretical insight
- They are just different solutions of the same mode?
  - The Class J Class B Class J\* Continuum
    - $v(\theta) = (1 \beta \cos \theta)(1 \alpha \sin \theta), \quad (-1 \le \alpha \le 1)$
  - Many more possible solutions





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- experimental validation of new theoretical insight





- Class J-B-J\* Continuum Sensitivity Analysis

#### On Cree 2W on-wafer device:

- $R_1$  held to  $R_{opt}$ ,  $R_2$  held to  $1.5\Omega$
- X<sub>1</sub> and X<sub>2</sub> were swept to examine the impact of the deviation off the Class-JB continuum contour

#### **Results**

- Class-JB continuum visually identifiable with a high efficiency contour
- Roll-off of efficiency is greater for a deviation in fundamental load compared to second harmonic





**Increased design flexibility** 



### **Realising Class-J Matching**



- Compromises need to be made/considered across this size of bandwidth.
- Fundamental load impedance matching given priority.
- Second harmonic already close to optimum class-J reactance at centre frequency of desired bandwidth as a result of output capacitance C<sub>ds</sub>

 $\rightarrow$  Z<sub>2f0</sub> allowed more latitude during the design.

- Shunt shorted-stub increases the effective capacitive reactance of second harmonic load at lower frequencies.



### Performance of PA Prototype (1st it.)



- The PA shows a measured 60%-and-above drain efficiency across the frequency range 1.35-2.25GHz.
- Drain efficiency measured for PA, model simulation and load-pull emulation.
- Closely agreeing results with the load-pull emulation.
- Output power across this same bandwidth is 9-11Watts (device-rated power).

Proposed bandwidth not met entirely, but still a 50% bandwidth PA achieved.



#### Performance of PA Prototype (2<sup>nd</sup> it.)

 Second design iteration extending high-efficiency operation across the originally intended PA bandwidth of 1.5-2.5GHz



● Input matched PA → Resulting gain and PAE profiles





– a powerful tool and concept



Waveform are the unifying link between device technology, circuit design and system performance



#### RF IV Waveform Measurement and Engineering - Emerging Multi-Tone Systems -



#### Centre for High Frequency Engineering

School of Engineering Cardiff University

#### **Contact information**

Prof. Paul J Tasker – *tasker@cf.ac.uk website*: www.engin.cf.ac.uk/chfe



- Demand for Multi-Tone Excitation
  - Synthesize "real" system stimulus







- Demand for Multi-Tone Excitation
- CW (Single Tone) to Modulated (Multi-Tone) Measurement System Development
  - RF Multi-Tone I-V Waveform Measurement
    - Intelligent Sampling
    - Inclusion of IF (Base-band signals)
  - RF Multi-Tone IV Waveform Engineering
    - IF (Base-band) active load-pull
- Application
  - Memory Investigations: Base-band Electrical Memory
- CW (Single Tone) to Modulated (Multi-Tone) Measurement System Development
  - RF Multi-Tone IV Waveform Engineering
    - RF active load-pull (Digital ELP)



- Multi-Tone Measurement Requirements

- Need to extend sampling strategy to accommodate multi-tone excitation
  - folded and interleaved sampling
- Need test-set architecture to account for all frequency components
  - RF hardware between DUT and the sampling receivers ignores base-band components





- Intelligent Sampling: Review CW Case

#### • CW Period Stimulus on a Specific Frequency Grid

- Sample over many RF cycles (M.P + C.Prime)
  - M is the number of RF cycles contained within the sample period
- Engineer Sampling T<sub>s</sub>=M.T<sub>rf</sub> + C.Prime.T<sub>rf</sub>/P (P=sampled points, C=cycles),
  - Multiple solutions  $f_{rf} = f_s.(M.P+C.Prime)/P$  are sampled into Fourier location C
  - If Prime (prime number) is greater than 1, time interleaving also occurs
- Independently Engineer the Fourier location of frequency components





- Intelligent Sampling: Multi-Tone Case

- Multi-Tone Period Stimulus
  - Sample over many modulated RF Cycles
  - Independently engineer Fourier location of carrier (and harmonics) and modulation (and distortion)

•  $T_s = N.T_{mod} + T_{mod}/P$  thus  $f_{mod} = f_s.(N.P+1)/P$  (Fourier Location 1) •  $T_s = M.T_{rf} + C.T_{rf}/P$  thus  $f_{rf} = f_s.(M.P+C)/P$  (Fourier Location C)





- Multi-Tone versus CW




# **Non-Linear Vector Network Analyzer:**

- Basic Architecture with RF and IF Test-set

- Requires a very broadband four channel receiver
- Utilizes integrated RF and IF directional couplers for detection/separation of waves
  - Critical components
    - Bias Tee/Diplexer
    - Bias-Tee/Combiner
    - IF Bis-Tee

Measures RF & IF a<sub>n</sub>(t) and b<sub>n</sub>(t) time varying Voltage Travelling Waves





## **RF I-V Waveform Measurement & Engineering**

- Need for IF Measurements



#### Waveform measurements necessitates all spectral components

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# **RF I-V Waveform Measurement & Engineering**

- Classical IF Measurements and Data Presentation



- Classical 2-tone often used
- Observation of IM magnitude and <u>symmetry</u>
- Limitation Little insight into sources of memory – just the consequences
- Traditional Instrumentation Spectrum Analysers,
- New Instrumentation VSA, and recently PNA-X



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# **RF I-V Waveform Measurement & Engineering**

- Non-Classical IF Measurements and Data Presentation

- What is envelope domain analysis
- Powerful approach intuitive
  - Critical to to capture all significant spectral components
  - DC, Baseband and RF spectra then used to 'rebuild' the modulation envelope.
  - Mag and Phase information key in this process.



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# **RF I-V Waveform Measurement & Engineering**

- Non-Classical IF Measurements and Data Presentation





# **RF I-V Waveform Measurement & Engineering**

- Investigation Linearity Issues (i.e. Memory)

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# **Realization of IF (Base-band) Engineering**

- initial focus on bias circuit electrical memory issues





# **Realization of IF (Base-band) Engineering**

- initial focus on bias circuit electrical memory issues





- Effect on RF Carrier Output Power (HBT)





Control of interaction of output dynamic waveforms with knee region explains carrier Power and efficiency sensitive to IF load impedance.



- Effect of Amplitude on Intermodulation Distortion (HBT)



Control of interaction of output dynamic waveforms with knee region explains intermodulation sensitive to IF load impedance.



- Effect of Amplitude on Intermodulation Distortion (HBT)





- Effect of Phase on Intermodulation Distortion (HBT)



Mixing of transfer and output non-linearities caused by interaction of dynamic output waveforms with knee region explains sensitivity to IF load impedance. **19** 



- Effect of Phase on Intermodulation Distortion (HBT)





## IF Input Voltage Engineering (Pre-distortion)

- Effect on RF Carrier Output Power (HBT)





Waveform shape explains carrier power and efficiency sensitive to IF source impedance.



## IF Input Voltage Engineering (Pre-distortion)

- Effect on Intermodulation Distortion (HBT)



 $i_o(t) = a_0 + a_1 \cdot v_i(t) + a_2 \cdot v_i(t)^2 + a_3 \cdot v_i(t)^3$ Transfer function explains intermodulation sensitivity to IF source impedance



## IF Input Voltage Engineering (Pre-distortion)

- Optimization of Linearization Process (HBT)



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# **Realization of IF (Base-band) Engineering**

- continue focus on bias circuit electrical memory issues





#### **Linearity and Memory Investigations:** - 20W Si LDMOS





- Optimum IF termination to simultaneously minimize IMD3 and IMD5





- Optimum IF termination to simultaneously minimize IMD3 and IMD5

Do these identified optimums change with tone-spacing?



- Indications are that the optimum IF impedances is independent of modulation frequency
- These impedances can be easily synthesised using an ET process



- Envelop Domain: Linearity Investigations





- Demystifying Memory: Envelop Domain Simulations

- 27ps delay line used as DUT
- 2-tone excitation
- 80 MHz tone separation used
- imparts 0.8 degree phase shift onto the envelope







- Demystifying Memory: Active Device Measurements

#### **Device specifics**

2W GAN Cree die. Fmax 40 GHz, gate width: 2x360um gate length 0.45um, Transit time 2.2ps Gm=180uS.

#### **Observations**

- Dynamic trajectories are well aligned with quasi-static case.
- Again, under controlled conditions, becomes possible to expose delay.
- The delay here is bigger however (~45ps) than that observed for the 27ps delay line.
- This can be explained here by transit time and charge time for intrinsic parasitics





- Demystifying Memory: Active Device Measurements

#### **Observation**

Majority of Looping can be removed by applying an approximate -45 ps linear delay to the output envelope



Observed delay can be explained (in this case) by intrinsic parasitic delay and transit time.



 $\begin{array}{c} Cgs \sim 0.72 \ pF \sim 35 \ ps \\ Cgd \sim 0.06 \ pF \sim \ 3 \ ps \\ Cds \sim 0.13 \ pF \sim \ 6 \ ps \\ Tgm \qquad \sim \ 2 \ ps \end{array}$ 

Total delay ~ 46 ps



#### - Envelop Domain: Linearity Investigations





# **RF I-V Waveform Measurement & Engineering**

- Demand for Multi-Tone Excitation
- CW (Single Tone) to Modulated (Multi-Tone) Measurement System Development
  - RF Multi-Tone I-V Waveform Measurement
    - Intelligent Sampling
    - Inclusion of IF (Base-band signals)
  - RF Multi-Tone IV Waveform Engineering
    - IF (Base-band) active load-pull
- Application
  - Memory Investigations: Base-band Electrical Memory
- CW (Single Tone) to Modulated (Multi-Tone) Measurement System Development
  - RF Multi-Tone IV Waveform Engineering
    - RF active load-pull (Digital ELP)



- consider in-band and harmonic circuit electrical memory issues





- consider in-band and harmonic circuit electrical memory issues





- Envelope load-pull solution: Envelop Tracking
  - Open loop at RF but a closed loop at envelope frequencies
    - No loop oscillations as no direct RF feedback
    - Reflection coefficient constant irrespective of the signal coming from DUT
  - Impedances set by simple electronics controlled by the X & Y inputs
    - Suitable for modulated signals





- Envelope load-pull solution: Envelop Tracking



9 Tone Modulated Signal => Confined to a few 100 kHz at present







- Envelope load-pull solution: 'Instantaneous' power sweeps





- Envelope load-pull solution: Envelop Tracking
  - Open loop at RF but a closed loop at envelope frequencies
    - No loop oscillations as no direct RF feedback
    - Reflection coefficient constant irrespective of the signal coming from DUT
  - Impedances set by simple electronics controlled by the X & Y inputs
    - Need high speed control electronics for relevant bandwidth modulated signals: Digital Solution Required





- Next generation ELP Systems: Digital control using FPGA

- DSP development board Stratix II edition
  - FPGA is Altera Stratix II clocked at 100 MHz
  - Two-channel, 12 bit, 125-MSPS A/D converter
  - Two-channel, 14 bit, 165-MSPS D/A converter
- The multi-tone measurement system is clocked by 10 MHz derived clocked from the FPGA master clock
- The control algorithm is implemented in time domain
- Frequency domain control will offer more functionality such as individual tone control
  - enable emulation of real world impedance matching network





- Next generation ELP Systems: Time Delay problem



- The control unit can support wideband stimulus albeit delay
- Phase variation over length of cable and components (group delay or envelope delay)
  - Must be compensated for accurate load impedance matching
- The repetitive nature of the measurement stimulus made delay compensation possible in the next repetition or N repetition later



- Next generation ELP Systems: Delay compensation determination

- Configurable FIFO RAM based unit delay
  - Unit delay is 10 ns (100 MHz clock)
  - Delay is compensated after 76 delay elements
  - Latest development of delay compensation is not limited to unit delay
- Linear group delay can be observed from the graph



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- Next generation ELP Systems: Digital control using FPGA using delay




## **RF I-V Waveform Engineering**

- Next generation ELP Systems: Two-Tone Signal with 2MHz separation

