ICAROB2016 DOIs List

ID	DOI	URL	Title
GS1-1	10.5954/ICAROB.2016.GS1-1	https://www.doi.org/10.5954/ICAROB.2016.GS1-1	Compensating Temperature-Dependent Characteristics of a Subthreshold-MOSFET Analog Silicon Neuron
GS1-2	10.5954/ICAROB.2016.GS1-2	https://www.doi.org/10.5954/ICAROB.2016.GS1-2	Medical Image Analysis of Brain X-ray CT Images By Deep GMDH-Type Neural Network
GS1-3	10.5954/ICAROB.2016.GS1-3	https://www.doi.org/10.5954/ICAROB.2016.GS1-3	Medical Image Diagnosis of Lung Cancer by Deep Feedback GMDH-Type Neural Network
GS1-4	10.5954/ICAROB.2016.GS1-4	https://www.doi.org/10.5954/ICAROB.2016.GS1-4	Feature Linking by Synchronized Response in Chaotic Cellar Neural Network for Visual Stimulus of Moving Objects
GS1-5	10.5954/ICAROB.2016.GS1-5	https://www.doi.org/10.5954/ICAROB.2016.GS1-5	An FPGA-based cortical and thalamic silicon neuronal network
GS2-1	10.5954/ICAROB.2016.GS2-1	https://www.doi.org/10.5954/ICAROB.2016.GS2-1	An accurate method for the extraction of structured light stripe
GS2-2	10.5954/ICAROB.2016.GS2-2	https://www.doi.org/10.5954/ICAROB.2016.GS2-2	Feature Acquisition From Facial Expression Image Using Convolutional Neural Networks
GS2-3	10.5954/ICAROB.2016.GS2-3	https://www.doi.org/10.5954/ICAROB.2016.GS2-3	Estimating Age on Twitter Using Self-Training Semi-Supervised SVM
GS2-4	10.5954/ICAROB.2016.GS2-4	https://www.doi.org/10.5954/ICAROB.2016.GS2-4	Interactive Musical Editing System to Support Human Errors and Offer Personal Preference for an Automatic Piano
GS2-5	10.5954/ICAROB.2016.GS2-5	https://www.doi.org/10.5954/ICAROB.2016.GS2-5	Geometric parameters measurement of wheel tread based on line structured light
GS2-6	10.5954/ICAROB.2016.GS2-6	https://www.doi.org/10.5954/ICAROB.2016.GS2-6	Study on the ORB algorithm in the application of Monocular SLAM
GS3-1	10.5954/ICAROB.2016.GS3-1	https://www.doi.org/10.5954/ICAROB.2016.GS3-1	Examination of Robotic Aerospace Engines Maintenance Supported by Augmented Reality through Cloud Manufacturing
GS3-2	10.5954/ICAROB.2016.GS3-2	https://www.doi.org/10.5954/ICAROB.2016.GS3-2	Unit Layout Design Supporting System of Cell Assembly Machine Using Two Robots by Reinforcement Learning
GS3-3	10.5954/ICAROB.2016.GS3-3	https://www.doi.org/10.5954/ICAROB.2016.GS3-3	Virtual Input Parts Decision System of Job-Shop Production Line by using GA with ON / OFF Gene
GS3-4	10.5954/ICAROB.2016.GS3-4	https://www.doi.org/10.5954/ICAROB.2016.GS3-4	An Evolutionary Algorithm for Making Decision Graphs for Classification Problems
GS3-5	10.5954/ICAROB.2016.GS3-5	https://www.doi.org/10.5954/ICAROB.2016.GS3-5	Improvement of Computational Efficiency of UPF by Automatic Adjustment of the Number of Particles
GS3-6	10.5954/ICAROB.2016.GS3-6	https://www.doi.org/10.5954/ICAROB.2016.GS3-6	Multi Objective Evolutionary Algorithms for Association Rule Mining: Advances and Challenges
GS4-1	10.5954/ICAROB.2016.GS4-1	https://www.doi.org/10.5954/ICAROB.2016.GS4-1	Applying Fuzzy Sliding Mode Control on Electrowetting on Dielectric System
GS4-2	10.5954/ICAROB.2016.GS4-2	https://www.doi.org/10.5954/ICAROB.2016.GS4-2	Development of Micro-Permanent Magnet Synchronous Reluctance Generator for TPMS on Smart Robots
GS4-3	10.5954/ICAROB.2016.GS4-3	https://www.doi.org/10.5954/ICAROB.2016.GS4-3	Study of Micro-Flux-Switching Permanent-Magnet Generator for TPMS on Smart Robots
GS4-4	10.5954/ICAROB.2016.GS4-4	https://www.doi.org/10.5954/ICAROB.2016.GS4-4	MEMS Microrobot Controlled by Mounted Neural Networks IC with Two Types Actuators
GS5-1	10.5954/ICAROB.2016.GS5-1	https://www.doi.org/10.5954/ICAROB.2016.GS5-1	Moving Robots Lies and Their Minds with Degree of Confidence in a Decentralized Autonomous FMS
GS5-2	10.5954/ICAROB.2016.GS5-2	https://www.doi.org/10.5954/ICAROB.2016.GS5-2	Conquest Oriented Robot Knowing Its Own Availability
GS6-1	10.5954/ICAROB.2016.GS6-1	https://www.doi.org/10.5954/ICAROB.2016.GS6-1	A Consideration on Feature Extraction for Operation Skill Based on Control Engineering Approach
GS6-2	10.5954/ICAROB.2016.GS6-2	https://www.doi.org/10.5954/ICAROB.2016.GS6-2	Design of a Data-Driven Control System for a Hydraulic Excavator
GS6-3	10.5954/ICAROB.2016.GS6-3	https://www.doi.org/10.5954/ICAROB.2016.GS6-3	An Optimization of Spatio-Spectral Filter Bank Design for EEG Classification
GS7-1	10.5954/ICAROB.2016.GS7-1	https://www.doi.org/10.5954/ICAROB.2016.GS7-1	Haptic system with fuzzy controller for extended control of Teleoperation mine detector wheeled robots
GS7-2	10.5954/ICAROB.2016.GS7-2	https://www.doi.org/10.5954/ICAROB.2016.GS7-2	Effects of System Parameters and Controlled Torque on The Dynamics of Rigid-Flexible Robotic Manipulator
GS7-3	10.5954/ICAROB.2016.GS7-3	https://www.doi.org/10.5954/ICAROB.2016.GS7-3	Modeling of Mobile Manipulator and Adaptive Super-Twisting Backstepping Control
GS7-4	10.5954/ICAROB.2016.GS7-4	https://www.doi.org/10.5954/ICAROB.2016.GS7-4	Self-tuned Local Feedback Gain Based Decentralized Fault Tolerant Control of Reconfigurable Manipulators
GS7-5	10.5954/ICAROB.2016.GS7-5	https://www.doi.org/10.5954/ICAROB.2016.GS7-5	Study on Decentralized Integral Nested Sliding Mode Control for Constrained Reconfigurable Manipulator with Harmonic Drive Transmission
GS7-6	10.5954/ICAROB.2016.GS7-6	https://www.doi.org/10.5954/ICAROB.2016.GS7-6	A Number of Mobile Manipulator Control for Moving an Object by using Cooperative Control
GS8-1	10.5954/ICAROB.2016.GS8-1	https://www.doi.org/10.5954/ICAROB.2016.GS8-1	Visual-servo Control of 4-DOF Robot Manipulator for Sorting Moving objects
GS8-2	10.5954/ICAROB.2016.GS8-2	https://www.doi.org/10.5954/ICAROB.2016.GS8-2	Self-identification of Mental State and Self-control through Indirect Biofeedback --- Indirect Representation and Placebo Effect ---
GS8-3	10.5954/ICAROB.2016.GS8-3	https://www.doi.org/10.5954/ICAROB.2016.GS8-3	Construction of a micro sense of force feedback and vision for micro-objects: development of a haptic device
GS8-4	10.5954/ICAROB.2016.GS8-4	https://www.doi.org/10.5954/ICAROB.2016.GS8-4	Dynamic Behavior Selection Model based on Emotional States for Conbe-I robot
GS8-5	10.5954/ICAROB.2016.GS8-5	https://www.doi.org/10.5954/ICAROB.2016.GS8-5	Consideration on a Crawler Robot with Six Legs
GS9-1	10.5954/ICAROB.2016.GS9-1	https://www.doi.org/10.5954/ICAROB.2016.GS9-1	Social Expression of Pet Robot Based on Artificial Consciousness and Biologically Inspired On-line Topological Method
GS9-2	10.5954/ICAROB.2016.GS9-2	https://www.doi.org/10.5954/ICAROB.2016.GS9-2	Anthropomorphic robot modelling with virtual height inverted pendulum approach in Simulink: step length and robot height influence on walking stability.
GS9-3	10.5954/ICAROB.2016.GS9-3	https://www.doi.org/10.5954/ICAROB.2016.GS9-3	A low cost genetic algorithm based control scheme for wheelchair control in hospital environment
GS9-4	10.5954/ICAROB.2016.GS9-4	https://www.doi.org/10.5954/ICAROB.2016.GS9-4	Simultaneous Localization and Mapping (SLAM) algorithm base on EKF and SPKF.
GS10-1	10.5954/ICAROB.2016.GS10-1	https://www.doi.org/10.5954/ICAROB.2016.GS10-1	Analyses of Postgraduates' Entrance Examination Scores Based on Linear Regression with Dummy Variables

GS10-2	10.5954/ICAROB.2016.GS10-2	https://www.doi.org/10.5954/ICAROB.2016.GS10-2	Clinical Evaluation of UR-System 2 for Recovery of Motor Function of Plegic Upper Limb after Stroke
GS10-3	10.5954/ICAROB.2016.GS10-3	https://www.doi.org/10.5954/ICAROB.2016.GS10-3	Knee Android Model Reproducing Internal-External Rotation with Screw-Home Movement of Human Knee
GS10-4	10.5954/ICAROB.2016.GS10-4	https://www.doi.org/10.5954/ICAROB.2016.GS10-4	Wood Species Recognition System based on Improved Basic Grey Level Aura Matrix as feature extractor
GS10-5	10.5954/ICAROB.2016.GS10-5	https://www.doi.org/10.5954/ICAROB.2016.GS10-5	Evaluation the Performance of a New Quadrotor Model Based on the Arm's Length Variation
IS1	10.5954/ICAROB.2016.IS1	https://www.doi.org/10.5954/ICAROB.2016.IS1	Redefining robot based technologies for elderly people assistance: a survey
IS2	10.5954/ICAROB.2016.IS2	https://www.doi.org/10.5954/ICAROB.2016.IS2	Affective Human Computer Interaction
OS1-1	10.5954/ICAROB.2016.OS1-1	https://www.doi.org/10.5954/ICAROB.2016.OS1-1	The development of new products of pineapple cheesecakes
OS1-2	10.5954/ICAROB.2016.OS1-2	https://www.doi.org/10.5954/ICAROB.2016.OS1-2	The Study on Ballroom Service Quality to Affect Customer Satisfaction
OS1-3	10.5954/ICAROB.2016.OS1-3	https://www.doi.org/10.5954/ICAROB.2016.OS1-3	The Relationship between Employees' Personality Traits, Work Values and Job Involvement with the Contribution to their Companies - For the Micro Food Service Industry
OS1-4	10.5954/ICAROB.2016.OS1-4	https://www.doi.org/10.5954/ICAROB.2016.OS1-4	Consumer's Acceptance to The New Product- Pineapple Jam as Example
OS1-5	10.5954/ICAROB.2016.OS1-5	https://www.doi.org/10.5954/ICAROB.2016.OS1-5	Development of An Innovative Design Process for Green Products
OS1-6	10.5954/ICAROB.2016.OS1-6	https://www.doi.org/10.5954/ICAROB.2016.OS1-6	Research on Nail Art 3D Design with Different Materials -- A Case Study of the Tang Dynasty Style
OS2-1	10.5954/ICAROB.2016.OS2-1	https://www.doi.org/10.5954/ICAROB.2016.OS2-1	Modified Quantum Particle Swarm Optimization for Chaos Synchronization
OS2-2	10.5954/ICAROB.2016.OS2-2	https://www.doi.org/10.5954/ICAROB.2016.OS2-2	A Simulation Model of Hall Sensor Misalignment in BLDC Motors
OS2-3	10.5954/ICAROB.2016.OS2-3	https://www.doi.org/10.5954/ICAROB.2016.OS2-3	Using Multi-Target Tracking and Identification TLD Algorithm for Intelligent Mobile Robot
OS2-4	10.5954/ICAROB.2016.OS2-4	https://www.doi.org/10.5954/ICAROB.2016.OS2-4	Handheld Mobile Devices for Remote Monitoring of Factory
OS2-5	10.5954/ICAROB.2016.OS2-5	https://www.doi.org/10.5954/ICAROB.2016.OS2-5	Task Assignment and Route Programming for Pattern Reformation on Grid Plane
OS2-6	10.5954/ICAROB.2016.OS2-6	https://www.doi.org/10.5954/ICAROB.2016.OS2-6	The Design of a Multifunctional Acousto-Optic Device with a Mobile Power Pack
OS3-1	10.5954/ICAROB.2016.OS3-1	https://www.doi.org/10.5954/ICAROB.2016.OS3-1	Discussion on Factors Influencing the Performance of Hospital Renovation Engineering Taking one Medical Center in Taiwan as Example
OS3-2	10.5954/ICAROB.2016.OS3-2	https://www.doi.org/10.5954/ICAROB.2016.OS3-2	Discussion on Land Expropriation Compensation System
OS3-3	10.5954/ICAROB.2016.OS3-3	https://www.doi.org/10.5954/ICAROB.2016.OS3-3	Study on User Satisfaction of Pick Areas for Elementary Schools - Using Nanyang Elementary School in Taichung City as Example
OS3-4	10.5954/ICAROB.2016.OS3-4	https://www.doi.org/10.5954/ICAROB.2016.OS3-4	Study on User Satisfaction in Sport Site Facilities for Senior Students of Elementary Schools in Taichung City
OS3-5	10.5954/ICAROB.2016.OS3-5	https://www.doi.org/10.5954/ICAROB.2016.OS3-5	The Establishment of the Sustainability Performance Indicators for Wetland Ecological Project: Using Construction Inspection Phase as Example
OS3-6	10.5954/ICAROB.2016.OS3-6	https://www.doi.org/10.5954/ICAROB.2016.OS3-6	Development of Type Control Guidelines for the Old Town District of Hsinchu City
OS4-1	10.5954/ICAROB.2016.OS4-1	https://www.doi.org/10.5954/ICAROB.2016.OS4-1	Study on the Promotion of Steel Slags Recycling in Taiwan
OS4-2	10.5954/ICAROB.2016.OS4-2	https://www.doi.org/10.5954/ICAROB.2016.OS4-2	The Research on the Utilization of Green Building Ecological Index Group in Campus Environment - Taking of Elementary Schools at Houli District, Taichung City as Example
OS4-3	10.5954/ICAROB.2016.OS4-3	https://www.doi.org/10.5954/ICAROB.2016.OS4-3	The Assessment and Research on the Reconstruction of Enclosing Wall into Open Type in Elementary School Campus - Taking of Erlin Township, Changhua County as Example
OS4-4	10.5954/ICAROB.2016.OS4-4	https://www.doi.org/10.5954/ICAROB.2016.OS4-4	The Study and Analysis on the Reuse and Transformation Strategy of Tile Kiln Space - Taking of San-He Tile Kiln as Example
OS4-5	10.5954/ICAROB.2016.OS4-5	https://www.doi.org/10.5954/ICAROB.2016.OS4-5	The Research on the Influence of Economic Benefit for High-Rise Buildings Constructed by Different Excavation Method - Taking of Residence Buildings at New Taipei City as Example
OS5-1	10.5954/ICAROB.2016.OS5-1	https://www.doi.org/10.5954/ICAROB.2016.OS5-1	Socialized Multi-Agent System Rendezvous via Networks of Networks
OS5-2	10.5954/ICAROB.2016.OS5-2	https://www.doi.org/10.5954/ICAROB.2016.OS5-2	Global sensor selection for maneuvering target tracking in clutter
OS5-3	10.5954/ICAROB.2016.OS5-3	https://www.doi.org/10.5954/ICAROB.2016.OS5-3	Attitude/Position Estimation of Rigid-Body using Inertial and Vision Sensors
OS5-4	10.5954/ICAROB.2016.OS5-4	https://www.doi.org/10.5954/ICAROB.2016.OS5-4	Modeling and Control of a Suspended Gravity Compensation System with Rigid-Flexible Coupling
OS5-5	10.5954/ICAROB.2016.OS5-5	https://www.doi.org/10.5954/ICAROB.2016.OS5-5	Trajectory Tracking Control for Omnidirectional Mobile Robots with Input Constraints
OS5-6	10.5954/ICAROB.2016.OS5-6	https://www.doi.org/10.5954/ICAROB.2016.OS5-6	Parameters tuning approach for prescribed performance function based active disturbance rejection control
OS6-1	10.5954/ICAROB.2016.OS6-1	https://www.doi.org/10.5954/ICAROB.2016.OS6-1	Adaptive Control of Discrete-Time Systems Using Multiple Fixed and One Adaptive Identification Models
OS6-2	10.5954/ICAROB.2016.OS6-2	https://www.doi.org/10.5954/ICAROB.2016.OS6-2	Adaptive Polynomial Regression and Its Application to Gene Selection of Rat Liver Regeneration
OS6-3	10.5954/ICAROB.2016.OS6-3	https://www.doi.org/10.5954/ICAROB.2016.OS6-3	Adaptive Consensus via Dynamic Feedback Control for Lipschitz Nonlinear Multi-Agent Systems
OS6-4	10.5954/ICAROB.2016.OS6-4	https://www.doi.org/10.5954/ICAROB.2016.OS6-4	Iterative Learning Based Thrust Ripple Suppression for PMLSM
OS6-5	10.5954/ICAROB.2016.OS6-5	https://www.doi.org/10.5954/ICAROB.2016.OS6-5	Adaptive Sliding Mode Control for A 2 DOF Magnetic Levitation System with Uncertain Parameters
OS6-6	10.5954/ICAROB.2016.OS6-6	https://www.doi.org/10.5954/ICAROB.2016.OS6-6	Undershoot Reduction in Discrete-Time ADRC of NMP Plant by Parameters Optimization
OS7-1	10.5954/ICAROB.2016.OS7-1	https://www.doi.org/10.5954/ICAROB.2016.OS7-1	A Method for Secure Communication Using a Discrete Wavelet Transform for Sound Data
OS7-2	10.5954/ICAROB.2016.OS7-2	https://www.doi.org/10.5954/ICAROB.2016.OS7-2	An Authentication Method Using a Discrete Wavelet Transform for a Recaptured Video
OS7-3	10.5954/ICAROB.2016.OS7-3	https://www.doi.org/10.5954/ICAROB.2016.OS7-3	A System for Facial Expression Analysis of a Person While Using Video Phone
OS7-4	10.5954/ICAROB.2016.OS7-4	https://www.doi.org/10.5954/ICAROB.2016.OS7-4	Emotion Recognition of a Speaker Using Facial Expression Intensity of Thermal Image and Utterance Time

OS7-5	10.5954/ICAROB.2016.OS7-5	https://www.doi.org/10.5954/ICAROB.2016.OS7-5	Estimation of Learners' Subjective Difficulty in e-Learning Using Thermal Image Processing
OS8-1	10.5954/ICAROB.2016.OS8-1	https://www.doi.org/10.5954/ICAROB.2016.OS8-1	Image Encryption Implementation Based on Fractional-order Chen System
OS8-2	10.5954/ICAROB.2016.OS8-2	https://www.doi.org/10.5954/ICAROB.2016.OS8-2	Mobile Camera based Motion Segmentation by Image Resizing
OS8-3	10.5954/ICAROB.2016.OS8-3	https://www.doi.org/10.5954/ICAROB.2016.OS8-3	Synchronization of the Fractional-order Permanent Magnet Synchronous Motor
OS8-4	10.5954/ICAROB.2016.OS8-4	https://www.doi.org/10.5954/ICAROB.2016.OS8-4	Analog Circuit Implementation and Full State Observation of Chua's Circuit
OS8-5	10.5954/ICAROB.2016.OS8-5	https://www.doi.org/10.5954/ICAROB.2016.OS8-5	Research on Visualized Rescue Robot
OS8-6	10.5954/ICAROB.2016.OS8-6	https://www.doi.org/10.5954/ICAROB.2016.OS8-6	Development of Training Instrument for Upper Limb Muscle Rehabilitation
OS8-7	10.5954/ICAROB.2016.OS8-7	https://www.doi.org/10.5954/ICAROB.2016.OS8-7	Design and Analog Circuit Implementation of a Dynamic Feedback Control System Based on RLC Series Circuit
OS8-8	10.5954/ICAROB.2016.OS8-8	https://www.doi.org/10.5954/ICAROB.2016.OS8-8	Simulation Study on the Tracking Technology of the Maximal Power Point of the Solar Photovoltaic Based on the Model Predictive Control
OS8-9	10.5954/ICAROB.2016.OS8-9	https://www.doi.org/10.5954/ICAROB.2016.OS8-9	Analysis and unidirectionally coupled synchronization of a novel chaotic system
OS9-1	10.5954/ICAROB.2016.OS9-1	https://www.doi.org/10.5954/ICAROB.2016.OS9-1	A Study on the Structural Hole of Patent Applicant Network in R&D Management
OS9-2	10.5954/ICAROB.2016.OS9-2	https://www.doi.org/10.5954/ICAROB.2016.OS9-2	The TCE-RBV Framework for Information Systems Outsourcing: Empirical Testing using Survey Data in Japan
OS9-3	10.5954/ICAROB.2016.OS9-3	https://www.doi.org/10.5954/ICAROB.2016.OS9-3	Momentum and Its Implications in Corporate Management
OS10-1	10.5954/ICAROB.2016.OS10-1	https://www.doi.org/10.5954/ICAROB.2016.OS10-1	Fast collective photographic subject detection without pixels by an assumption about a shoot and its elevation angle
OS10-2	10.5954/ICAROB.2016.OS10-2	https://www.doi.org/10.5954/ICAROB.2016.OS10-2	Evaluation of a safety map generated from a collection of difference of Individuals
OS10-3	10.5954/ICAROB.2016.OS10-3	https://www.doi.org/10.5954/ICAROB.2016.OS10-3	Endeavor to adopt GIS data on evacuation decision making model
OS11-1	10.5954/ICAROB.2016.OS11-1	https://www.doi.org/10.5954/ICAROB.2016.OS11-1	Automated Multiple-Brightness Peak Image Processing Method Using Curvature and Variance Estimation
OS11-2	10.5954/ICAROB.2016.OS11-2	https://www.doi.org/10.5954/ICAROB.2016.OS11-2	Histogram Matching Based on Gaussian Distribution on the HSB Color System
OS11-3	10.5954/ICAROB.2016.OS11-3	https://www.doi.org/10.5954/ICAROB.2016.OS11-3	Quantitative Evaluation of Flash-based Educational Visualizing Simulator
OS11-4	10.5954/ICAROB.2016.OS11-4	https://www.doi.org/10.5954/ICAROB.2016.OS11-4	Relation between Optimal Stopping Solution and NSPR for Structural Change Point Detection Problem
OS12-1	10.5954/ICAROB.2016.OS12-1	https://www.doi.org/10.5954/ICAROB.2016.OS12-1	Development of a Tool to Keep Consistency between a Model and a Source Code in Software Development Using MDA.
OS12-2	10.5954/ICAROB.2016.OS12-2	https://www.doi.org/10.5954/ICAROB.2016.OS12-2	Necessary spaces for seven-way four-dimensional Turing machines to simulate four-dimensional one-marker automata
OS12-3	10.5954/ICAROB.2016.OS12-3	https://www.doi.org/10.5954/ICAROB.2016.OS12-3	Analysis for $4\bar{7} \cdot 2$ board of Othello
OS12-4	10.5954/ICAROB.2016.OS12-4	https://www.doi.org/10.5954/ICAROB.2016.OS12-4	A space lower-bound technique for four-dimensional alternating Turing machines
OS13-1	10.5954/ICAROB.2016.OS13-1	https://www.doi.org/10.5954/ICAROB.2016.OS13-1	Automatic Generation, Creativity, and Production of Narrative Contents
OS13-2	10.5954/ICAROB.2016.OS13-2	https://www.doi.org/10.5954/ICAROB.2016.OS13-2	A Design Plan of a Game System including an Automatic Narrative Generation Mechanism: The Entire Structure and the World Settings
OS13-3	10.5954/ICAROB.2016.OS13-3	https://www.doi.org/10.5954/ICAROB.2016.OS13-3	A Way for using the Verb Conceptual Dictionary in an Integrated Narrative Generation System: the Use of Co-occurrence Information on Verb Concepts
OS13-4	10.5954/ICAROB.2016.OS13-4	https://www.doi.org/10.5954/ICAROB.2016.OS13-4	A Viewing Experiment on the Effects of Advertising Story
PS1	10.5954/ICAROB.2016.PS1	https://www.doi.org/10.5954/ICAROB.2016.PS1	Disrupting the Industry with Play
PS2	10.5954/ICAROB.2016.PS2	https://www.doi.org/10.5954/ICAROB.2016.PS2	A Study on Differential Evolution Using BetaCOBL, B3R, and TPBO