

Technological Breakthroughs in Grid Revitalization

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The Evolving Landscape of Power Systems

PES - Emerging Technology - July 2008

System Integrity Protection Schemes - SIPS

CIGRE/IEEE definition of SPS
IEEE Power System Relaying Committee
Definition of SIPS
Local, or Wide Area, or combination

NERC/WECC
SPS/RAS

Safety Nets

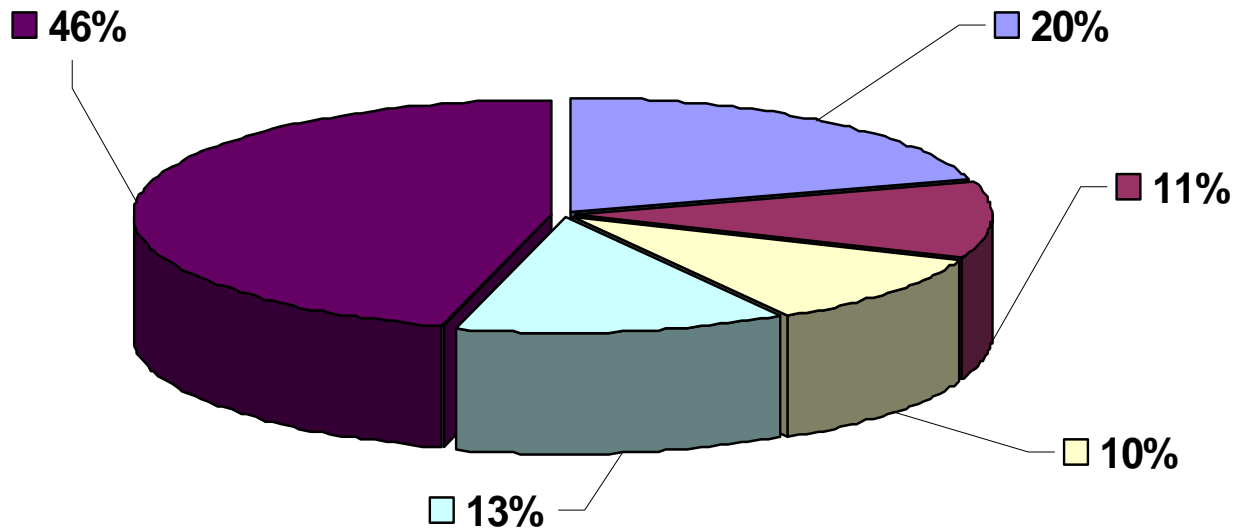


Application Naming

Source: IEEE PSRC WG C-4
Global Industry Experiences with
System Integrity Protection Schemes

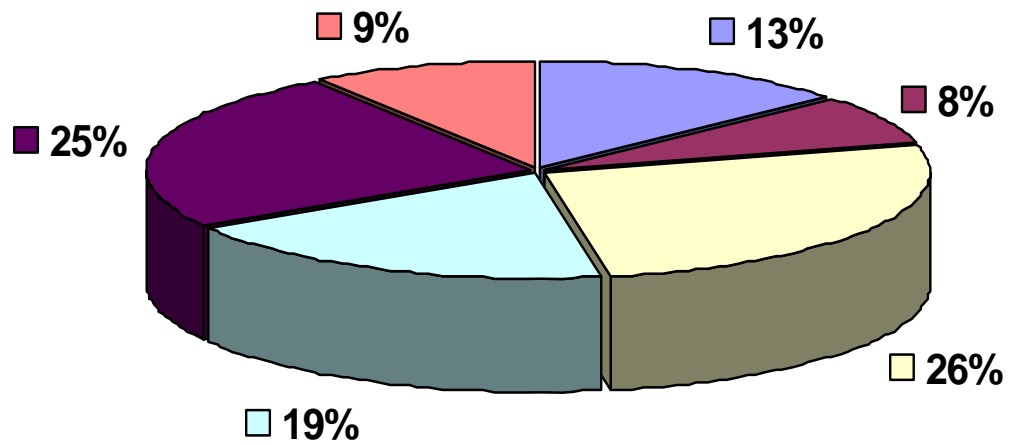
- Generator Rejection
- Load Rejection
- Under-Frequency Load Shedding
- Under-Voltage Load Shedding
- Adaptive Load Mitigation
- Out-of-Step Tripping
- Voltage Instability Advance Warning Scheme
- Angular Stability Advance Warning Scheme
- Overload Mitigation
- Congestion Mitigation
- System Separation
- Shunt Capacitor Switching
- Tap-Changer Control
- SVC/STATCOM Control
- Turbine Valve Control
- HVDC Controls
- Power System Stabilizer Control
- Discrete Excitation
- Dynamic Breaking
- Generator Runback
- Bypassing Series Capacitor
- Black-Start or Gas-Turbine Start-Up
- AGC Actions
- Busbar Splitting

Pie Charts: Classification (422 Entries)



- i. Essential
- ii. Increased Security
- iii. Increased Power Flow Capability
- iv. Important
- v. Normal

Pie Chart: To provide protective actions against (53 Entries)

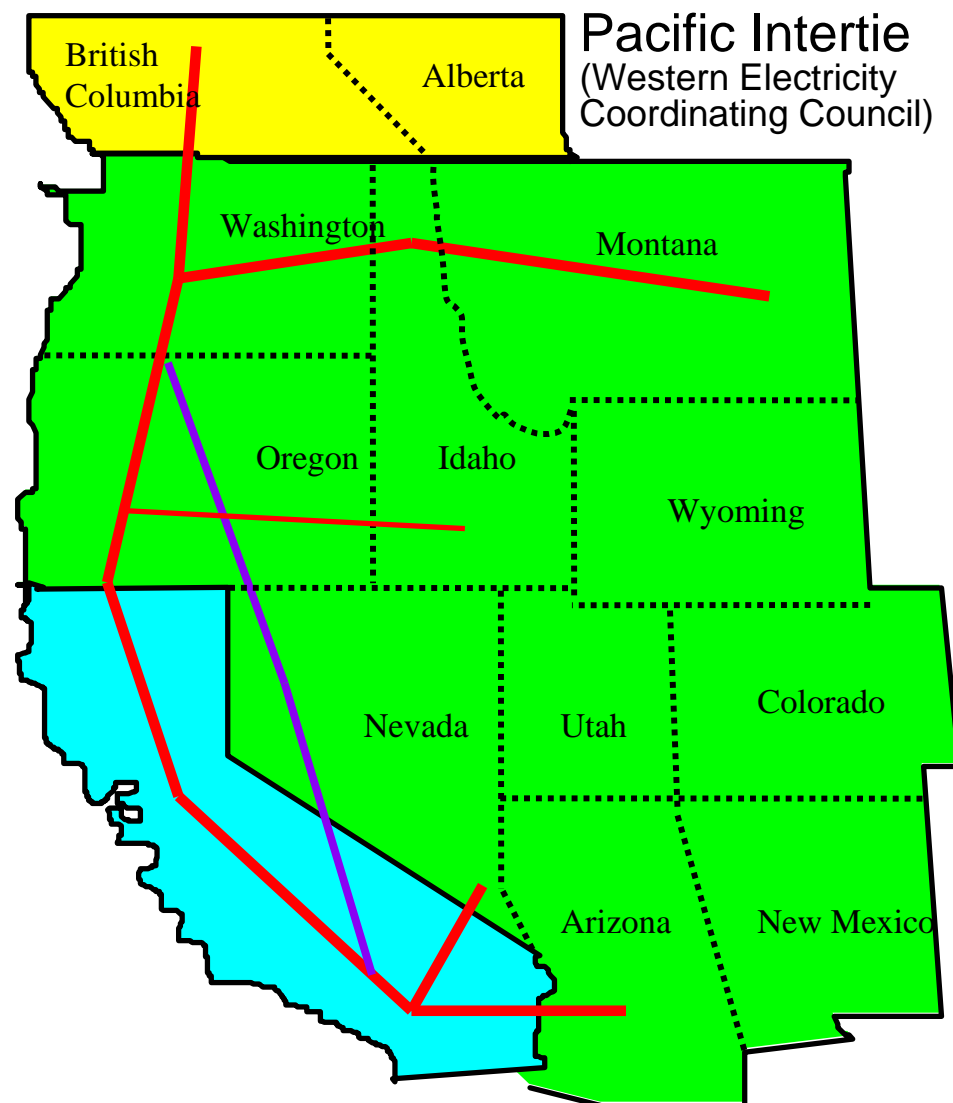


- i. Congestion
- ii. Small-Disturbance Angle Instability
- iii. Transient Instability
- iv. Frequency Instability
- v. Voltage Instability
- vi. Thermal Overloading



RAS or SIPS

- ❑ System to protect integrity of power system over a wide area
- ❑ Applied to protect system stability, maintain overall system connectivity, and/or to avoid damage to equipments during major system events
- ❑ System may require multiple detection and actuation devices, and communication facilities
- ❑ Logic, design and actions are driven by the system purpose
- ❑ Advanced schemes involve hierarchical architecture with several steps

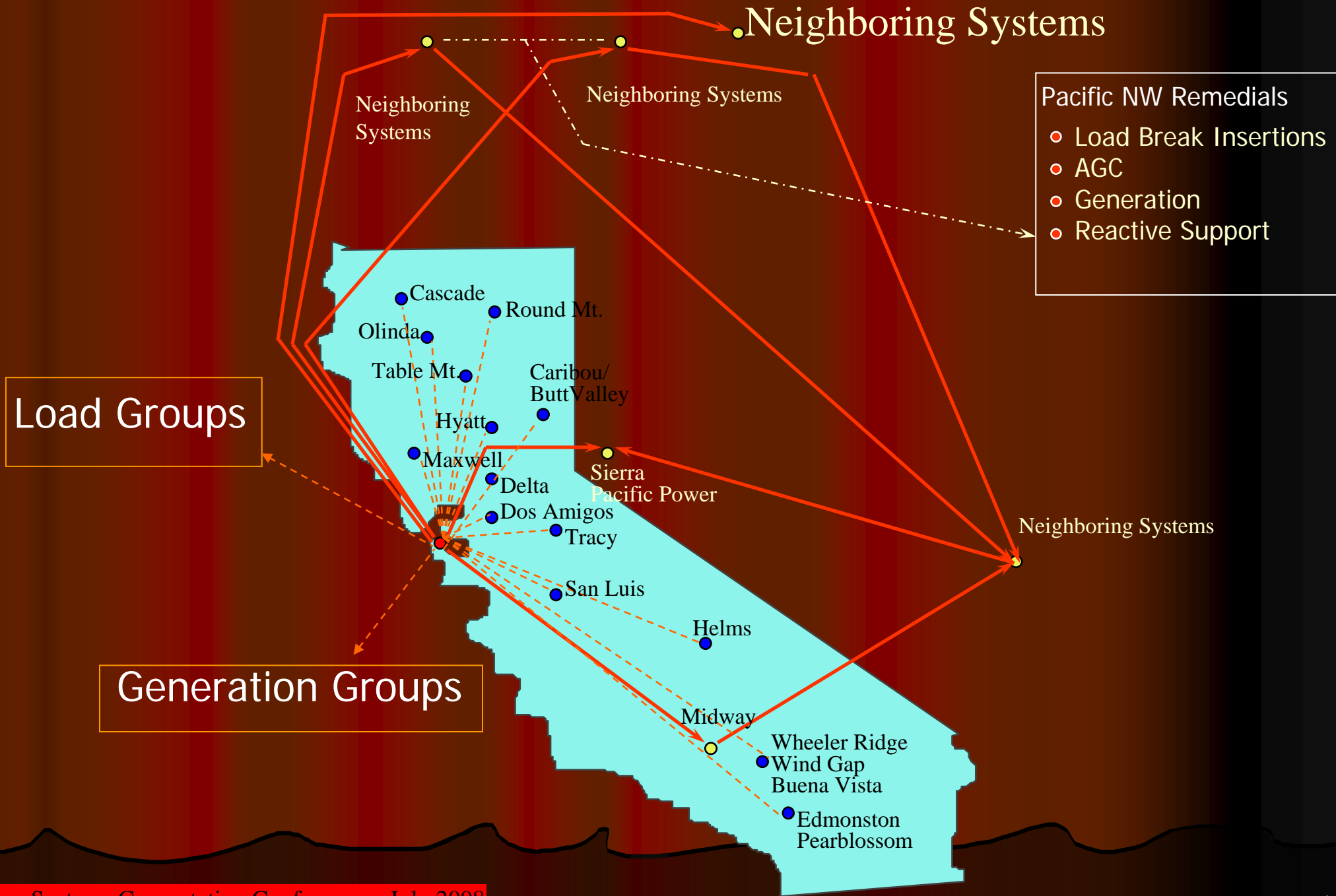


Pacific Intertie
(Western Electricity
Coordinating Council)

— PDCI – DC Link, 1000kV

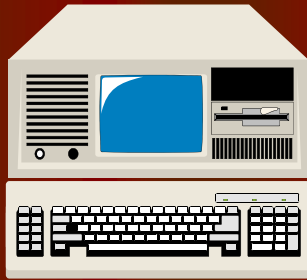
— PACI – AC Corridor, 500kV

Large Scale Coordinated SIPS

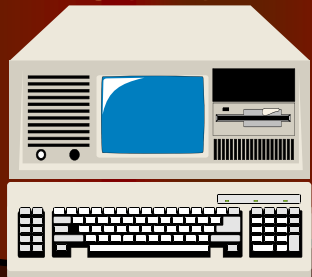


Multiple RAS Control Centers

Existing
Control
Center

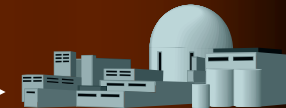


New
Control
Center



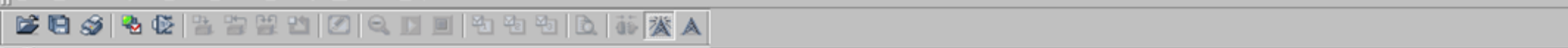
Field Devices -
Keep the existing
or change to new??

Existing Comms links



New Comms links





Voltage (Field Device, Phase Values Set Unbalance for Demo)

PARAMETER	SOURCE 1
Name	SRC 1
PHASORS	View
RMS Vag	49.976 V
RMS Vbg	31.244 V
RMS Vcg	19.971 V
Phasor Vag	40.998 V 0.0 deg
Phasor Vbg	19.966 V 0.0 deg
Phasor Vcg	29.983 V -359.9 deg

F1 Actual Values: Metering: Source Screen ID: 107

Current (Field Device, Phase Values Set Unbalance for Demo)

PARAMETER	SOURCE 1
Name	SRC 1
PHASORS	View
RMS Ia	1.096 A
RMS Ib	2.095 A
RMS Ic	3.092 A
RMS In	4.091 A
Phasor Ia	1.096 A -359.4 deg
Phasor Ib	2.094 A -179.1 deg
Phasor Ic	3.092 A -179.4 deg

F1 Actual Values: Metering: Source Screen ID: 106

DC (milliamp) Transducer Values Set Uneven for Demo)

PARAMETER	VALUE
IEC61850 GOOSE Analog Input 1 Actual	0.521
IEC61850 GOOSE Analog Input 2 Actual	5.170
IEC61850 GOOSE Analog Input 3 Actual	53.813
IEC61850 GOOSE Analog Input 4 Actual	542.250
IEC61850 GOOSE Analog Input 5 Actual	0.000
IEC61850 GOOSE Analog Input 6 Actual	0.000
IEC61850 GOOSE Analog Input 7 Actual	0.000

F1 Actual Values: Metering Screen ID: 93

Direct Inputs // PACI: AC-31: ...

Parameter	Value
Msg Return Time 1	31 ms
Unreturned Msg Count 1	0
CRC Fail Count 1	0
Msg Return Time 2	31 ms
Unreturned Msg Count 2	0
CRC Fail Count 2	1
DI 1	Off
DI 2	Off
DI 3	Off
DI 4	On

F1 Actual Values: Status Screen ID: ...

Cross Over Enabled - Message is Looped

Parameter	Value
Msg Return Time 1	62 ms
Unreturned Msg Count 1	0
CRC Fail Count 1	0
Msg Return Time 2	10000 ms
Unreturned Msg Count 2	0
CRC Fail Count 2	3142
DI 1	On

C1 Actual Values: Status Screen ID: ...

Cross Over Enabled - Message is Looped

Parameter	Value
Msg Return Time 1	62 ms
Unreturned Msg Count 1	0
CRC Fail Count 1	0
Msg Return Time 2	10000 ms
Unreturned Msg Count 2	0
CRC Fail Count 2	141
DI 1	On

C2 Actual Values: Status Screen ID: ...

Direct Analog Inputs // PACI: RAS-A33: ...

PARAMETER	VALUE
Direct Analog Input 1 Actual	49.979 Vag
Direct Analog Input 2 Actual	31.245 Vbg
Direct Analog Input 3 Actual	19.977 Vcg
Direct Analog Input 4 Actual	1.096 Ia
Direct Analog Input 5 Actual	2.095 Ib
Direct Analog Input 6 Actual	3.092 Ic
Direct Analog Input 7 Actual	0.521 degC
Direct Analog Input 8 Actual	5.170 ma
Direct Analog Input 9 Actual	53.813 kv
Direct Analog Input 10 Actual	542.250 A

C1 Actual Values: Metering Screen ID: 85

Direct Analog Inputs // PACI: RAS-C34: ...

PARAMETER	VALUE
Direct Analog Input 1 Actual	49.976 Vag
Direct Analog Input 2 Actual	31.243 Vbg
Direct Analog Input 3 Actual	19.973 Vag
Direct Analog Input 4 Actual	1.096 Ia
Direct Analog Input 5 Actual	2.095 Ib
Direct Analog Input 6 Actual	3.092 Ic
Direct Analog Input 7 Actual	0.521 degC
Direct Analog Input 8 Actual	5.170 mA
Direct Analog Input 9 Actual	53.813 KV
Direct Analog Input 10 Actual	542.250 A

C2 Actual Values: Metering Screen ID: 85

IEEE C37.94 @128kbps
 Throughput Time - 16 milliseconds (one way)
 Transmission System stretch ~ 250 miles (~ 400 kilometer)



Throughput Timing – 128kbps

(Excludes Controller Time ~ 10-12 msec)

- ❑ Distributed Intelligence and Central Processing
- ❑ Very inefficient to transport all of the raw data only to combine the various values after the data arrives at the control center
- ❑ Amount of raw data can overwhelm the bandwidth
- ❑ Methods to reduce the amount of raw data by pre-processing it prior to transmission
- ❑ If the mathematical combination and simplification can be done at remote sites, the required communication bandwidth is reduced
- ❑ Local subsystems be designed for station-to station communication
 - ❖ For local coordination
- ❑ Total measured time Device to Device - 16 milliseconds for one way, 250 miles (~ 425 km)
- ❑ Field Device (3 milliseconds)
- ❑ Central Controller Device (3 msec)
- ❑ Channel bank field, 1.5 msec
- ❑ Channel bank central device, 1.5 msec
- ❑ Propagation Time = $[16 - (3+3+1.5+1.5)] \sim 7$ msec for 250 miles
- ❑ For 500 miles (~850km), it is safe to say < 14 msec



Thank You



Participate:

- NASPI - North American Synchronized phasor initiative Performance Standards Task Team (PSTT)
- IEEE Power System Relaying Committee (PSRC) - Survey WG C-4 (Global Industry Experiences with SIPS)

