NOVEL SWITCHED CAPACITOR-FILTER COMPENSATOR FOR SMART GRID-ELECTRIC VEHICLE CHARGING SCHEME

Professor Adel M. Sharaf

Why EV/Hybrid EV

- Rising Cost / depleting Resources of fossil fuels
- Unreliable / Unproven reserves
- Climate change/Global warming and CO2 Emissions
- Need to incorporate green Energy/Energy Efficiency and Renewable Energy in the Energy Mix Scenario
- Hybrid Fast Charging Regimes
- Low impact on the Host Electrical Grid
- Improved Utilization

What is the Solution?

 EV and Hybrid Plug-in EV and Ultimately Electric Vehicle (EV)

Why?

- Low Pollution /Smog and GHG& Clean Environment
- Charged by Sustainable/Green/Renewable Sources(FC,PV, Wind,....)
- Carbon Foot Print/Less Global Warming
- Cheaper Running Cost/KWh Charges

What Challenges?

- Low Impact/Improved Decoupling/Fast Battery Charging
 Scheme
- Minimal Impact in terms of Power quality and Improved Power Factor
- Efficient Energy Utilization and effective Interface of Smart
 Grid with Renewable hybrid Green Energy Sources
- Improved Less transient and Inrush Current Conditions
- Hybrid Secure and Diverse Utilization of RE/Green
 Sustainable Sources including Hydrogen

Novel FACTS Schemes

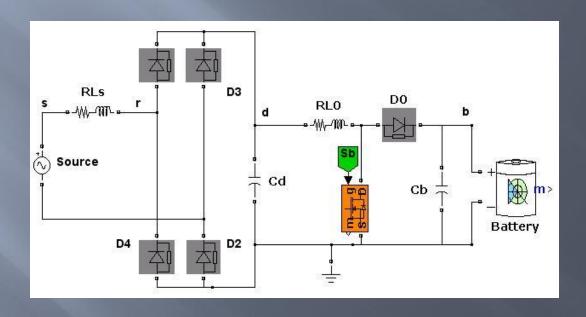
>On AC Side:

- Switched Capacitor-Filter Compensator (HSCFC)
- New Switching Controller for Improved AC-DC Coupling and Enhanced PQ/PF Operation

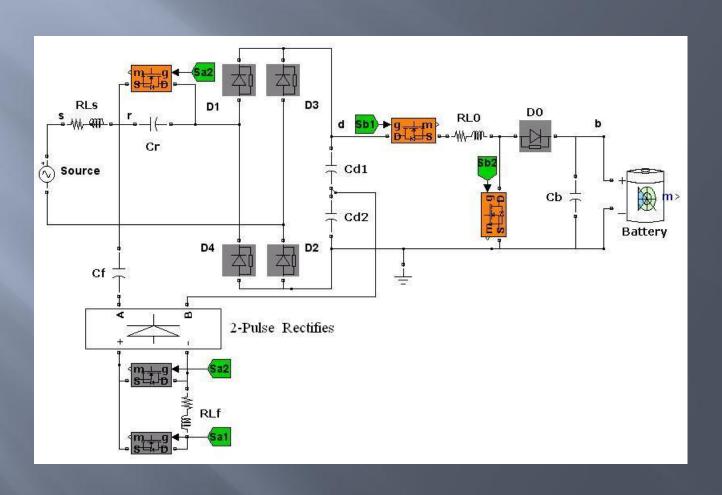
>DC Side:

 New Multi Model V_I_P Charging Regime with Weighted Switching Controller for DC-DC Chopper

Basic Smart Grid-Battery Charging Scheme

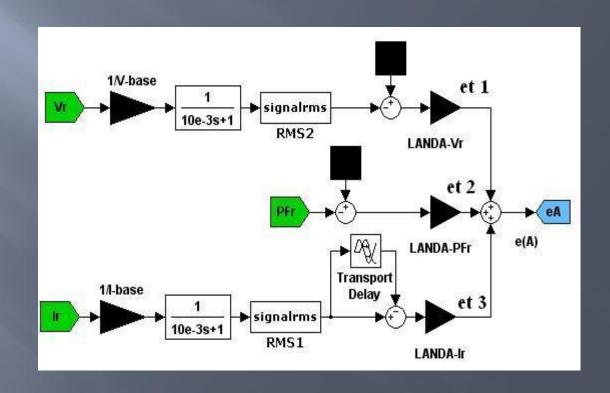


Proposed Battery Charger Grid



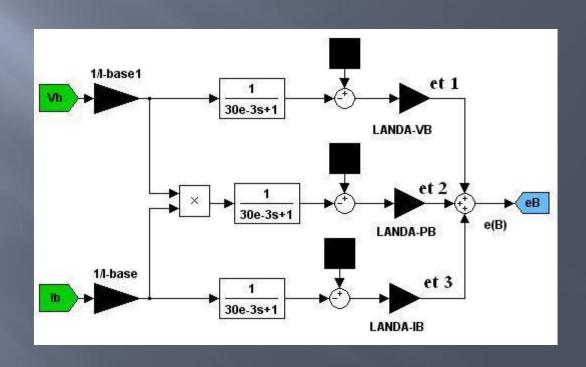
Dynamic Error-Driven Controller for HSCFC

- Triple-LoopController:
- <u>et1</u>: DynamicVoltage Error
- <u>et2:</u> DynamicPower FactorError
- <u>et3</u>: DynamicCurrent Ripple

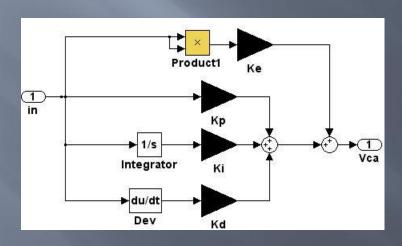


Dynamic Error-Driven Controller for Buck-Boost DC/DC Chopper

- Triple-LoopController:
- et1: VoltageDeviation fromDesired Value
- <u>et2</u>:Power Deviation from Desired Value
- <u>et3</u>:CurrentDeviation fromDesired Value



Weighted Modified PID with Error Squared Acceleration Loop



Simulation Results

using MATLAB/SIMULINK

 C_f =150micro Farad, R_f =0.05 Ω , Lf=3 mH C_r =30 micro Farad C_{d1} = C_{d2} = 2000 micro Farad C_B =4500 micro Farad

Battery Type: Lithium-Ion,

Nominal Voltage: 300V, Rated Capacity: 650 Ah

Multi-Loop Error Driven Controller:

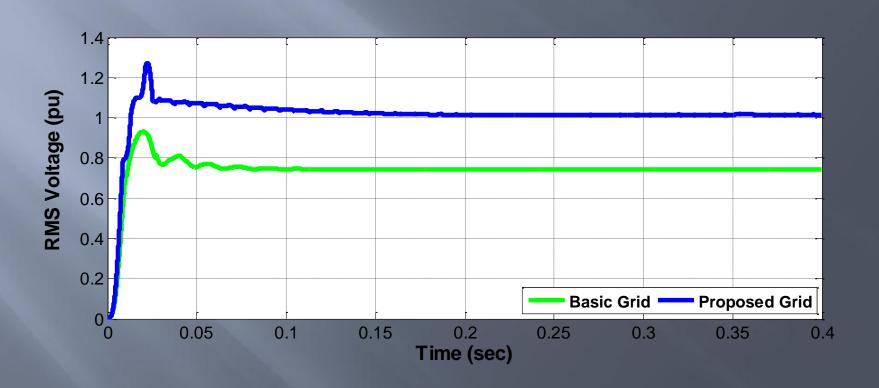
$$\gamma_{Vr}$$
=0.75, γ_{Ipf} =0.5, γ_{Ir} =0.5
 γ_{Vb} =0.75, γ_{Pb} =0.25, γ_{Ib} =0.5

WM-PID Controller:

$$K_e = 0.05$$
, $K_p = 2$, $K_i = 0.1$, $K_d = 0.05$

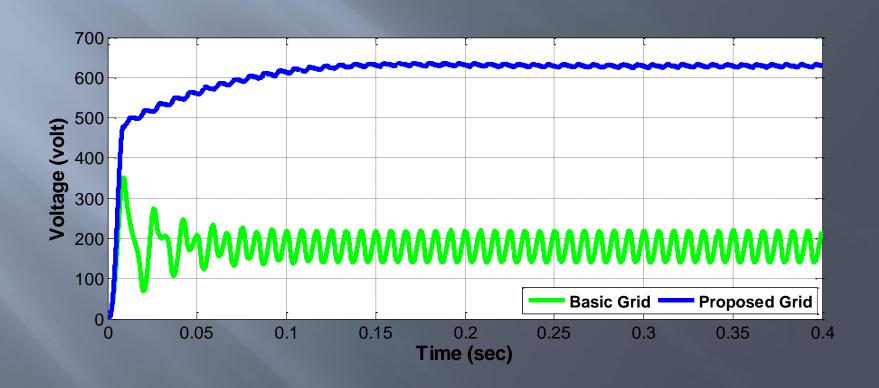
Voltages

Node r



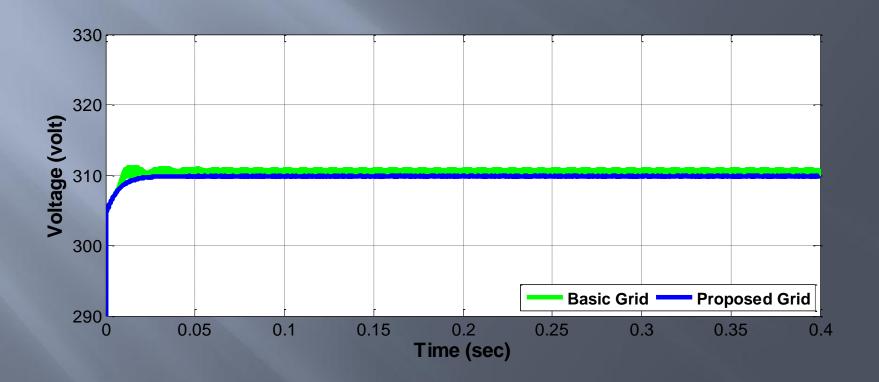
Voltages

Node d

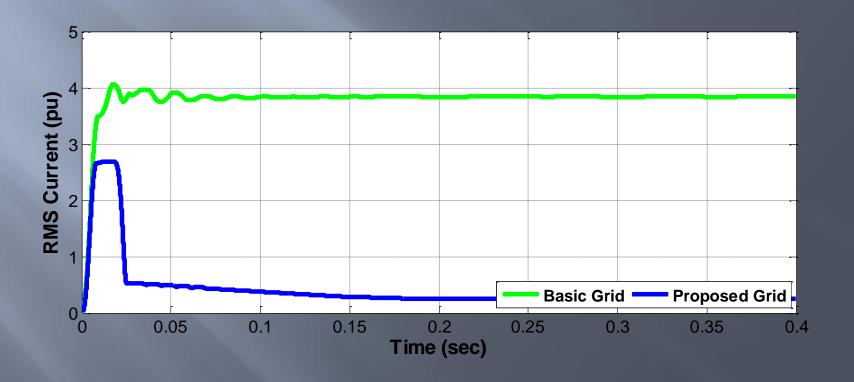


Voltage

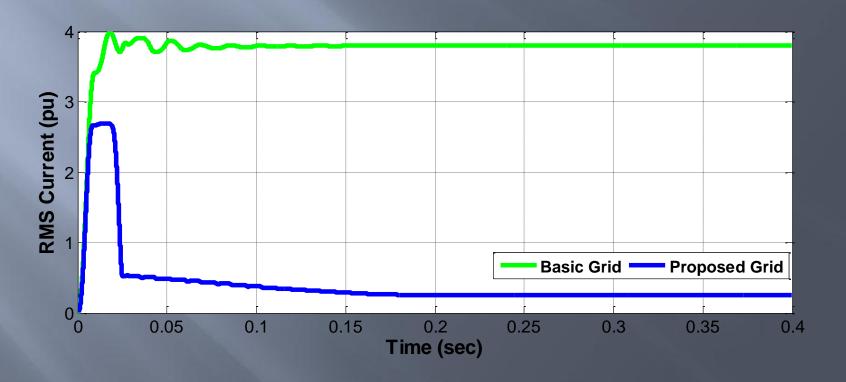
Node b



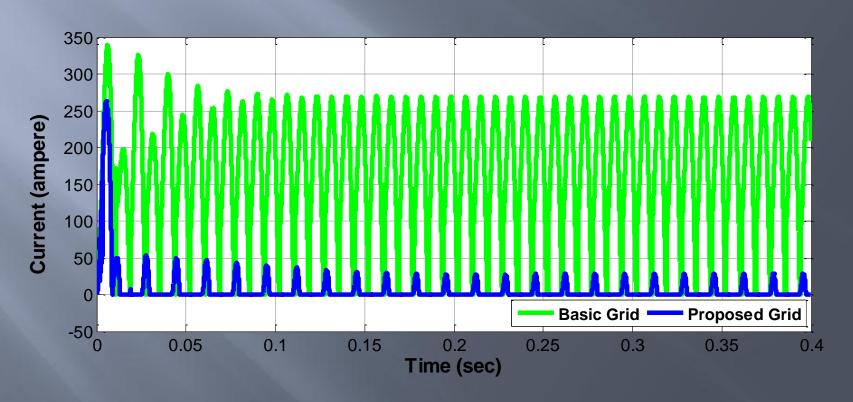
Node S



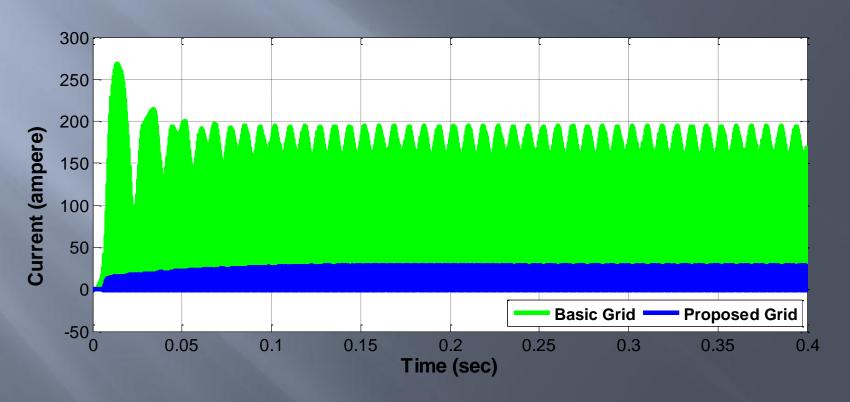
Node R



Node d

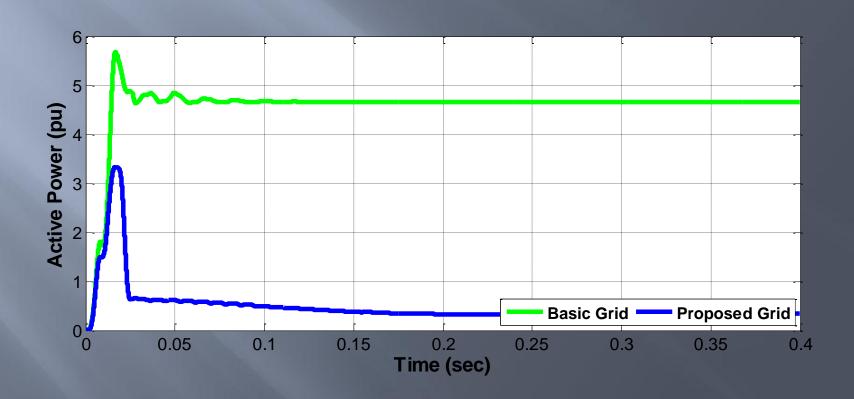


Node B



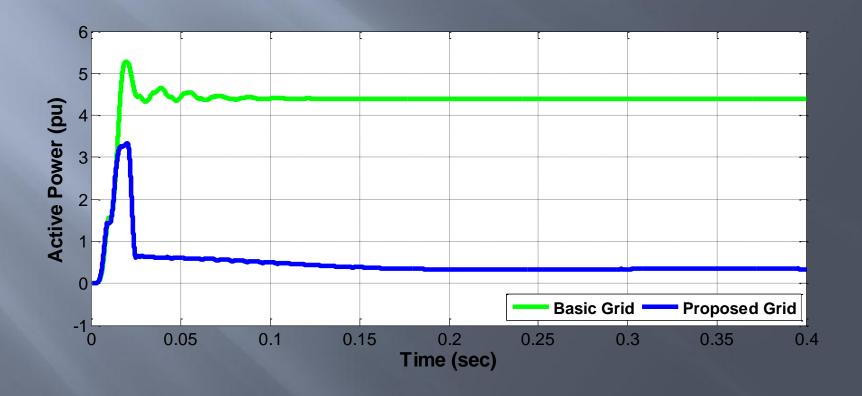
Active Power

Node S



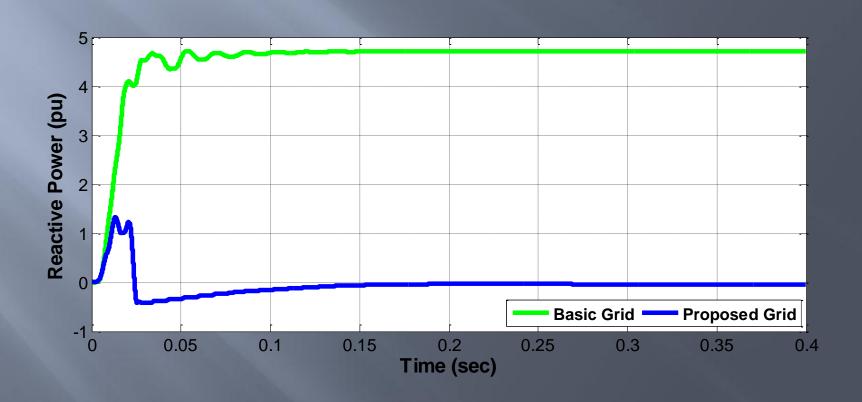
Active Power

Node R



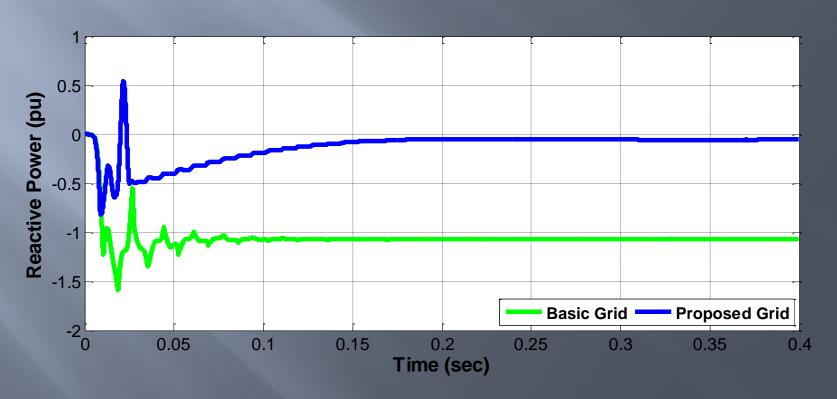
Reactive Power

Node S



Reactive Power

Node R



Conclusions

FACTS Hybrid SCFC + Buck-Boost DC/DC Chopper+ Novel Dynamic Control Strategies

For...

- Improved Voltage Regulation/Minimal inrush/transients in addition
- Improved Power Quality/Power Factor at AC-DC Bus interface
- Reduced reactive Power demand on the Limited Short Circuit and Minimum Impact on Smart Grid Interface
- Flexible Hybrid V_I_P Charging Regimes for Fast Charging
- Can be extended for Flexible AC and DC side interface of PV, Wind and
 FUEL CELL/Hydrogen PEM Green Renewable Energy Sources

Thank You