

# Signal Processing and Coding for Distributed Sensing and Storage

Xiaodong Wang

Electrical Engineering Dept.  
Columbia University, New York

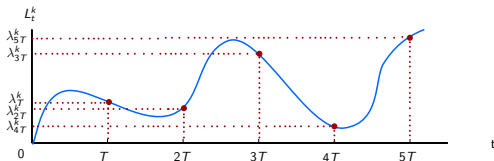
# Outline

- Distributed spectrum sensing via level-triggered sampling
- Coding and resource allocation for distributed wireless cloud

# Uniform Sampling vs. Event-triggered Sampling

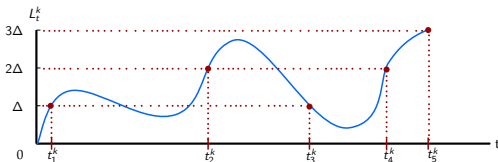
- Uniform in-time sampling:

- sample with period  $T$
- deterministic sampling

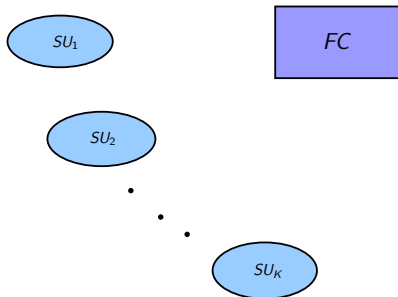


- Event-triggered sampling:

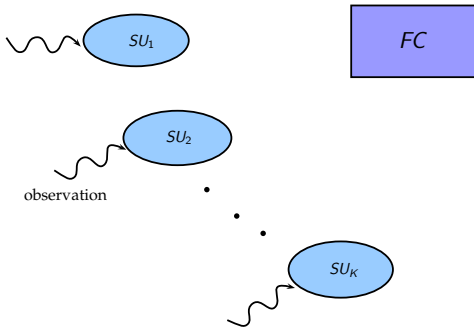
- sample whenever an event occurs (e.g., a level is passed)
- dynamic sampling  $\rightarrow$  samp. times dictated by the signal (random)



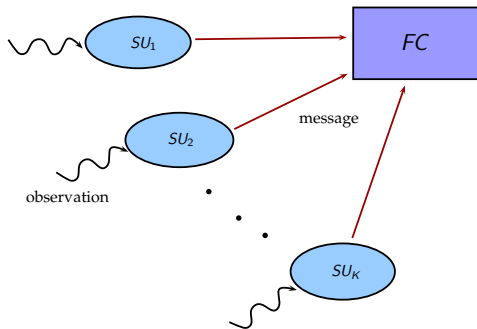
# Cooperative Spectrum Sensing



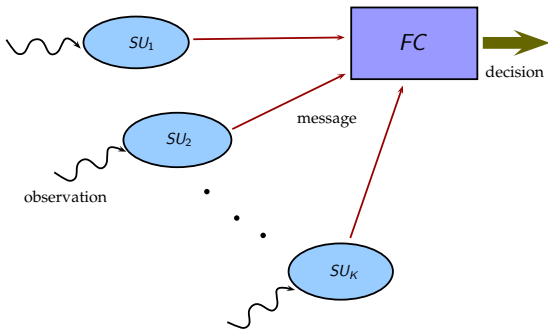
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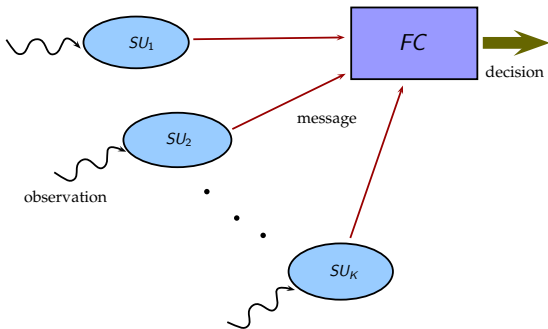
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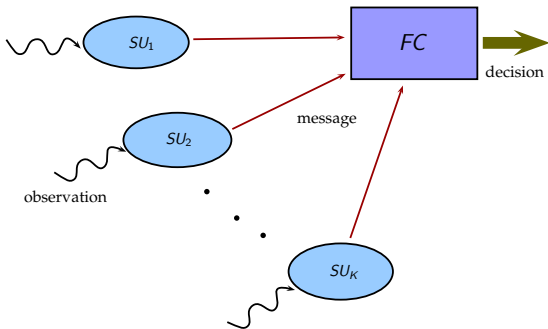
# Cooperative Spectrum Sensing



Decision mechanism: fixed sample size / sequential

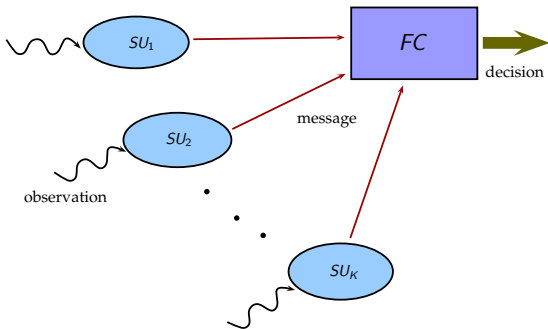


# Cooperative Spectrum Sensing



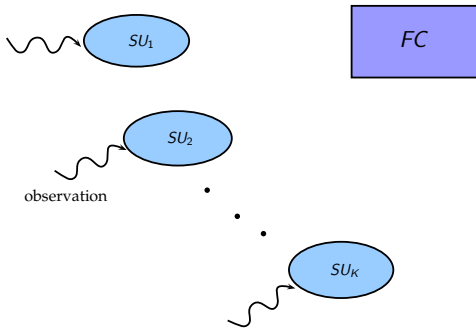
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# Cooperative Spectrum Sensing

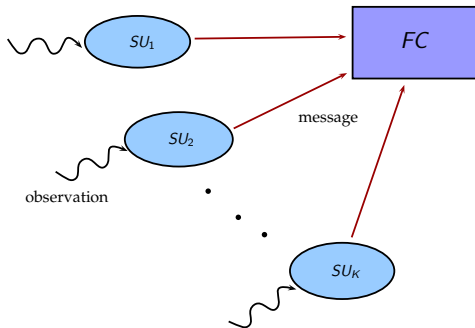


Decision mechanism: fixed sample size / sequential  
SPRT

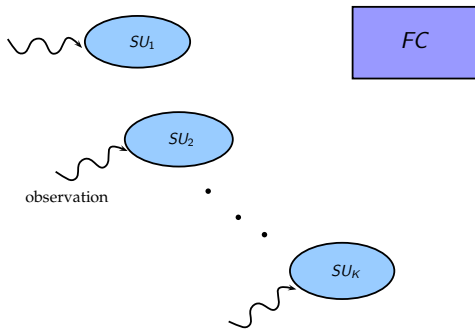
# Motivation



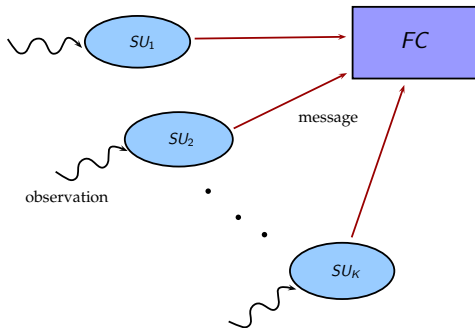
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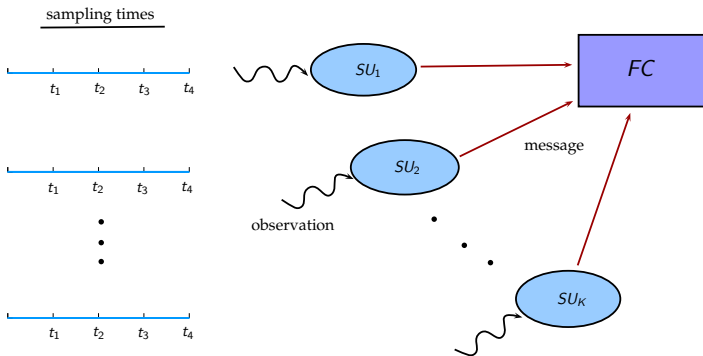
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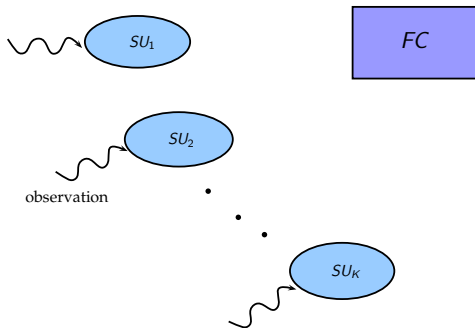


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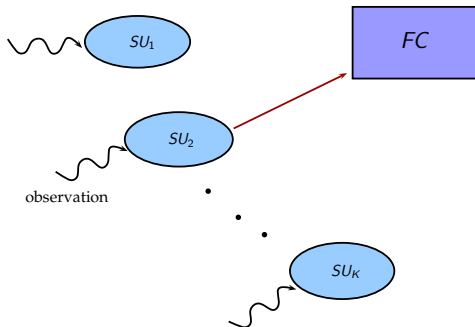
global clock (synchronous communication)

# Motivation

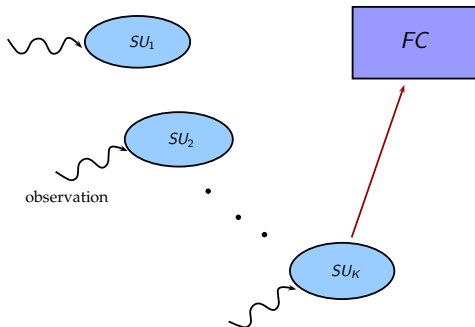




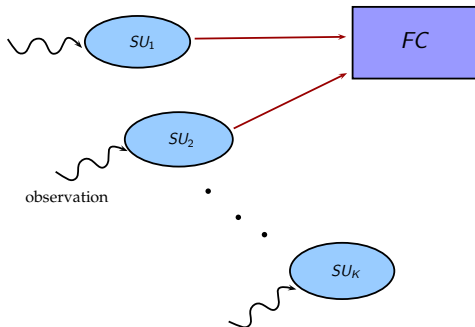
# Motivation



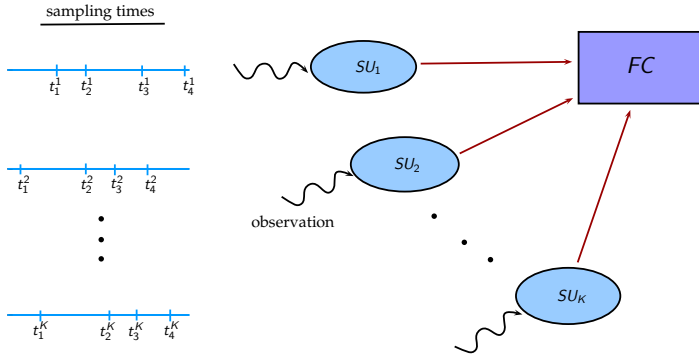
# Motivation



# Motivation



# Motivation



dynamic sampling (asynchronous communication)

# Spectrum Sensing via SPRT

Having observations  $\{y_1^k, \dots, y_t^k\}_{k=1}^K$  at SUs, we perform the following hypothesis test,

$$\begin{aligned} H_0 &: \{y_1^k, \dots, y_t^k\} \sim f_0, \quad k = 1, \dots, K \\ H_1 &: \{y_1^k, \dots, y_t^k\} \sim f_1, \quad k = 1, \dots, K \end{aligned} \quad (4)$$

Each SU computes its own log-likelihood ratio (LLR) and sends it to the FC.

$$L_t^k \triangleq \log \frac{f_1(y_1^k, \dots, y_t^k)}{f_0(y_1^k, \dots, y_t^k)} = \sum_{n=1}^t \underbrace{\log \frac{f_1(y_n^k)}{f_0(y_n^k)}}_{\ell_n^k} = L_{t-1}^k + \ell_t^k \quad (5)$$

FC computes the global LLR,  $L_t = \sum_{k=1}^K L_t^k$ , and applies SPRT to make a sensing decision.

## SPRT

$$\mathcal{S} = \inf \{t > 0 : L_t \notin (-B, A)\}, \quad (6)$$

$$\delta(\mathcal{S}) = \begin{cases} 1, & \text{if } L_{\mathcal{S}} \geq A, \\ 0, & \text{if } L_{\mathcal{S}} \leq -B. \end{cases} \quad (7)$$

# Spectrum Sensing via SPRT

Thresholds  $A, B$  are selected so that SPRT satisfies following constraints with equality.

$$P_0(\delta_S = 1) \leq \alpha \quad \text{and} \quad P_1(\delta_S = 0) \leq \beta \quad (8)$$

There are two serious practical weaknesses of SPRT in our problem.

- Local LLRs must be sent to the FC at Nyquist-rate.
- Infinite number of bits is required to represent local LLRs.

Substantial communication overhead is incurred between SUs and FC!

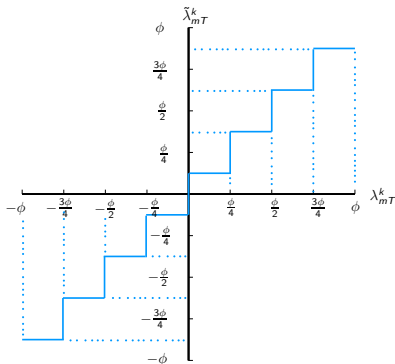
## Objective

Decentralized schemes  $\equiv$  low rate info. transmission from SUs to FC

# Decentralized Q-SPRT Scheme

## Secondary Users

- sample local LLRs uniformly at time instants  $T, 2T, \dots, mT, \dots$
- quantize sampled values using a finite number of levels,  $\tilde{r}$  (e.g. uniform mid-riser quantizer)



- send  $\tilde{\lambda}_{mT}^k$  to FC using  $\log_2 \tilde{r}$  bits

## Fusion Center

- synchronously receives quantized info. from SUs
- updates the approximation of the global running LLR

$$\tilde{L}_{mT} = \tilde{L}_{(m-1)T} + \sum_{k=1}^K \tilde{\lambda}_{mT}^k \quad (9)$$

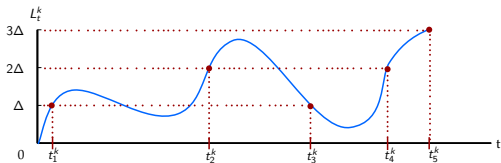
- applies the SPRT idea using  $\tilde{L}_{mT}$  and  $\tilde{A}, -\tilde{B}$  as the two thresholds.



# Decentralized Scheme based on Event-triggered Sampling

## Secondary Users

- sample local LLR process  $L_t^k$  at a sequence of random times  $\{t_n^k\}$



- send the information of the threshold that is crossed by  $\lambda_n^k = L_{t_n^k}^k - L_{t_{n-1}^k}^k$  to FC (either  $\Delta$  or  $-\Delta$ )

$$b_n^k = \text{sign}(\lambda_n^k) \quad (10)$$

### Remark

Each SU performs a local SPRT with thresholds  $\Delta$  and  $-\Delta$ .

# Decentralized Scheme based on Event-triggered Sampling

## Fusion Center

- approximates the local incremental LLR as  $\hat{\lambda}_n^k = b_n^k \Delta$ .

$$\hat{L}_{t_n^k}^k = \sum_{j=1}^n \hat{\lambda}_j^k = \hat{L}_{t_{n-1}^k}^k + b_n^k \Delta = \sum_{j=1}^n b_j^k \Delta \quad (11)$$

## Remark

If  $\lambda_n^k$  hits exactly one of the boundaries  $\pm\Delta$ , then we have exact recovery ( $\hat{L}_{t_n^k}^k = L_{t_n^k}^k$ ).

- adds all the received bits transmitted by all SUs up to time  $t$  and then normalizes the result with  $\Delta$ .

$$\hat{L}_t = \sum_{k=1}^K \hat{L}_t^k = \Delta \sum_{k=1}^K \sum_{n: t_n^k \leq t} b_n^k \quad (12)$$

- applies the SPRT idea using  $\hat{L}_t$  and  $\hat{A}, -\hat{B}$  as the two thresholds.

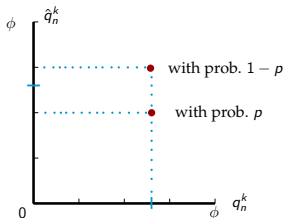
# Enhancement: Overshoot Quantization at SUs

A very important source of performance degradation:  $L_t^k - \hat{L}_t^k$

## Idea

use additional bits to quantize over(under)shoots,  $q_n^k \triangleq |\lambda_n^k| - \Delta$ .

- Divide  $[0, \phi]$  uniformly into  $\hat{r}$  subintervals.
- Transmit either lower or upper end of the corresponding subinterval by random selection.



$p$  is chosen so that

$e^{\hat{L}_{t_n}}$  and  $e^{-\hat{L}_{t_n}}$  are supermartingales,

which greatly simplifies the

performance analysis of the scheme

- FC at time  $t_n$  receives  $(b_n, \hat{q}_n)$ , and updates its approx. running LLR.

$$\hat{L}_{t_n} = \hat{L}_{t_{n-1}} + b_n(\Delta + \hat{q}_n) \quad (13)$$

## Definition

Any sequential scheme  $(\mathcal{T}, \delta_{\mathcal{T}})$  satisfying the error prob. bounds as  $\alpha, \beta \rightarrow 0$ , is said to be order-1 asymptotically optimal if

$$1 \leq \frac{E_i[\mathcal{T}]}{E_i[\mathcal{S}]} = 1 + o_{\alpha, \beta}(1); \quad (14)$$

and order-2 asymptotically optimal if

$$0 \leq E_i[\mathcal{T}] - E_i[\mathcal{S}] = O(1) \quad (15)$$

where  $(\mathcal{S}, \delta_{\mathcal{S}})$  is the optimum SPRT.

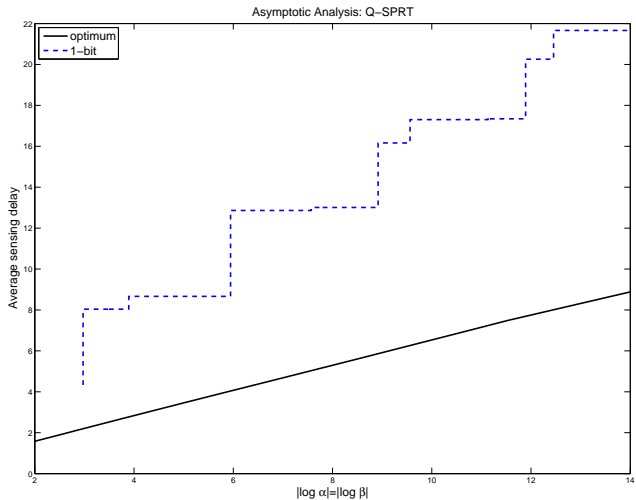
Cont.-time results:

- Q-SPRT is **not** even order-1 asymp. optimal with **any fixed** number of bits.
- RLT-SPRT is **order-2** asymp. optimal with only **one** bit.

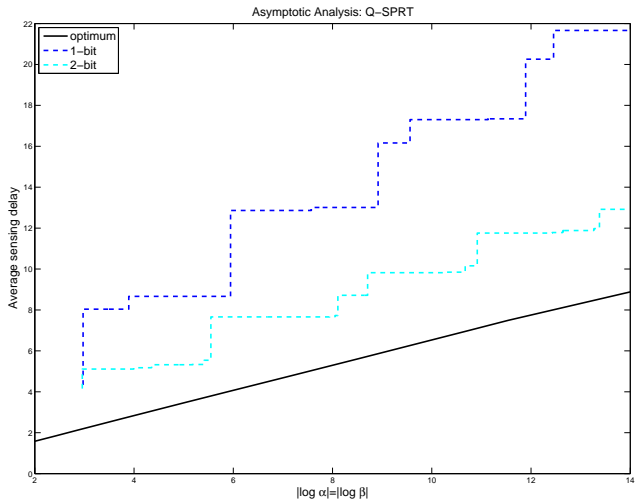
In order to make fair comparisons,  $\Delta$  is adjusted so that average frequency of received messages by the FC is the same for Q-SPRT and RLT-SPRT.

- RLT-SPRT needs significantly less bits than Q-SPRT in order to enjoy order-2 asymptotic optimality.
- For fixed  $s$ , RLT-SPRT achieves order-1 asymp. optimality when  $T \rightarrow \infty$  with a rate slower than  $|\log \alpha|$ .
- In contrast, by controlling  $T$ , Q-SPRT can not enjoy any form of asymp. optimality.

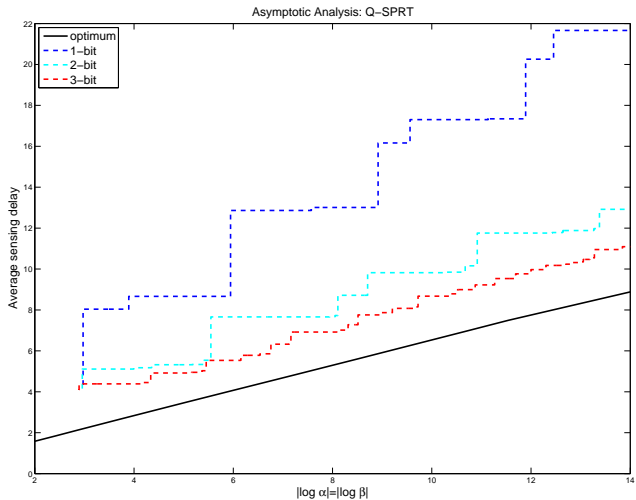
# Simulations: Q-SPRT



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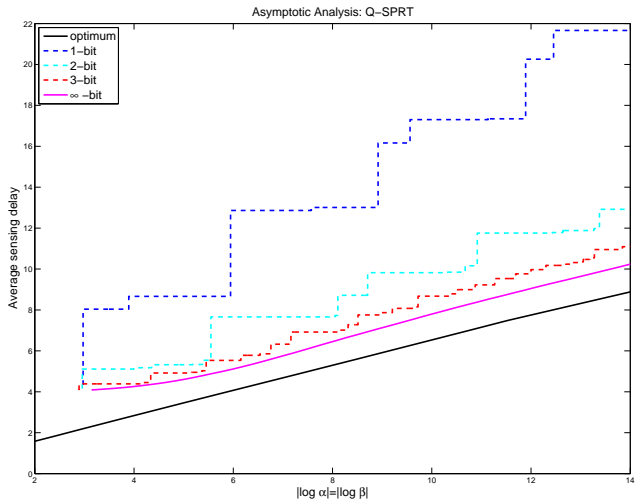


# Simulations: Q-SPRT

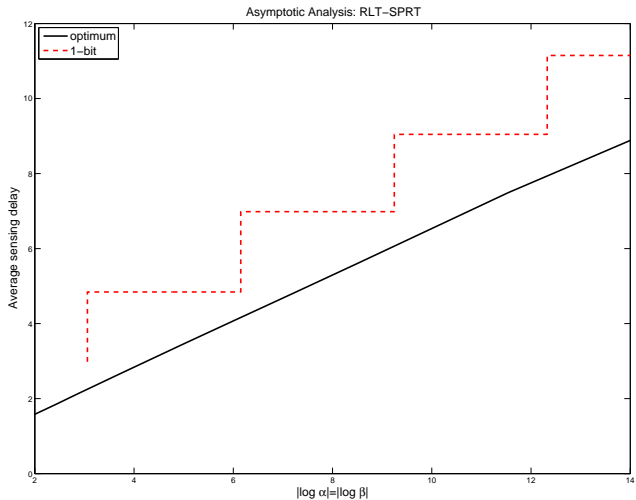




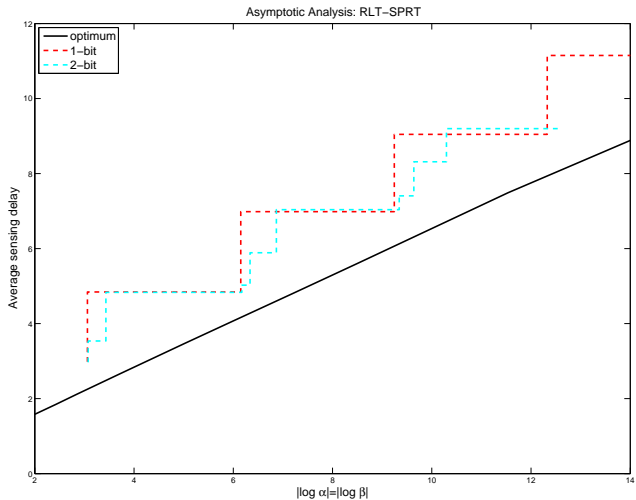
# Simulations: Q-SPRT



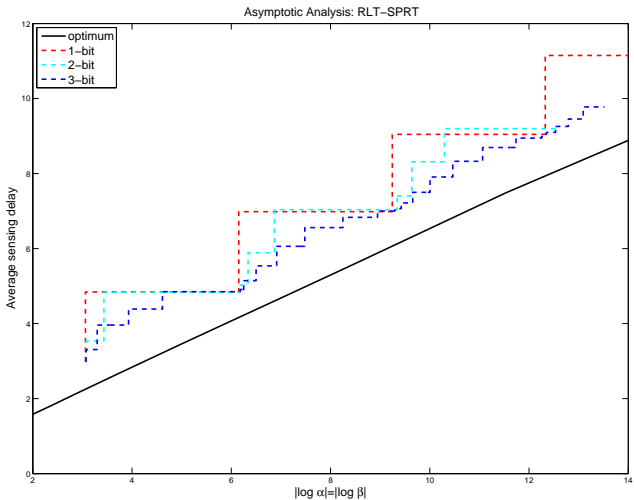
# Simulations: RLT-SPRT



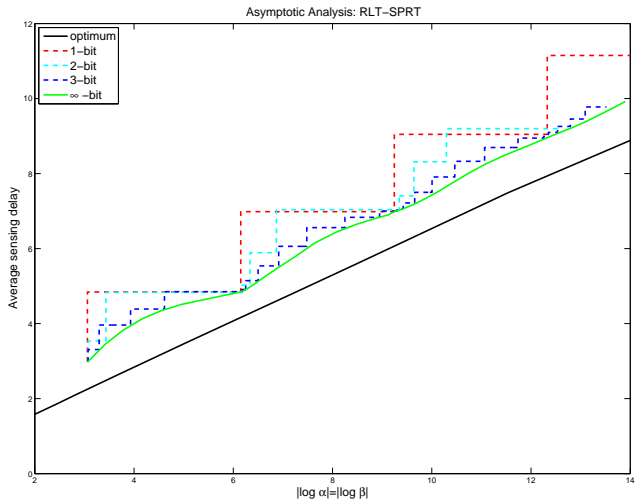
# Simulations: RLT-SPRT



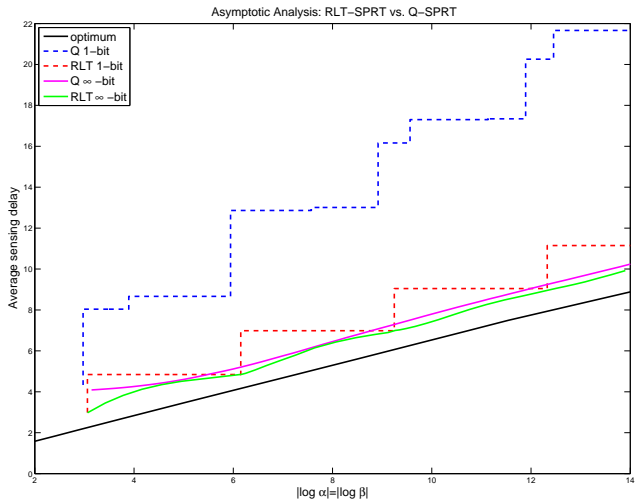
# Simulations: RLT-SPRT



# Simulations: RLT-SPRT



# Simulations: RLT-SPRT vs. Q-SPRT



The proposed decentralized (low-rate transmission) scheme based on non-uniform samplers

- asynchrony among SUs
- order-2 asymp. optimality
  - only 1 bit in cont.-time
  - significantly less number of bits ( $-\log_2 T$ ) than Q-SPRT in disc.-time
- order-1 asymp. optimality using a constant num. of bits when av. comm. period is controlled

Its uniform sampling counterpart (Q-SPRT)

- no optimality using const. num. of bits
- order-2 optimality when num. of bits is allowed to increase at a rate  $O(\log |\log \alpha|)$
- no optimality when num. of bits kept constant and av. comm. period changed

# Coding for Distributed Storage in Wireless Clouds

Chen Gong

Qualcomm Research San Diego, Qualcomm Inc.

Prof. Xiaodong Wang

Department of Electrical Engineering, Columbia University



## Data Centers

- Server clusters that store and process all the data in the Internet
- There were 509147 data centers worldwide in 2011
- Consume vast amounts of energy - more than 2% of US electricity
  - Power to run and repair servers, and for cooling systems
  - Backup power generators use diesel cause air pollution
- Consequences if a data center breaks down (electricity failure)

## Desired Properties of Distributed Storage

- Reliability against disk failures
- Recovery with minimum cost
- Simple updates when data changes
- Easy accessibility without blocking
- Easy failed node repair
  - no data recovery efficiency loss after failed node repair

## Trade-offs in Distributed Storage

- Reliability vs. Storage
  - Replication is the most commonly used redundancy
  - $(n, k)$  MDS Codes - any  $k$  out of  $n$  sufficient for data recovery
- Storage vs. Repair Bandwidth
  - Locally Repairable Codes - To restore a failed disk by accessing minimum number of working disks
- Accessibility vs. Storage
  - Coding gives lower blocking probability than replication for the same storage (Energy Cost)

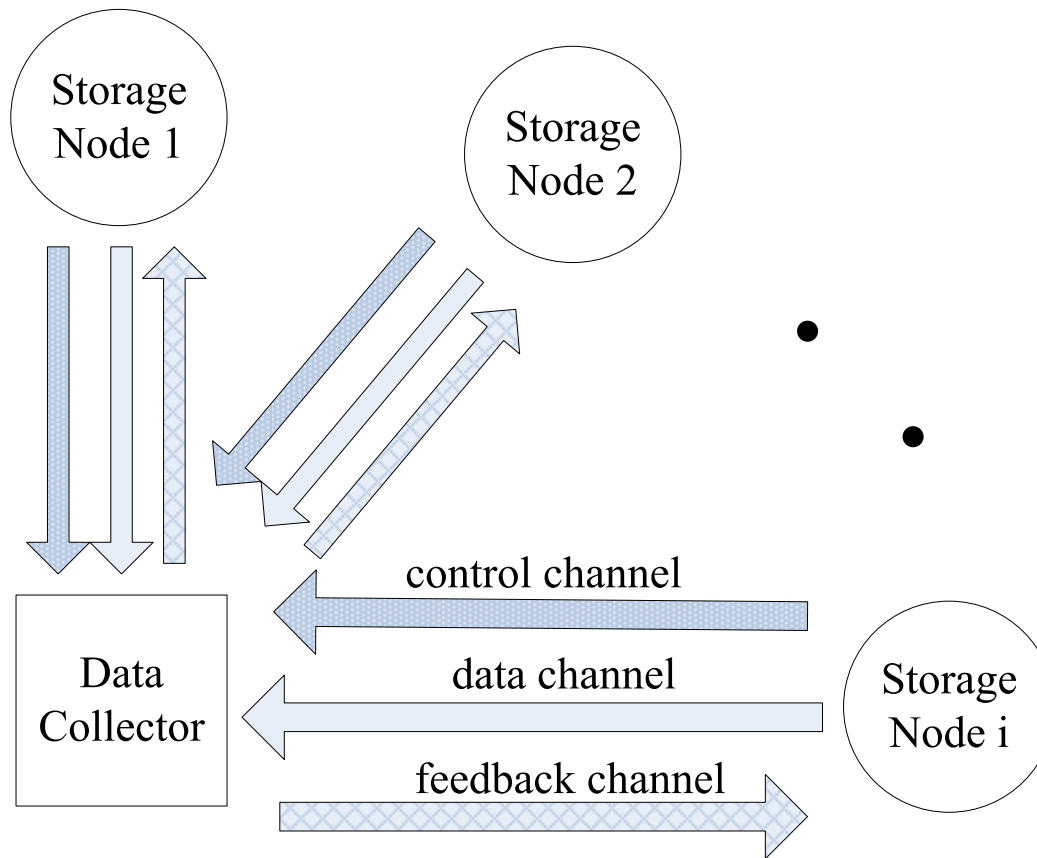
## Distributed Wireless Clouds

- Information storage and retrieve in Mobile Wireless Cloud
- Mobile Wireless Cloud without Infrastructure
  - Military communication networks
  - Wireless cloud of Vehicles and Ships
  - Emergency cases: earthquake, tsunami, infrastructures destroyed
- Large amount of data exceeding the infrastructure capacity
- Security reasons, information must be stored locally

## Technique Overview

- A file split into several parts,
  - coded symbols across the split parts,
  - stored in various data storage nodes;
- A data collector, reconstruct the original files:
  - via downloading data from the storage nodes
- Download part of the data from each storage node
  - amount of downloaded data depends on wireless link strength
- Orthogonal wireless channels for symbol downloading

## Basic Structure for Wireless Storage Networks



wireless distributed storage network structure

## Failed Node Regeneration

- A failed storage node downloads symbols from other nodes;
- Exactly recover the coded data symbols it stored;
- Similar procedure as that for data reconstruction.

# Distributed Storage Modeling for Wireless Cloud

## Distributed storage:

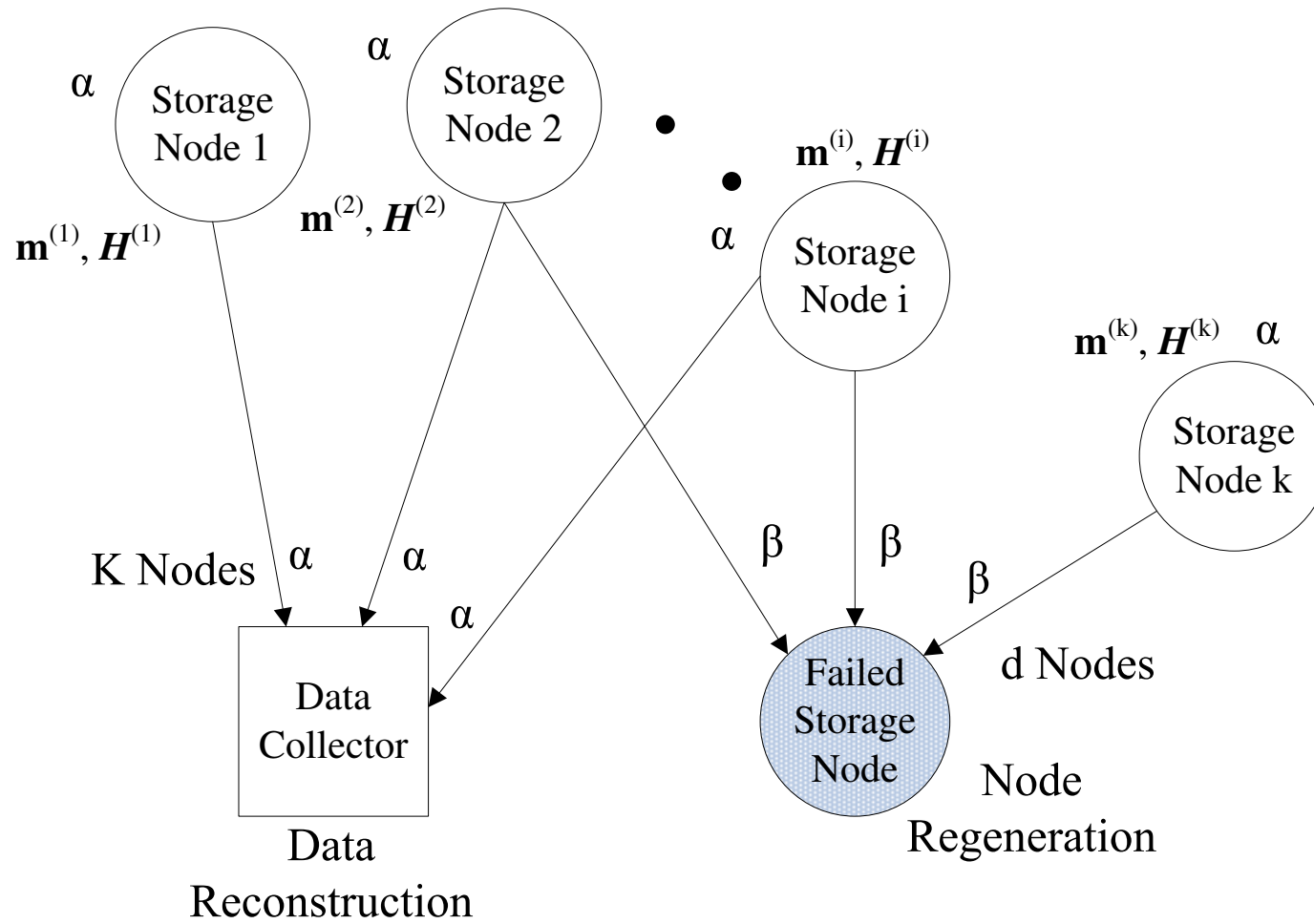
- store a file in a distributed manner, **in several nodes**
- two operations:
  - reconstruct the original file
  - repair the storage in a failed node

## $(S, K, d, \alpha, \beta)$ regenerating code:

- totally  $S$  storage nodes, each storing  $\alpha$  symbols;
- reconstruct original file,
  - via downloading all  $K\alpha$  symbols from **any  $K$  nodes**;
- repair a failed node,
  - via downloading  $\beta$  symbols each from any  $d$  surviving nodes



# Data Reconstruction and Node Regeneration



# Wireless Distributed Storage Data Coding

## Distributed storage setting:

- original file:  
 $\mathbf{s} = [s_1, s_2, \dots, s_M];$
- each storage node  $i$  stores:  
 $\mathbf{m}^{(i)} = \mathbf{s}^T \mathbf{H}^{(i)};$

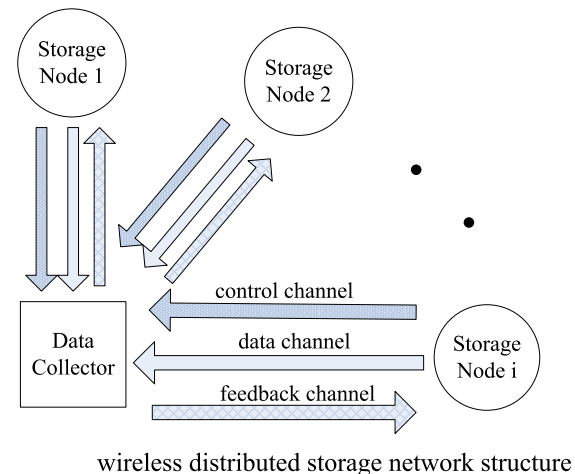
## Wireless network setting:

- a data collector (DC)
- $N$  orthogonal channels

$$c(|g_j^{(i)}|^2 P_j) = \frac{WT}{B} \log_2 \left( 1 + \kappa \frac{|g_j^{(i)}|^2 P_j}{\sigma^2} \right)$$

## Full downloading and partial downloading:

- full downloading
  - power grows exponentially with the capacity
- partial downloading



# Partial Downloading Linear Combination

## Partial downloading formulation:

- downloading  $\mu_i \leq \alpha$  symbols from storage node  $i$
- downloading linear combination  $\mathbf{s}^T \mathbf{H}^{(i)} \mathbf{A}^{(i)}$ 
  - $\mathbf{A}_{\alpha \times \mu_i}^{(i)}$  linear combination matrix;
- downloading symbols:  $\mathbf{s}^T \left[ \mathbf{H}^{(i)} \mathbf{A}^{(i)} \right]_{i \in \mathcal{S}}$ 
  - $\mathbf{s}$  reconstructable iff  $\left[ \mathbf{H}^{(i)} \mathbf{A}^{(i)} \right]_{i \in \mathcal{S}}$  of rank  $M$

## Downloading original symbols:

- **Theorem:**  $\left[ \mathbf{H}^{(i)} \mathbf{A}^{(i)} \right]_{i \in \mathcal{S}}$  of rank  $M \Rightarrow \left[ \bar{\mathbf{H}}^{(i)} \right]_{i \in \mathcal{S}}$  of rank  $M$ ,
  - $\exists \bar{\mathbf{H}}^{(i)}, \alpha \times \mu_i$  submatrix of  $\mathbf{H}^{(i)}$
- downloading original symbols suffices
  - no need to use linear combination (matrix  $\mathbf{A}^{(i)}$ )

# Wireless Cloud Resource Allocation Formulation

## Wireless resource allocation:

- data reconstructable:  $[\mu_1, \mu_2, \dots, \mu_S]$ ,  $M \times \mu_i$  submatrix  $\bar{\mathbf{H}}^{(i)}$  of  $\mathbf{H}^{(i)}$ 
  - $[\bar{\mathbf{H}}^{(i)}]_{i \in \mathcal{S}}$  of rank  $M$
- $\beta_j^{(i)} = 1$  if DC downloads from storage node  $i$  using channel  $j$ 
  - $X_j = c(P_j \sum_{i \in \mathcal{S}} \beta_j^{(i)} |g_j^{(i)}|^2)$ ,  $\mu_i = \sum_{j=1}^N \beta_j^{(i)} X_j$  .....(1)

## Problem formulation:

minimize transmission power s.t. data reconstructable

- $\min \sum_{j=1}^N P_j$ ; s.t. data reconstructable, (1),  $\sum_{i \in \mathcal{S}} \beta_j^{(i)} \leq 1$ .

## Difficulty: how to analyze the data reconstructability

- transform the full rank constraint to ...

## Data Reconstructability (MSR)

### Full rank constraint:

- transform it using  $\mu_i$ : downloading  $\mu_i$  symbols from node  $i$ ;

### Minimum storage regeneration (MSR):

- MSR:  $M = K\alpha$ , minimum downloading for data reconstruction
  - $\left[ \mathbf{H}^{(i)} \right]_{i \in \mathcal{R}}$  of rank  $M$  for **any**  $|\mathcal{R}| = K$ ;
- Simple necessary condition: number of downloaded symbols  $\geq M$ 
  - this is **also sufficient**
- **Theorem:** For **any**  $\sum_{i \in \mathcal{S}} \mu_i \geq M$ ,  $\mu_i \leq \alpha$ , there exists  $\mu_i \times \alpha$  submatrix  $\bar{\mathbf{H}}^{(i)}$  of  $\mathbf{H}^{(i)}$ , such that  $\left[ \bar{\mathbf{H}}^{(i)} \right]_{i \in \mathcal{S}}$  is of rank  $M$ .
  - keep adding linearly independent symbols, plus some stuck processing

## Wireless Cloud Resource Allocation (MSR)

### Relaxed resource allocation problem:

- $\sum_{i \in \mathcal{S}} \mu_i \geq M, \mu_i \leq \alpha \Rightarrow$  remove constraint  $\mu_i \leq \alpha$ ;
- problem reformulation
  - minimize transmission power, s.t. **totally downloading  $M$  symbols**;
  - $\min \sum_{j=1}^N P_j$ ; s.t.  $\sum_{j=1}^N X_j = M$ .
- two-step **optimal solution**
  - each channel  $j$  allocated to the best user,  $\max_i |g_j^{(i)}|^2$ ;
  - **optimal greedy algorithm** for symbol allocation.

### Local adjustment:

- in case that the constraint  $\mu_i \leq \alpha, i \in \mathcal{S}$  violated
- rarely happens in simulation scenarios

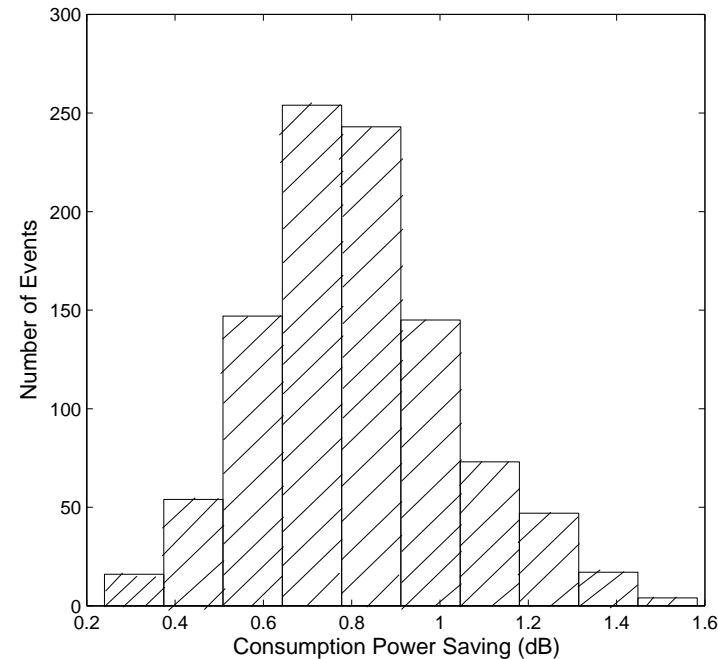
## Wireless Cloud Resource Allocation Results (MSR)

### System setup:

- node number  $S = 16$ , channel number  $N = 64$ , noise  $\sigma^2 = 0.25$ , coefficients  $\kappa = 0.5$ ,  $\frac{WT}{B} = 0.25$ ;
- MSR:  $M = 16$ ,  $K = \alpha = 4$ ;

### Partial downloading:

- 1000 channel realization,
- total transmission power  
- mostly more than 0.6dB performance gain over full downloading



## Wireless Cloud Resource Allocation (MBR)

### Partial downloading:

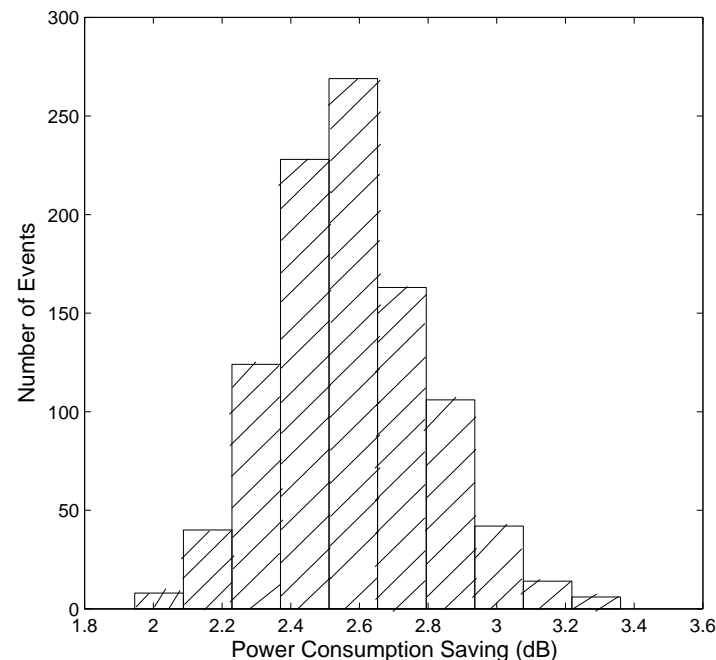
- more complicated reconstructability condition;
- downloaded symbols:  $M(< K\alpha)$ 
  - $K\alpha$  required by full downloading;

### Resource allocation:

- relax to  $\sum_{i \in \mathcal{S}} \mu_i = M$ ;
- optimal greedy solution + local adjustment (rare);

### Results:

- 1000 channel realization,
- total transmission power
  - mostly around 2.5dB performance gain over full downloading





## Performance Comparison with Existing Schemes

### Existing schemes - flexible downloading:

- any  $\sum_{i \in \mathcal{S}} \mu_i \geq M$  symbols suffice data reconstruction;
- needs  $\gamma$  symbols for failed node repair;

### Bound for failed node repair $\gamma$ :

- MSR point  $\alpha = 4, M = 16$ : bound  $\gamma \geq 7$ , partial downloading  $\gamma = 7$ ;
- MBR point  $\alpha = 6, M = 18$ : bound  $\gamma \geq 8$ , partial downloading  $\gamma = 6$ ;  
- only  $\sum_{i \in \mathcal{S}} \mu_i \geq M$  not suffices, but usually suffices for wireless setting

### Explicit coding schemes for failed node repair:

- MSR point: flexible downloading  $\gamma = 10$ , partial downloading  $\gamma = 7$ ;
- MBR point: flexible downloading  $\gamma = 12$ , partial downloading  $\gamma = 6$ ;