Application of time-reversal methods to communication in hostile environments

San Ramon, CA
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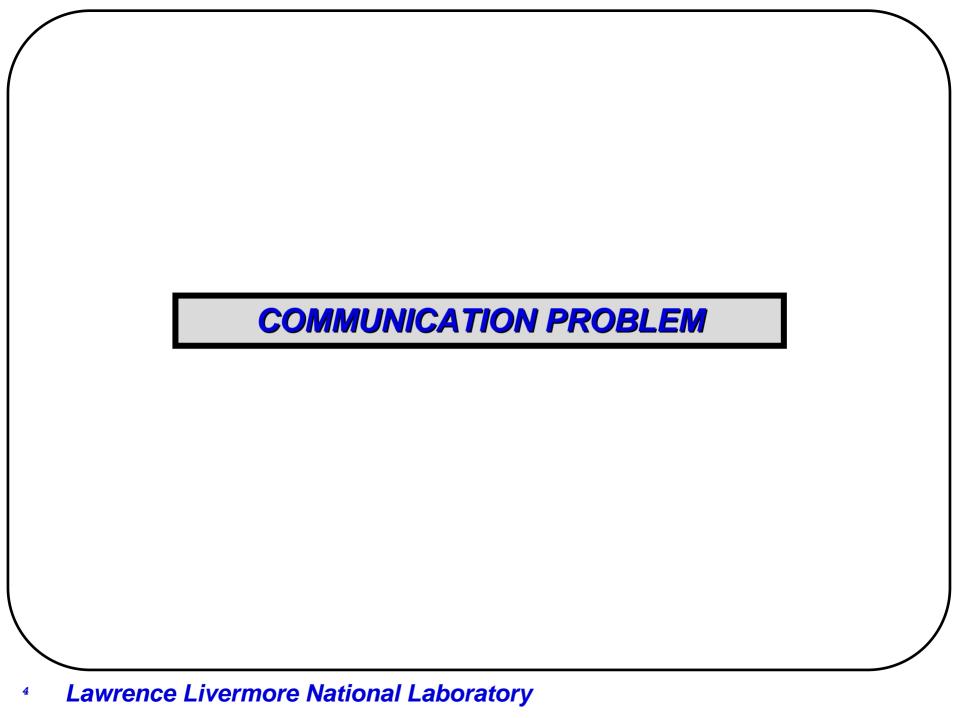
Auspices

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UCRL-PRES-225469

ORGANIZATION

- COMMUNICATION PROBLEM
- REVIEW OF TIME-REVERSAL
- TIME-REVERSAL POINT-TO-POINT (P2P) RECEIVERS
- TIME-REVERSAL ARRAY-TO-ARRAY (A2A) RECEIVERS
- WIDEBAND TIME-REVERSAL RECEIVERS
- SUMMARY AND FUTURE DIRECTIONS

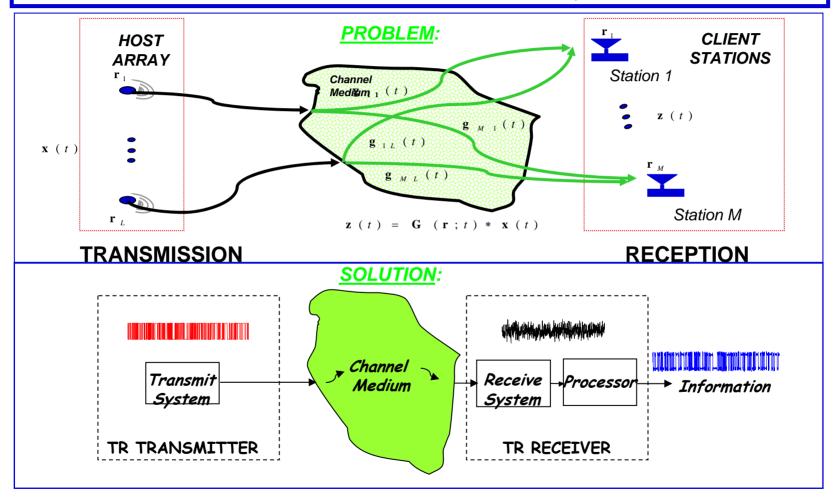




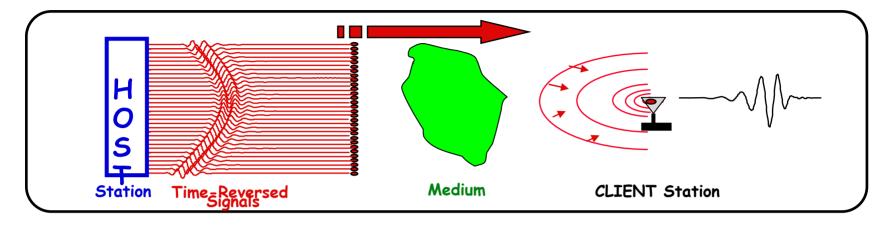
Transmit information in a hostile medium (mpath, mscatterers, reverb, noise) and extract it with minimal symbol/bit error

APPROACH:

Time reversal (TR) communication system

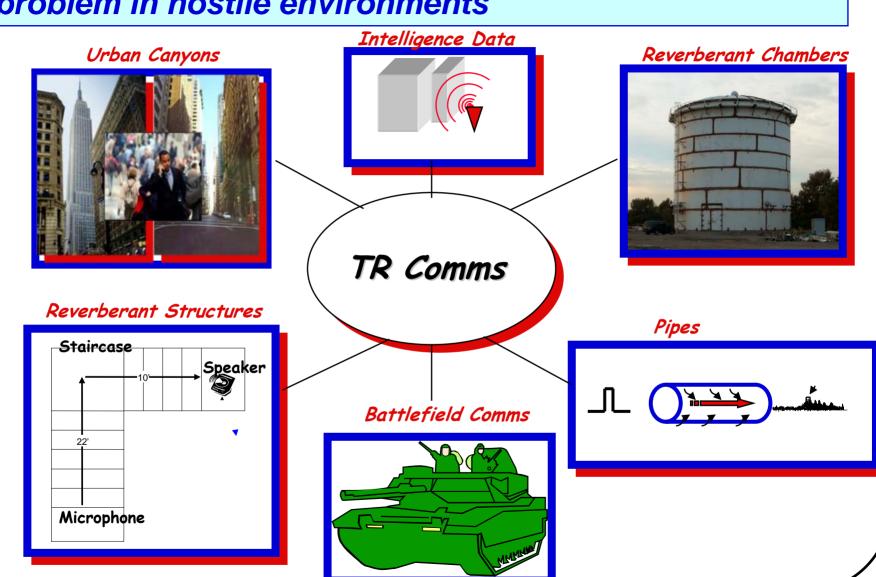


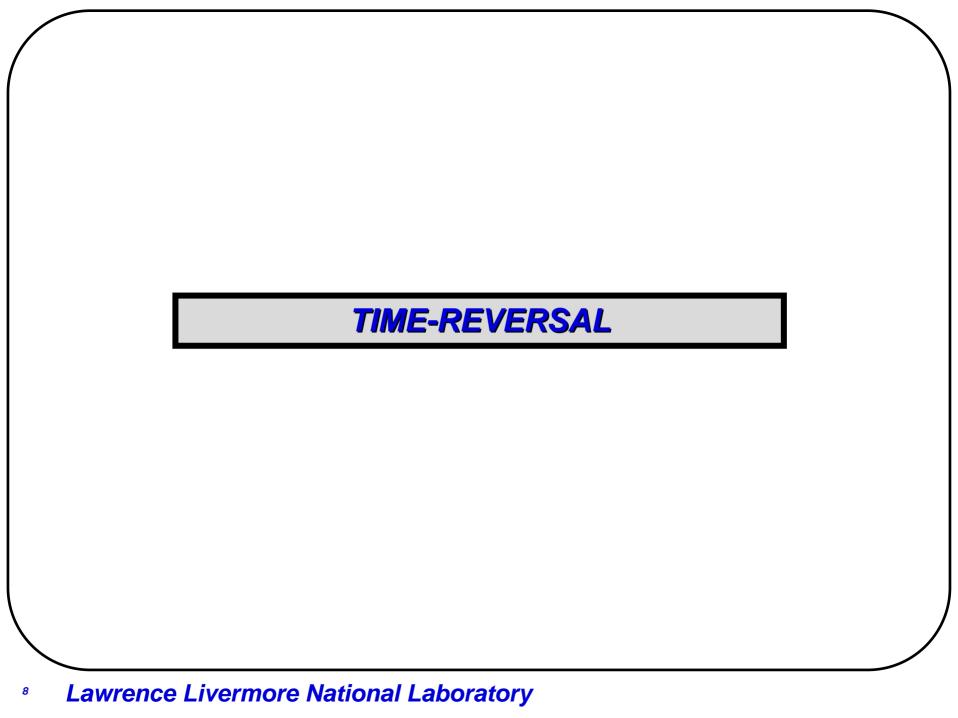
TR communication systems can:



- · mitigate multipath, multiple scattering, inhomogeneous effects
- · focus signal energy at a client station through a hostile medium
- · provide a secure link (unique medium function) from host-to-client
- · be deployed in point-to-point (P2P) or array configurations (A2P, A2A)
- · compliment existing communications technology
- · be implemented in software

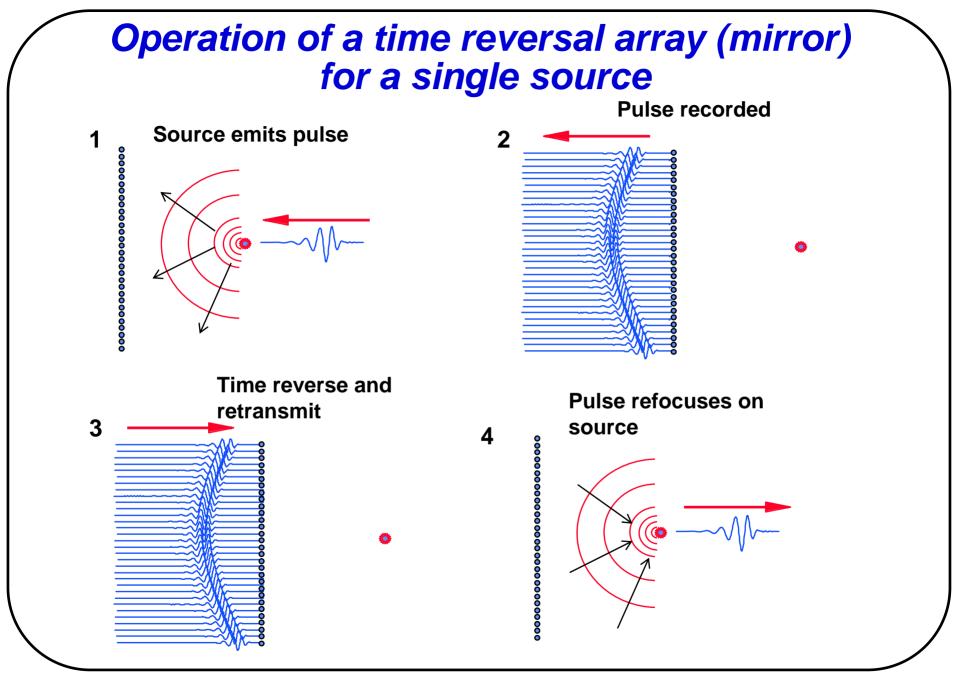
TR offers an alternate solution to the communications problem in hostile environments



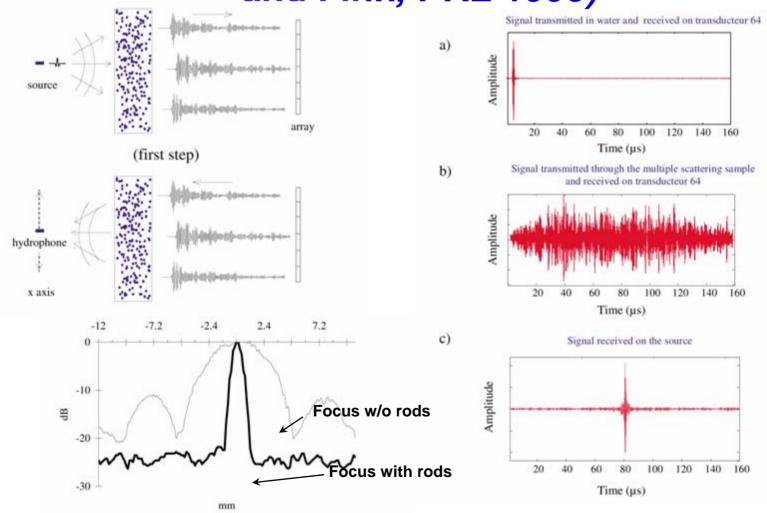


What is time reversal wave propagation?

- Time reversal techniques exploit the symmetry of wave propagation to the direction of time (time invariance, reciprocity) to enhance focusing, imaging, and target characterization
- Experimentalist: A simple technique for focusing energy on a target through an uncharacterized or complicated media
- Signal processor: A hardware implementation of a broadband spatio-temporal matched filter for multi-channel array data (minimal calculation)
- Applied mathematician: A symmetry of propagation and scattering useful for understanding scattering in difficult media and designing inversion and imaging methods ==> target characterization



Time reversal allows focusing through complicated media (experiment by Derode, Roux, and Fink; PRL 1995)



Time reversal as a spatio-temporal matched filter (1)

Simple matched filter

Given data u(t) = s(t) + n(t); s(t): signal, n(t): white noise Determine filter h(t) so that y(t) = h(t)*u(t) has maximum SNR at time T:

$$SNR(T) = \frac{\left| \int_0^T h(t')s(T-t')dt' \right|^2}{\sigma^2 \int_0^T \left| h(t') \right|^2 dt'} \qquad \sigma : \text{ noise variance}$$

Answer is h(t) = s(T-t); time-reversed version of signal

• Generalization to multi-channel data u_n(t) gives MMSE beamformer

Time reversal as a spatio-temporal matched filter (2)

Spatio-temporal matched filter
 Given an array with elements at positions a_n: n= 1,2,...,N
 Determine excitations E_n(t) that maximize SNR of the transmitted field at time T AND position x₀

$$\psi(x,t) = \sum_{n=1}^{N} \int_{0}^{t} G(x,a_{n},t-t') E_{n}(t') dt'$$
 Field at x and t generated by array

 \mathbf{x}_0 $G(x,t;a_n,t)$ Green's function (impulse response)

$$SNR(x_0, T) = \frac{\left| \sum_{n=1}^{N} \int_{0}^{T} G(x_0, a_n, T - t') E_n(t') dt' \right|^2}{\sum_{n=1}^{N} \int_{0}^{T} \left| E_n(t') \right|^2 dt'}$$

Answer is $E_n(t) = G(x_o, a_n, T-t)$: time-reversed Green's function

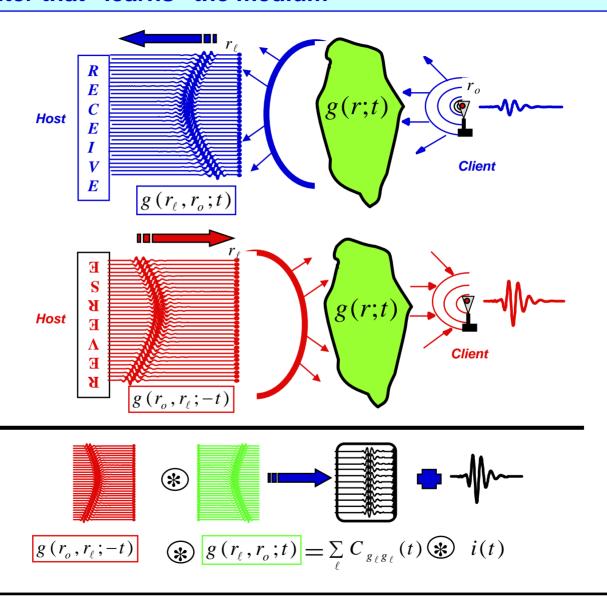
$$\psi_{MF}(x,t) = \sum_{n=1}^{N} \int_{0}^{t} G(x,a_{n},t-t')G(x_{0},a_{n},T-t')dt'$$

a₃ ■

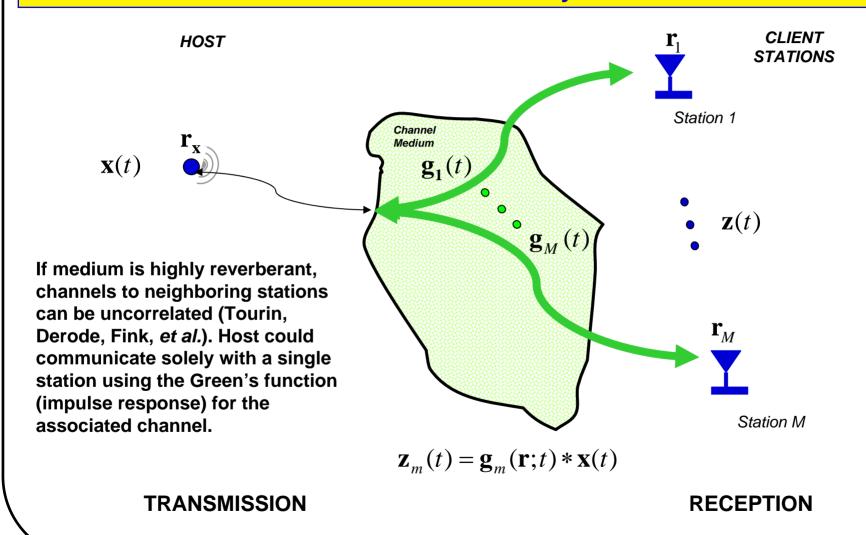
 a_N^{\bullet}



A TR communication system is an intelligent, *optimal*, space-time, matched-filter that "learns" the medium



The medium (Green's function) provides UNIQUE paths (channels) from each client station to the host sensor---this is the key in T/R communications



TR processing - time and frequency domains

$$z(t) = g(r;t) * i(t) \Leftrightarrow Z(\omega) = G(r;\omega) \times I(\omega)$$

Impulsive for highly reverberant medium

In the time domain, the TR processor is:

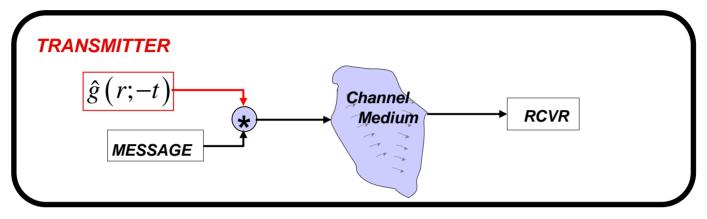
$$\hat{i}(t) \approx z(t) * \hat{g}(r;-t) = [g(r;t) * \hat{g}(r;-t)] * i(t) = C_{gg}(t) * i(t)$$

While in the temporal frequency domain it looks more familiar:

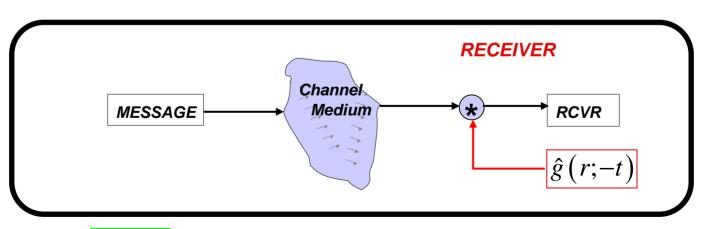
$$\hat{I}(\omega) = Z(\omega) \times G^{*}(r;\omega) = \left[G(r;\omega) \times G^{*}(r;\omega) \right] \times I(\omega) = \left| G(r;\omega) \right|^{2} \times I(\omega)$$

Spectral
Phase Conjugation

TR signal processing can be applied at either the transmitter or receiver:

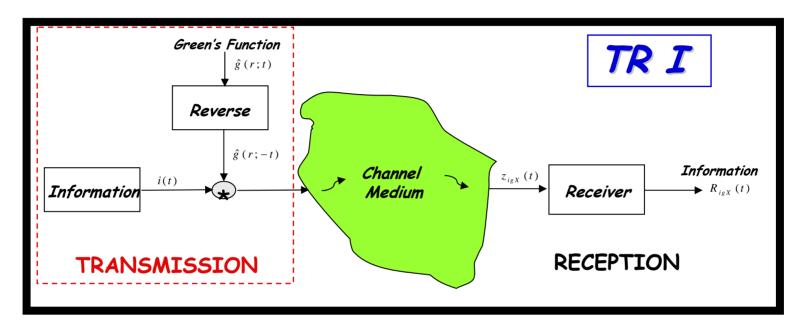


$$R(t) = g(r;t) * [\hat{g}(r;-t)*i(t)] = [g(r;t)*\hat{g}(r;-t)]*i(t) = C_{g\hat{g}}(r;t)*i(t) \approx i(t)$$

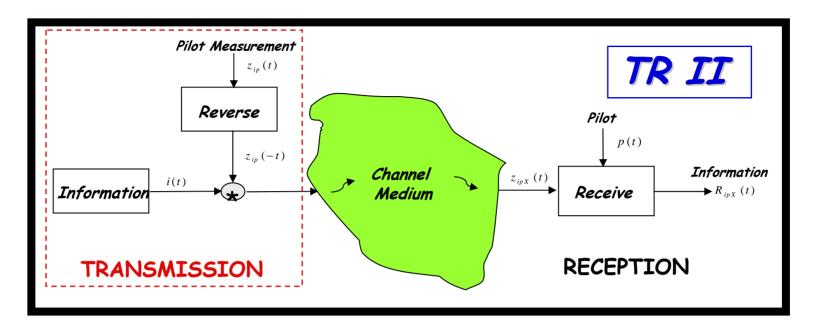


$$R(t) = \hat{g}(r; -t) * [g(r; t) * i(t)] = [\hat{g}(r; -t) * g(r; t)] * i(t) = C_{g\hat{g}}(r; t) * i(t) \approx i(t)$$

We have implemented two versions of TR receivers on transmission:



- 1. Receiver *j* sends pilot to transmitter
- 2. Transmitter estimates Green's function: $\hat{g}_{i}(t)$
- 3. Transmitter sends $\hat{g}_{j}(-t) * I(t)$
- 4. Receiver j records $g_j(t) * \hat{g}_j(-t) * I(t) = \hat{C}_{jj}(t) * I(t) \approx I(t)$ Receiver k records $g_k(t) * \hat{g}_j(-t) * I(t) = \hat{C}_{jk}(t) * I(t) \neq I(t)$



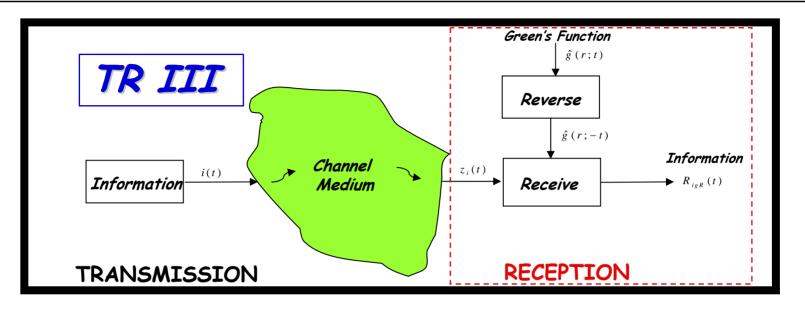
- 1. Receiver *j* sends pilot p(t) to transmitter, $p(t) * p(-t) = C_{pp}(t) \approx \delta(t)$
- 2. Transmitter receives $z_{jp}(t) = p(t) * g_j(t)$
- 3. Transmitter sends $z_{in}(-t) * I(t)$
- 4. Receiver *j* records signal and convolves it with pilot

$$p(t) * g_{i}(t) * z_{ip}(-t) * I(t) = C_{pp}(t) * C_{ii}(t) * I(t) \approx I(t)$$

Receiver k produces

$$p(t) * g_k(t) * z_{ip}(-t) * I(t) = C_{pp}(t) * C_{ik}(t) * I(t) \neq I(t)$$

... and we have implemented 2 TR receiver versions on reception:

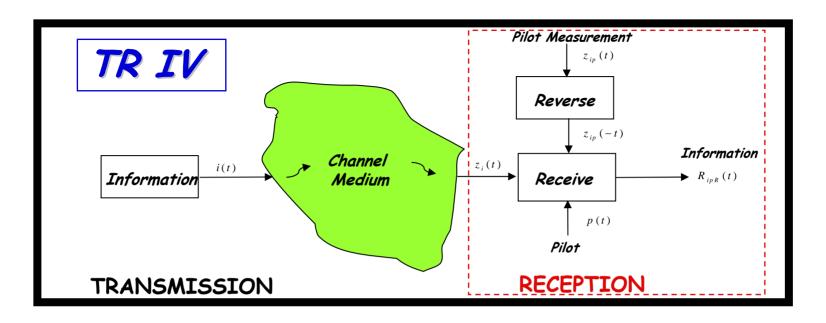


- 1. Transmitter sends pilot p(t)
- 2. Receiver j records $p(t) * g_j(t)$ and estimates Green's function $\hat{g}_j(t)$
- 3. Transmitter sends *I(t)*
- 4. Receiver j records signal and convolves it with $\hat{g}_{j}(-t)$

$$\hat{g}_{i}(-t) * g_{i}(t) * I(t) = \hat{C}_{ii}(t) * I(t) \approx I(t)$$

Receiver k does the same:

$$\hat{g}_{k}(-t) * g_{k}(t) * I(t) = \hat{C}_{kk}(t) * I(t) \approx I(t)$$



- 1. Transmitter sends pilot p(t), $p(t) * p(-t) = C_{pp}(t) \approx \delta(t)$
- 2. Receiver j records $z_{jp}(t) = p(t) * g_{j}(t)$
- 3. Transmitter sends p(t) * I(t)
- 4. Receiver j records signal and convolves it with $z_i(-t)$

$$z_{jp}(-t) * g_{j}(t) * p(t) * I(t) = C_{jj}(t) * C_{pp}(t) * I(t) \approx I(t)$$

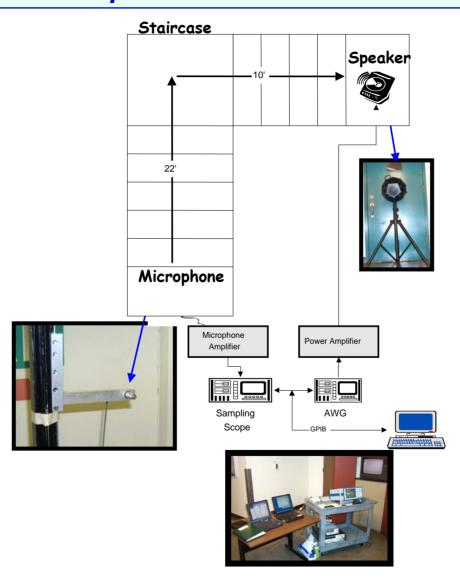
Receiver k does the same:

$$z_{kp}(-t) * g_k(t) * p(t) * I(t) = C_{kk}(t) * C_{pp}(t) * I(t) \approx I(t)$$

Summary of TR receiver types

	TR Green's function g	TR g*pilot
Transmission (focused)	Type I	Type II
Reception (broadcast)	Type III	Type IV

We developed a P2P ACOUSTICS experiment in a hostile, highly reverberant free space environment to evaluate the T/R receiver:



The experiment was accomplished with:

· SOURCE/AMP: B&K 4296/2716 20dB

· PILOT/CODE: Analogic 2020 arbitrary waveform generator

· MICROPHONE: B&K 2716

· DIGITIZER: LeCroy 8-bit

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• PILOT: Chirp pulse swept from 0.1-2KHz

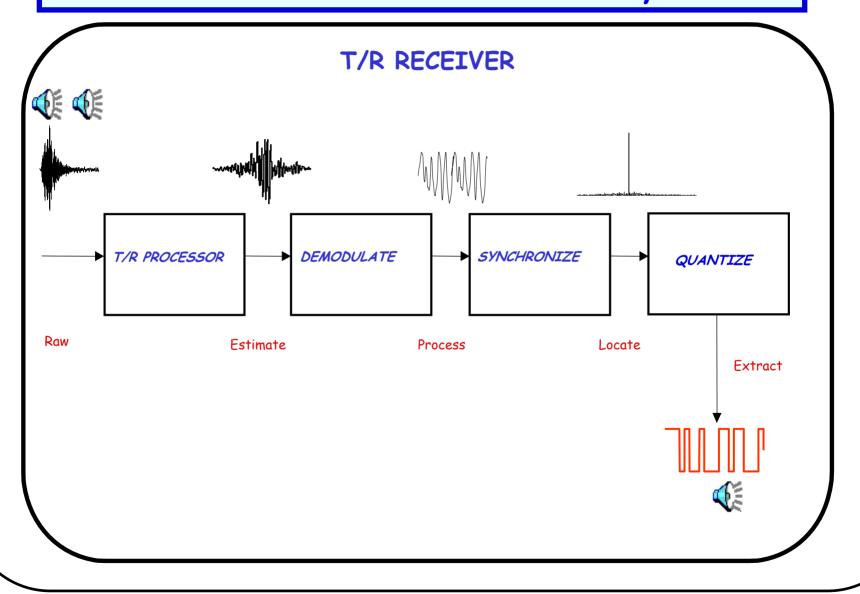
· CODE: BPSK 0.1KHz BW

· MODULATION: AM center frequency at 1.207KHz

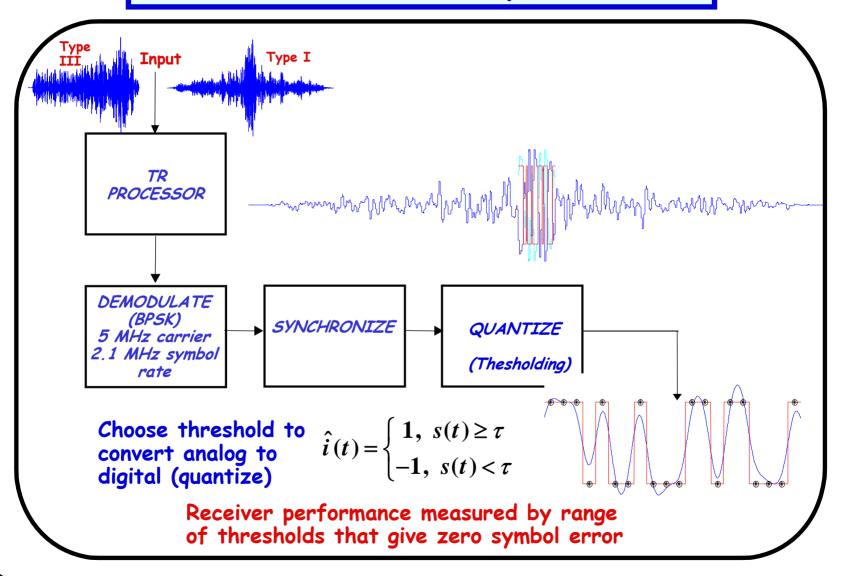
· SAMPLING FREQUENCY: 10KHz

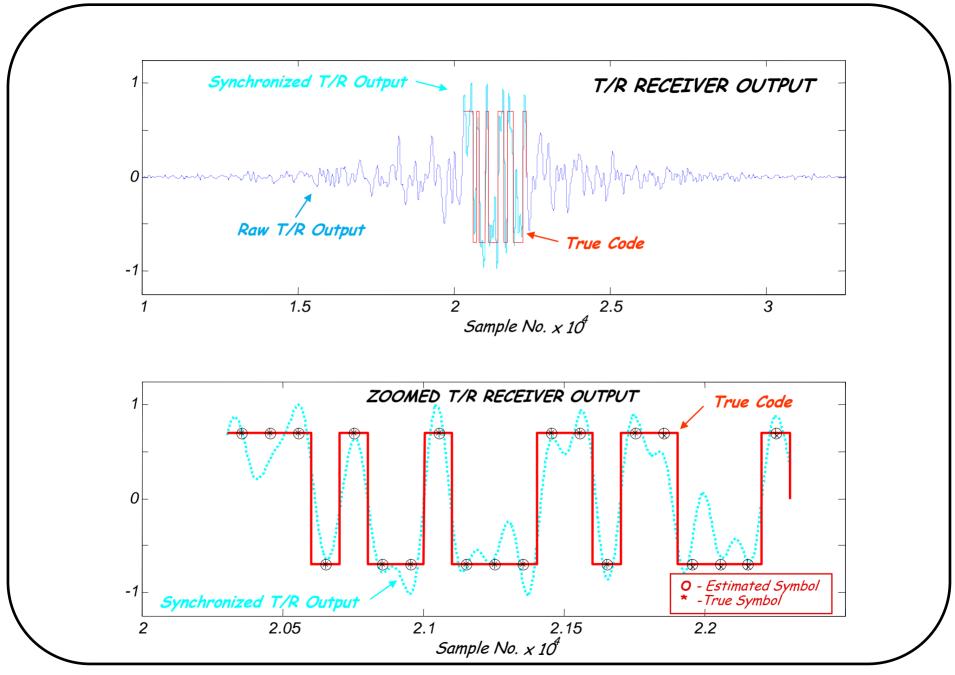
SYMBOL/BIT RATE: 100 samples/symbol

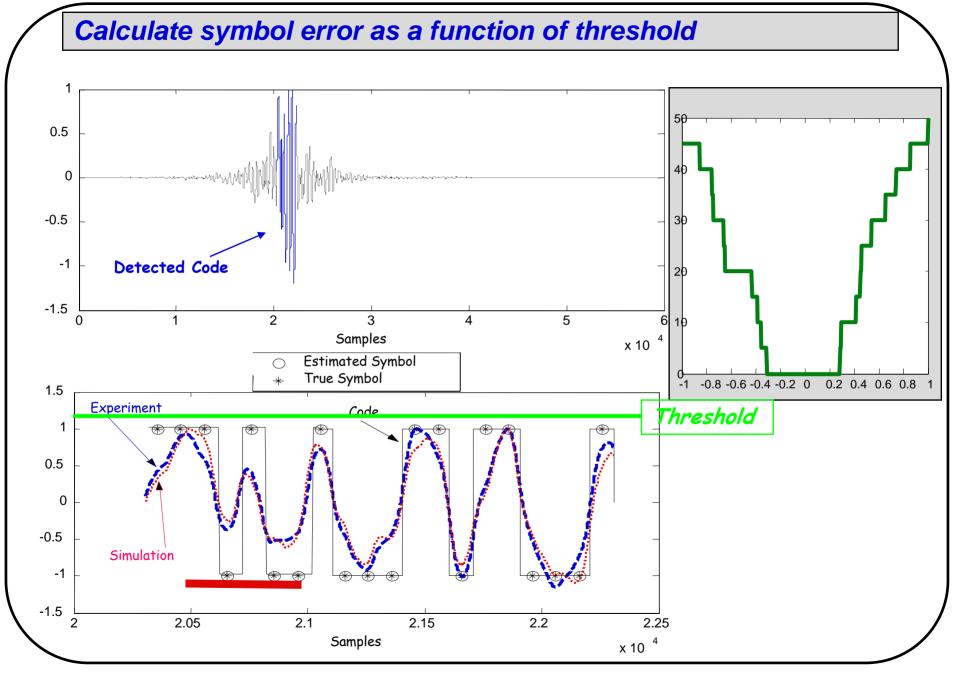
T/R acoustic receiver for stairwell experiment



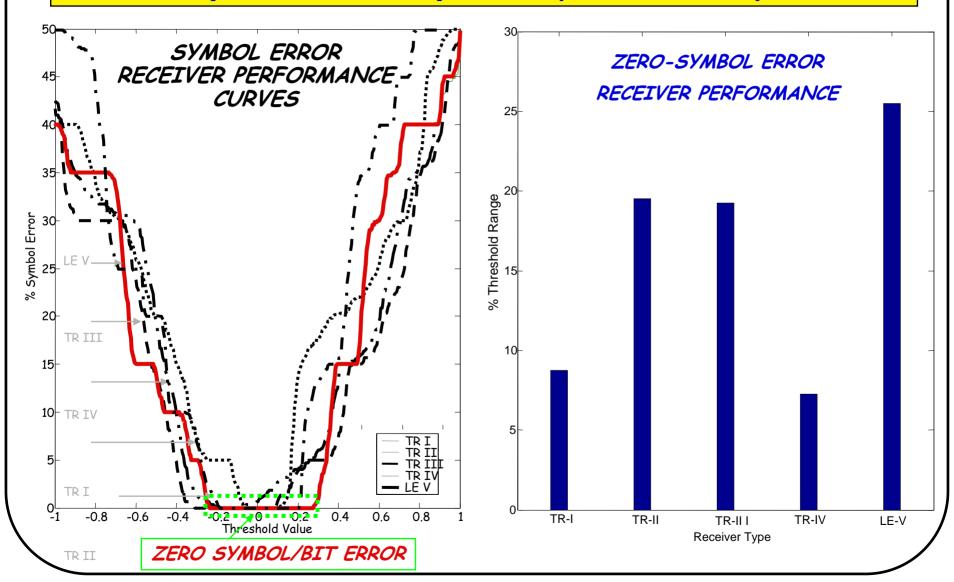
TR acoustic receiver implementation







TR acoustic receiver performance compares favorably with the optimal linear equalizer (inverse filter)

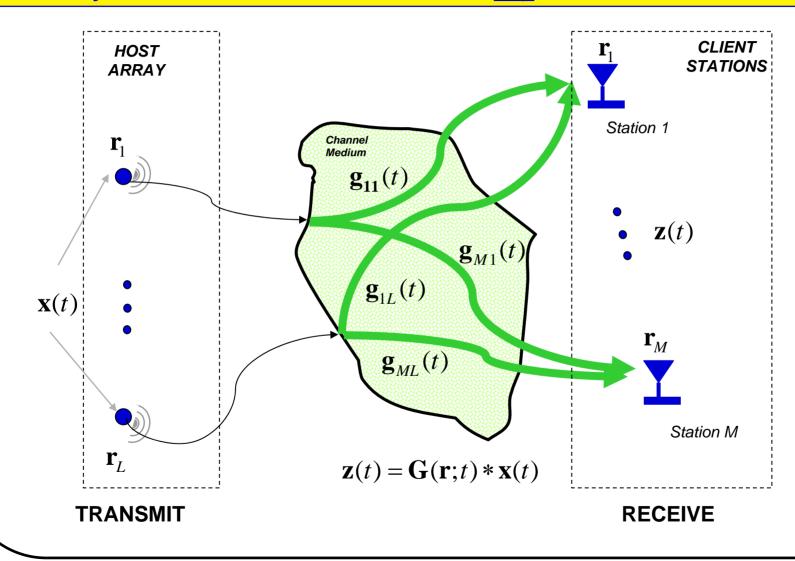


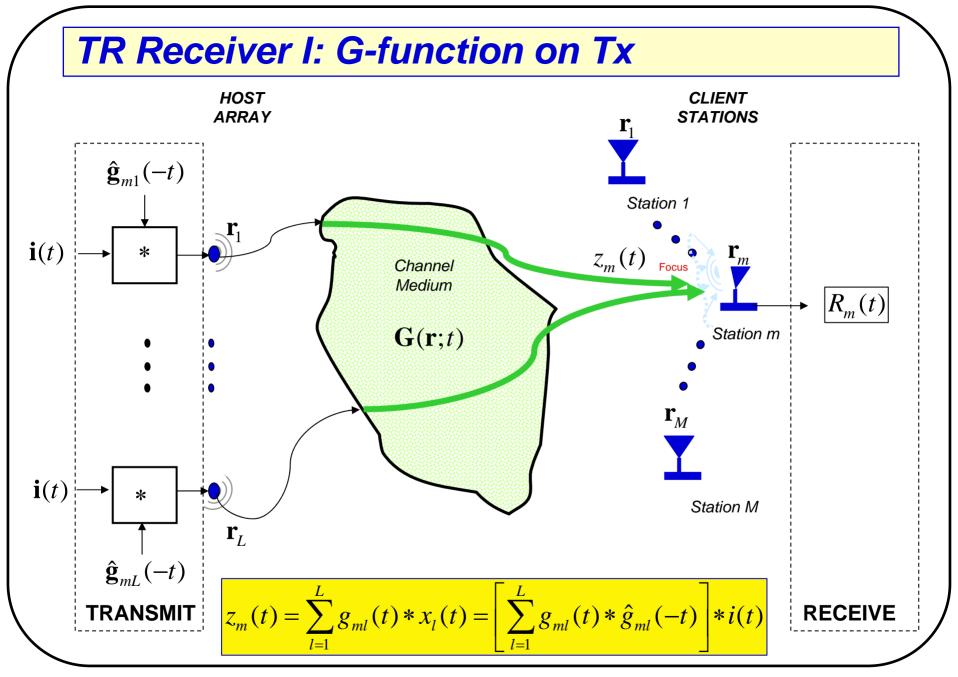
Summary of P2P results:

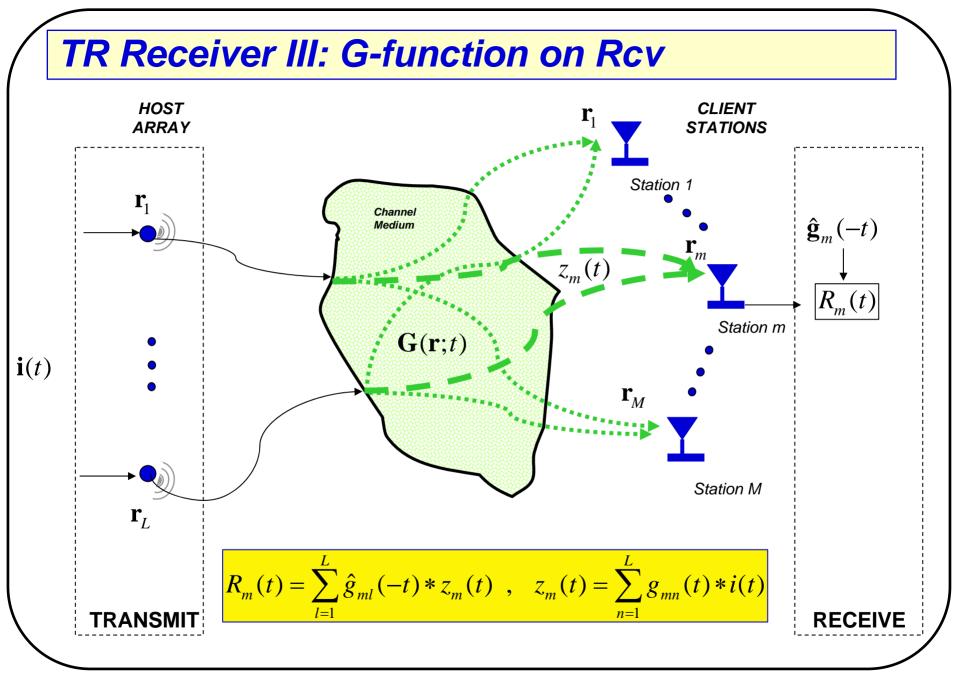
- We have discussed the idea of communications in a hostile environment using time-reversal processing with multi-channel (intelligent array) signal processing
- We have discussed the approach using theory and experiment to evaluate the performance of 4 TR receiver realizations
- We have evaluated receiver performance using a set of metrics based on symbol error. Performance compares favorably with more complex linear equalization (inverse filter).

TIME-REVERSAL ARRAY-TO-ARRAY (A2A) RECEIVERS

The medium (Green's function) provides UNIQUE paths (channels) from the host array to each client station---this is the key in TR communications







ANALYSIS of TR Receiver Operation

TR Receiver I: focus at receiver m, calculate response at receiver k

$$\left| \hat{C}_{nl}^{km}(t) \equiv g_{kn}(t) * \hat{g}_{ml}(-t) \approx \delta_{km} \delta_{nl} \delta(t) \right|$$
 (for high multipath)

TR Receiver III:

$$R_{m}(t) = \sum_{l=1}^{L} \hat{g}_{ml}(-t) * z_{m}(t) = \left[\sum_{l=1}^{L} \sum_{n=1}^{L} \hat{g}_{ml}(-t) * g_{mn}(t)\right] * i(t) = \left[\sum_{l=1}^{L} \sum_{n=1}^{L} \hat{C}_{nl}^{km}(t)\right] * i(t)$$

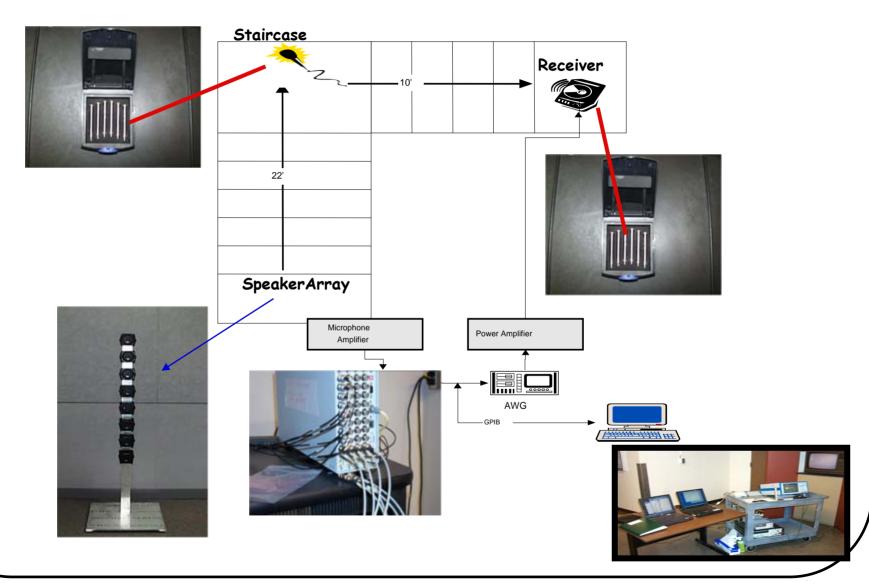
$$= \left[\sum_{l=1}^{L} \hat{C}_{ll}^{mm}(t)\right] * i(t) + \left[\sum_{\substack{l,n=1\\l\neq n}}^{L} \hat{C}_{nl}^{mm}(t)\right] * i(t)$$

$$\approx L \ i(t) + "noise"$$

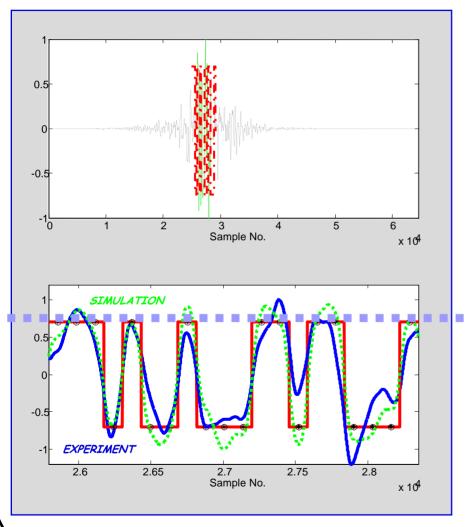
(TR I result)

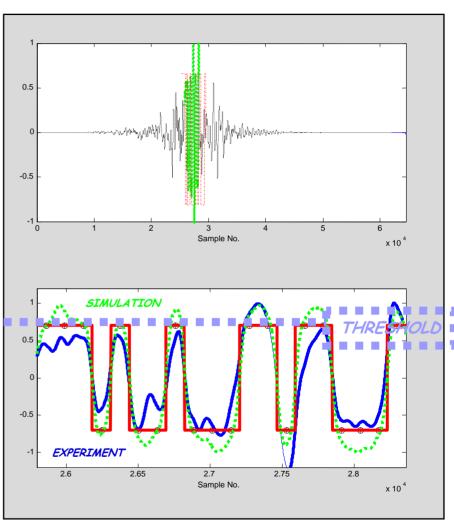
Outputs of active (I) and passive (III) receivers are not equivalent

We developed A2P ACOUSTICS experiment in a hostile, highly reverberant free space environment to evaluate the T/R receiver:

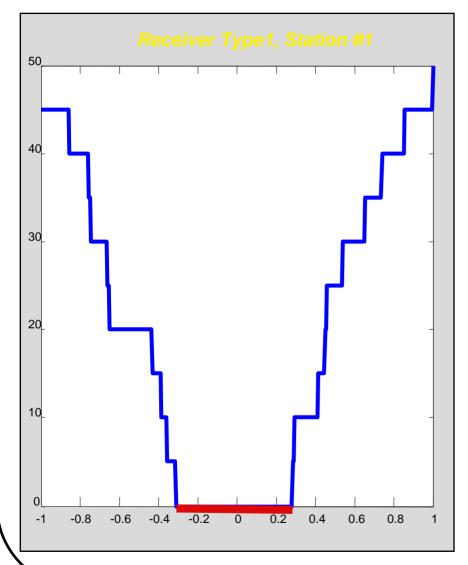


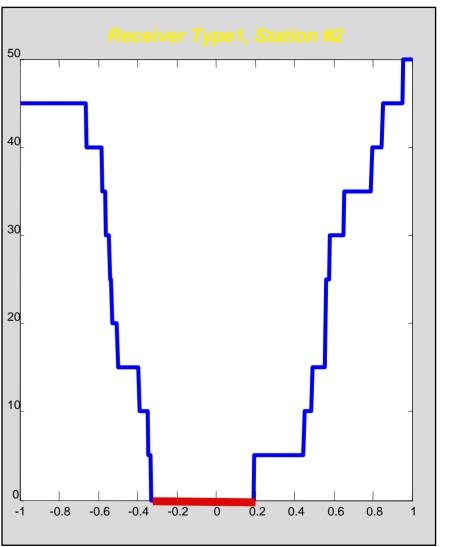
TR RECEIVER I: Focuses on Each Client



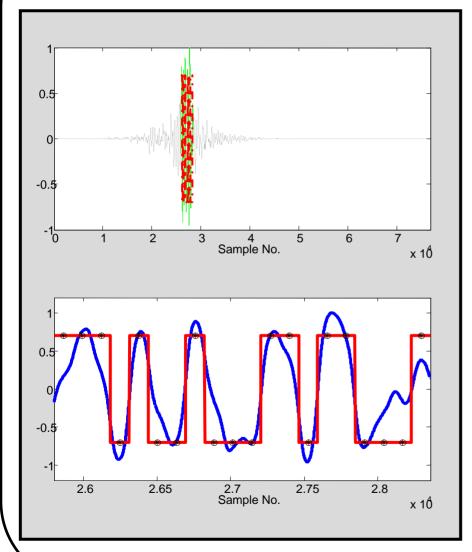


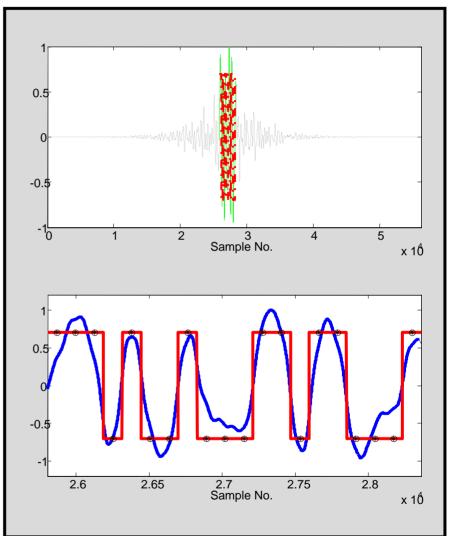
TR Receiver I: Performance



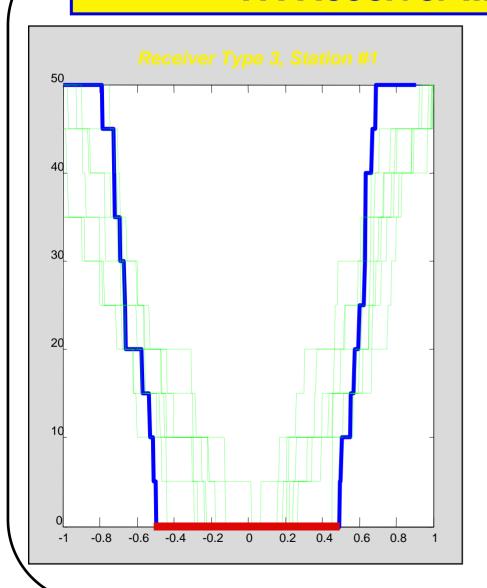


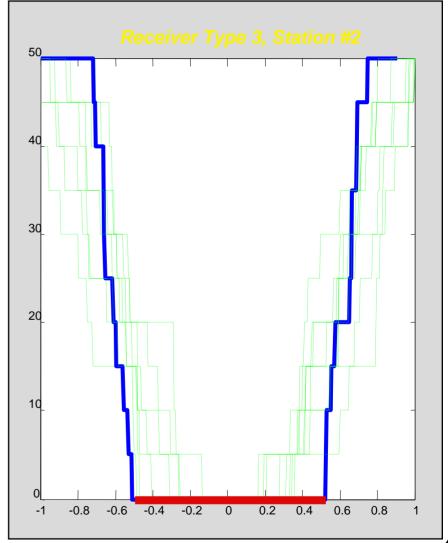
TR RECEIVER III: Focus on Client Receiver



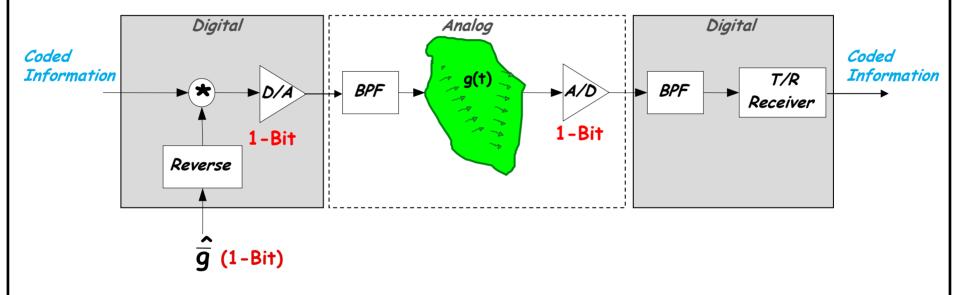


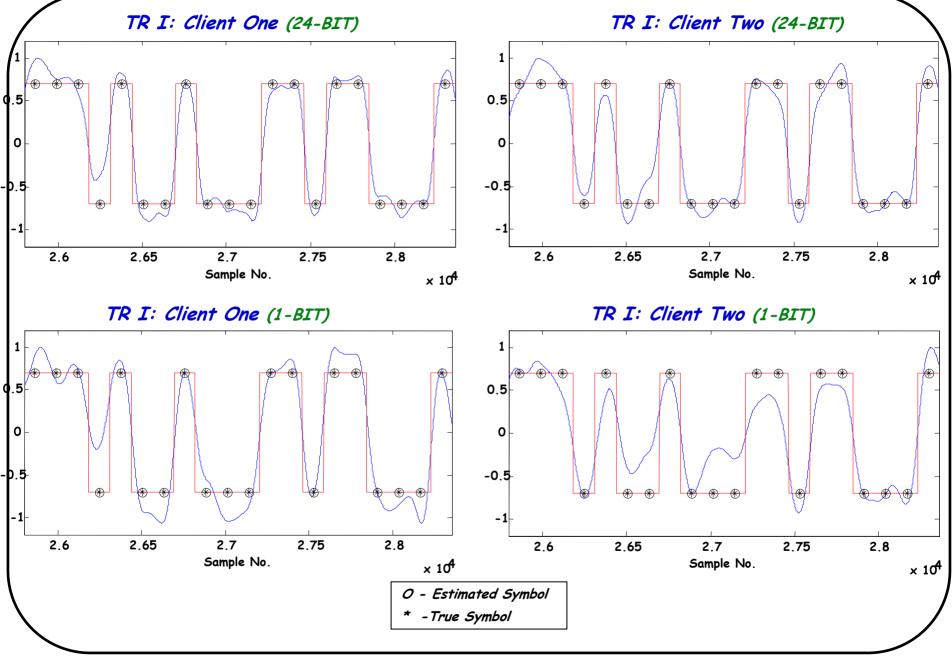
TR Receiver III: Performance





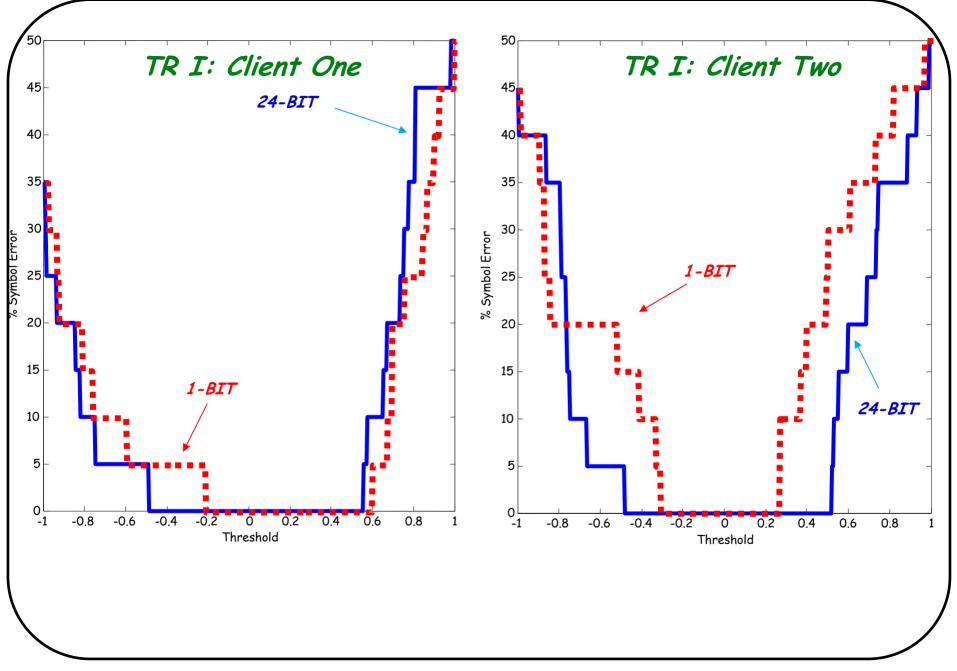
TR I realization in a 1-bit implementation



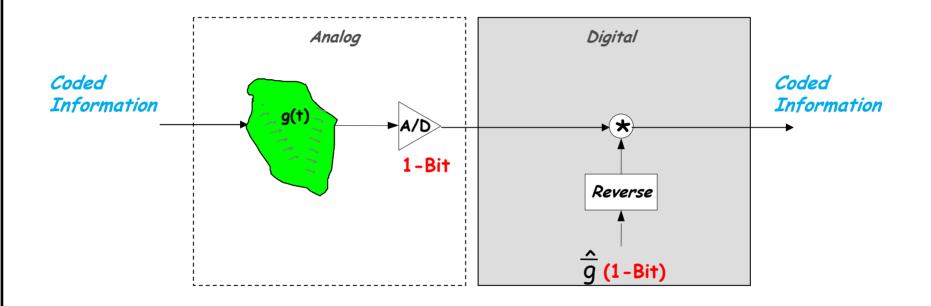


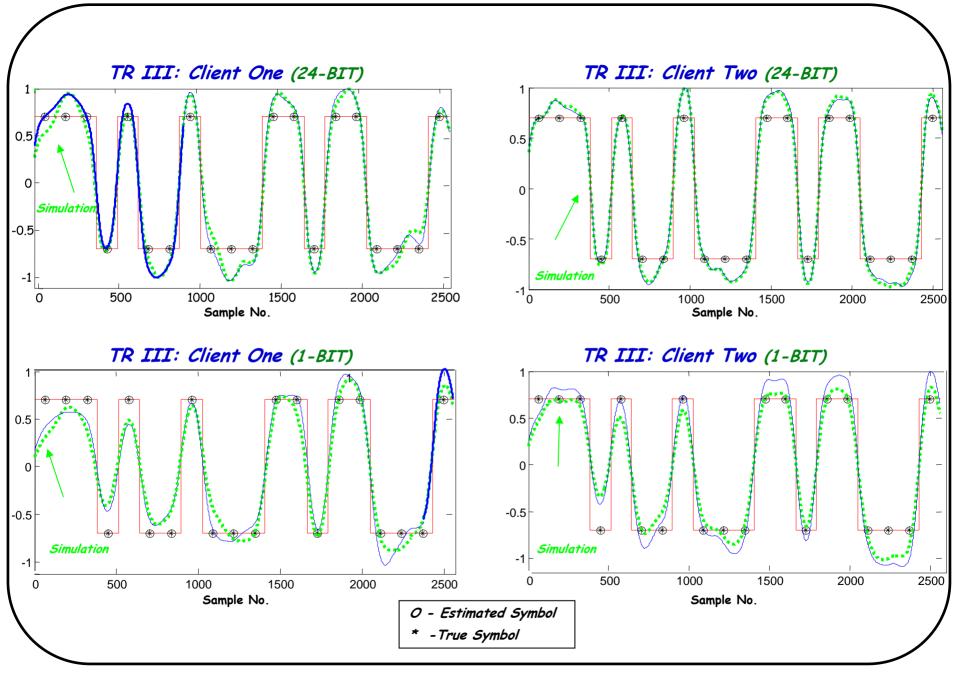
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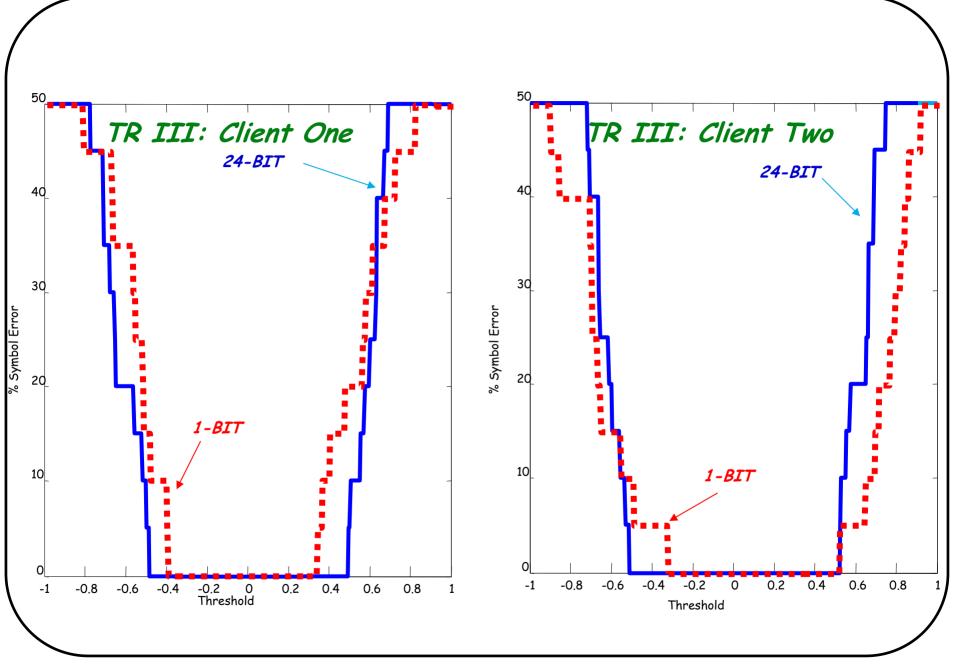
TR III realization in a 1-bit implementation





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Proof-of-principle experiments have shown great results!

- standard receivers try to "ignore" multipath by using only direct path information (time gating)
- · arrays have been recently introduced into comms area, but not intelligent (learn Green's function) T/R arrays

 BUT
- we have shown for <u>array-to-point</u> (A2P) communications the concept of a time-reversal (T/R) receiver is <u>capable</u> of operating successfully in a highly reverberative environment

Summary for A2A realizations:

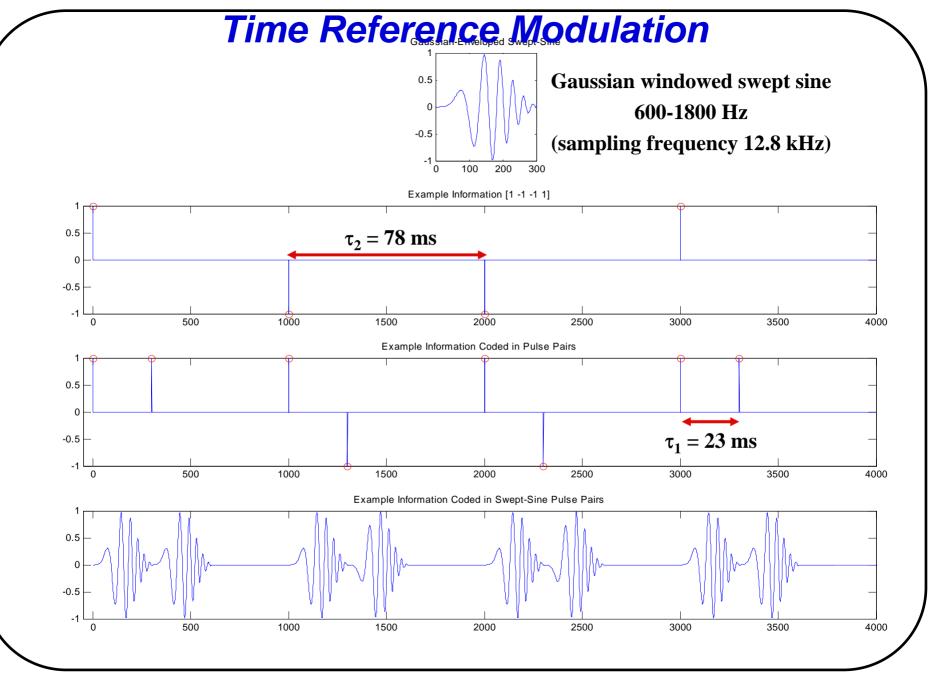
- We have generalized the idea of P2P TR communications to an A2A configuration.
- We have discussed the approach using theory, simulation, and experiment to evaluate the performance of T/R receiver realizations
- We have shown improved performance using a host array over the P2P results.
- We have shown a "1-bit" realization of a TR receiver.

WIDEBAND TIME-REVERSAL RECEIVERS

Synchronization & demodulation create a significant problem for carrier-based NB receivers (collaborating with MIR people)

To improve our performance we:

- decided on a wide-band design (F_{BW}=BW/F_C>20%;F^{TR}>50%)
- chose to use a "time-reference" (XR) synchronization and modulation/demodulation scheme (2 pulses/bit; polarity check)
- performed experiments in the tunnel-like (cave) of B194 demonstrating the capability



Time Reference Demodulation

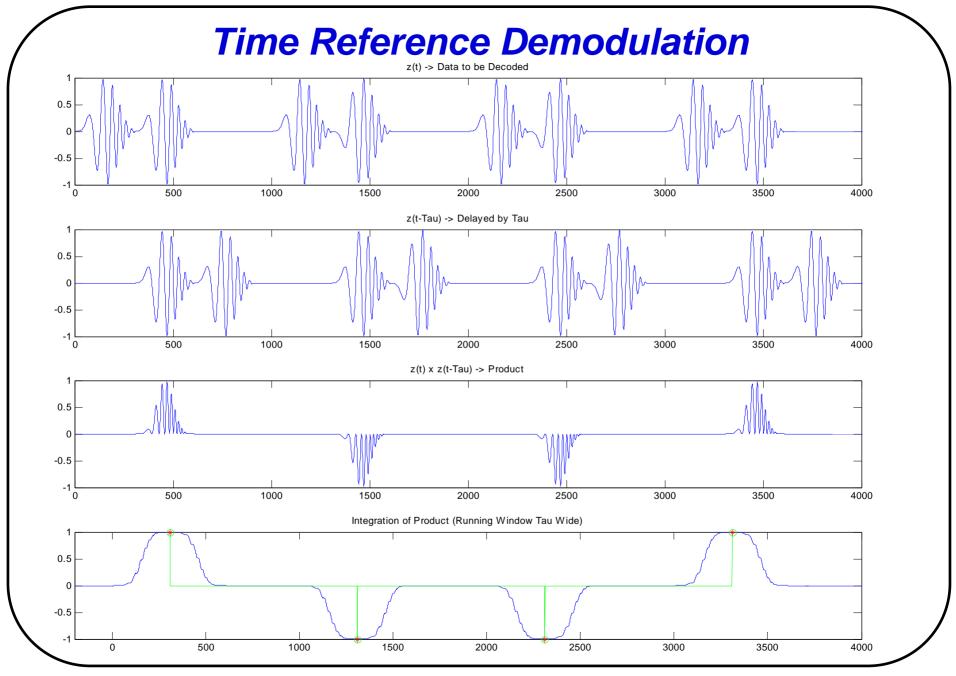
$$z(t) = g(r,t) * i(t) \xrightarrow{} \\ & \downarrow \\ &$$

$$R_{zz}(t) = [g(r,t) * i(t)] * [g(r, \tau_2-t) * i(\tau_2-t)]$$

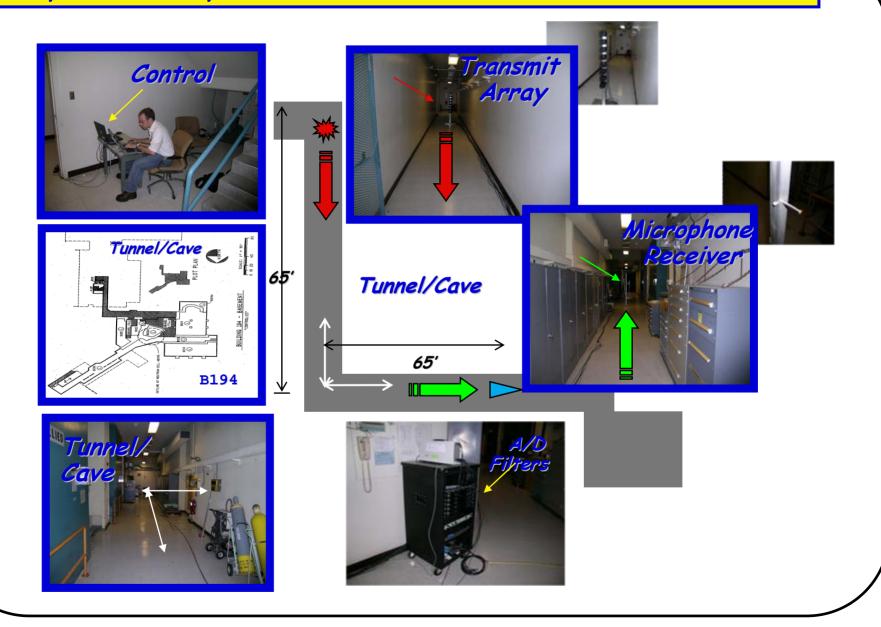
$$R_{zz}(t) = [g(r,t) * g(r, \tau_2-t)] * [i(r,t) * i(\tau_2-t)]$$

$$R_{zz}(t) = R_{gg}(\tau_2 - t) * R_{ii}(\tau_2 - t)$$

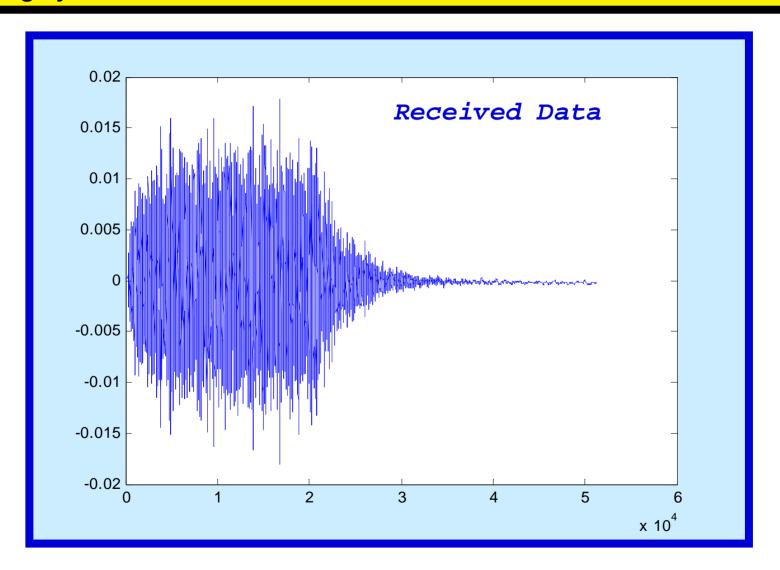
 \therefore R_{zz} a maximum at t = τ_2



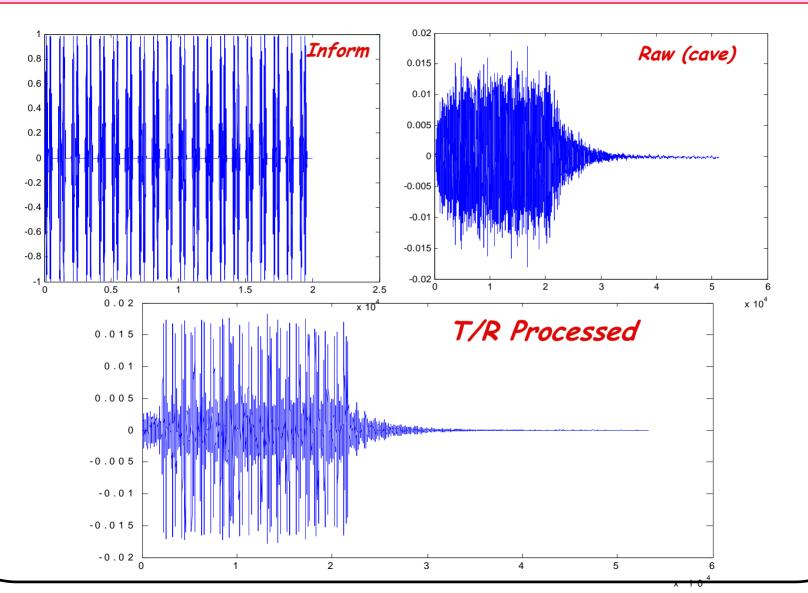
We performed experiments in a hostile tunnel/cave environment



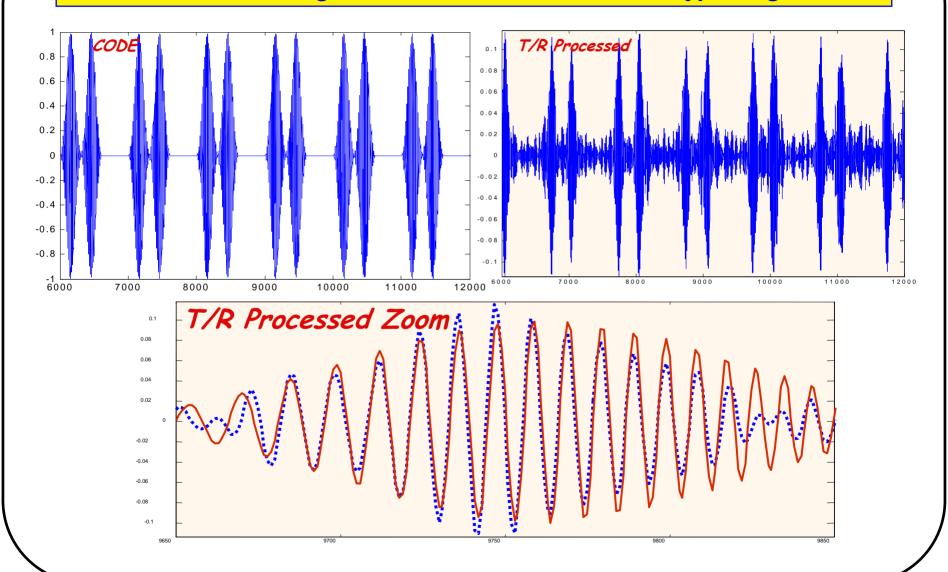
The raw transmitter-reference (XR) information is broadcast in the highly reverberant tunnel-like environment

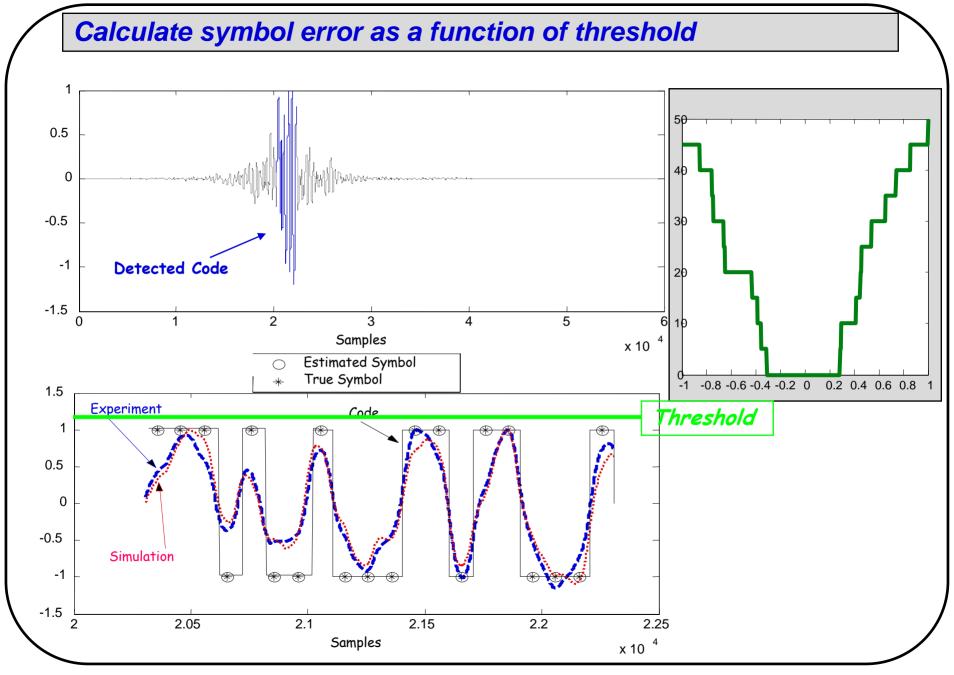


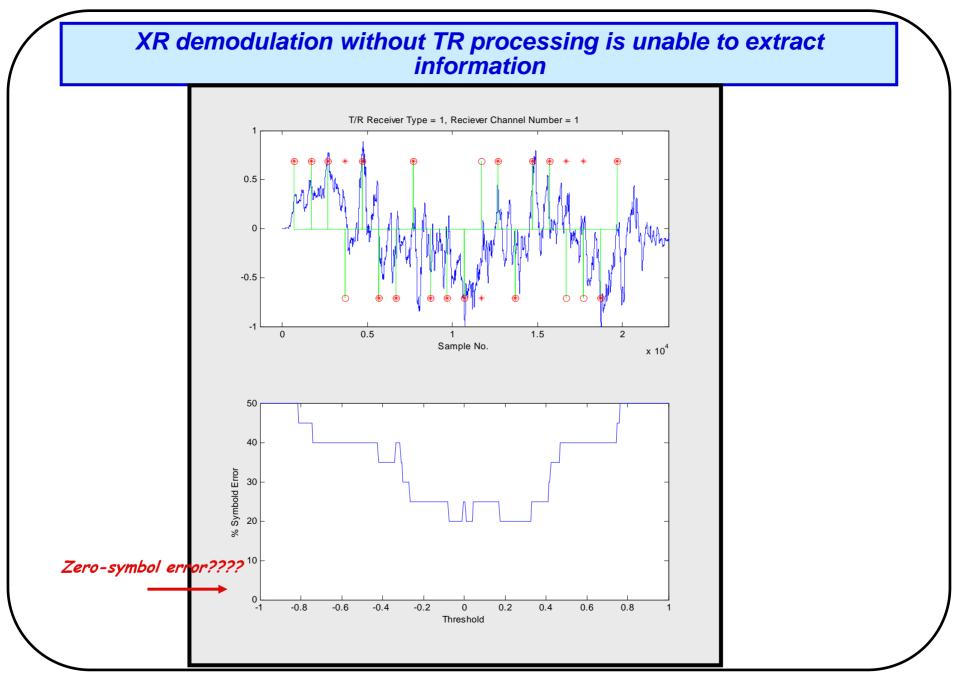
Compare the original information signal with the T/R received Type III signal

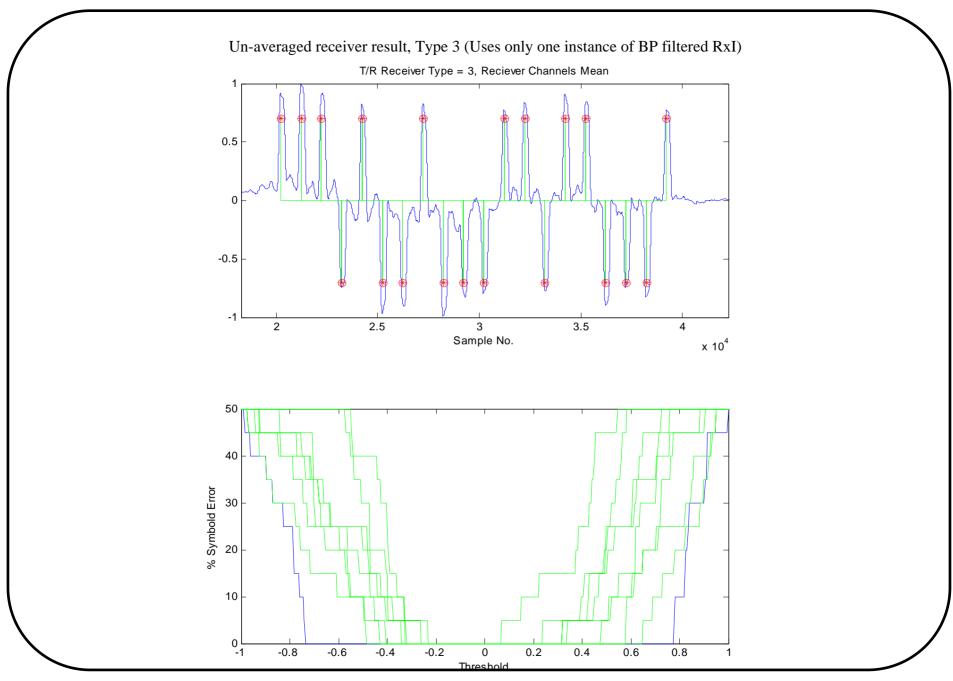


A zoom of the original information and received Type I signals









Summary for wideband implementation:

- Showed the time-reversal can be implemented for wideband systems
- Time-reversal approach is compatible with a carrier-less modulation scheme
- Experiment in a tunnel-like environment shows array gain

Conclusion

- TR communications schemes can be implemented either on transmit (active) or receive (passive)
- Performance approaches the ideal linear equalizer (inverse filter) for point-to-point implementation
- Performance improves for array-to-point implementation
- Receiver performs well even when signal range is restricted to 1bit
- TR approach is compatible with wideband, carrier-less communications