Application of time-reversal methods to communication in hostile environments

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COMMUNICATION PROBLEM COMMUNICATION PROBLEM

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PROBLEM:

Transmit information in a hostile medium (mpath,mscatterers,reverb,noise) and extract it with minimal symbol/bit error APPROACH:

Time reversal (TR) communication system

TR communication systems can:

- **mitigate multipath, multiple scattering, inhomogeneous effects**
- **focus signal energy at a client station through a hostile medium**
- **provide a secure link (unique medium function) from host-to-client**
- **be deployed in point-to-point (P2P) or array configurations (A2P,A2A)**
- **compliment existing communications technology**
- •**be implemented in software**
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TR offers an alternate solution to the communications problem in hostile environments

TIME-REVERSAL

What is time reversal wave propagation?

- **Time reversal techniques exploit the symmetry of wave propagation to the direction of time (time invariance, reciprocity) to enhance focusing, imaging, and target characterization**
- • **Experimentalist: A simple technique for focusing energy on a target through an uncharacterized or complicated media**
- • **Signal processor: A hardware implementation of a broadband spatio-temporal matched filter for multi-channel array data (minimal calculation)**
- \bullet **Applied mathematician: A symmetry of propagation and scattering useful for understanding scattering in difficult media and designing inversion and imaging methods ==> target characterization**

Operation of a time reversal array (mirror) for a single source

Pulse recorded

Time reversal allows focusing through complicated media (experiment by Derode, Roux, and Fink; PRL 1995)

Time reversal as a spatio-temporal matched filter (1)

•**Simple matched filter**

> **Given data u(t) = s(t) + n(t); s(t): signal, n(t): white noise Determine filter h(t) so that y(t) = h(t)*u(t) has maximum SNR at time T:**

$$
SNR(T) = \frac{\left|\int_0^T h(t^*)s(T-t^*)dt\right|^2}{\sigma^2 \int_0^T \left|h(t^*)\right|^2 dt^{\prime}}
$$
 σ : noise variance

Answer is h(t) = s(T-t); time-reversed version of signal

•**Generalization to multi-channel data u n(t) gives MMSE beamformer**

Time reversal as a spatio-temporal matched filter (2)

•**Spatio-temporal matched filter**

> **Given an array with elements at positions** *a ⁿ***:** *n= 1,2,…,N* **Determine excitations** *En(t)* **that maximize SNR of the transmitted field at time** *T* **AND position** *x0*

 $\frac{N}{\sqrt{2}}$ *et* $\psi(x,t) = \sum_{n=1}^{N} \int_0^t G(x,a_n,t-t')E_n(t')dt'$ Field at x and t
generated by array *a1* $(x,t) = \sum_{n=1}^{n} \int_0^t G(x, a_n, t-t') E_n(t') dt'$ *na 2*=*x0 G(x,t;a n,t) Green's function (impulse response) a 3*2 $\frac{N}{\sqrt{1}}$ \mathbf{r} ∑ ∫ \blacksquare $G(x_0, a_0, T-t')E_0(t')dt$ $(x_0, a_n, T-t')E_n(t')dt'$ − $\mathcal{L}_0(T) = \frac{\left|\sum_{n=1}^{T} \int_0^{\infty} \zeta x_0 \zeta x_n, T(T) \right|}{\sum_{n=1}^{N} \int_0^T |F_n(z_n)|^2}$ $\frac{N}{n-1}$ **b** $\frac{N}{n}$ **c**^T₁ ¹ \blacksquare $SNR(x_0, T)$ (x_{0},T) = = ∑ ∫ $E_{r}(t')$ ^{\sim} dt $(t')\vert^{\sim} dt'$ *a Nn* $\frac{1}{1}$ J 0 *n*=

> Answer is $E_n(t) = G(x_o, a_n, T-t)$: time-reversed Green's function $(x,t) = \sum_{n=1}^{\infty} \int_0^{\infty} G(x, a_n, t-t') G(x_0, a_n, T-t') dt'$ 1 $\frac{N}{\sqrt{2}}$ م $\psi_{MF}(x,t) = \sum_{n=1}^{t} \int_0^t G(x,a_n,t-t')G(x_0,a_n,T-t')dt$ *n*=

TIME-REVERSAL POINT REVERSAL POINT-TO -POINT (P2P) RECEIVERS (P2P) RECEIVERS

A TR communication system is an intelligent, *optimal***, space-time, matched-filter that "learns" the medium**

The medium (Green's function) provides UNIQUE paths (channels) from each client station to the host sensor---this is the key in T/R communications

TR signal processing can be applied at either the transmitter or receiver:

 $R(t) = g(r; t) * [\hat{g}(r; -t) * i(t)] = [g(r; t) * \hat{g}(r; -t)] * i(t) = C_{g\hat{g}}(r; t) * i(t) \approx i(t)$

We have implemented two versions of TR receivers on transmission :

- **1. Receiver** *j* **sends pilot to transmitter**
- 2. Transmitter estimates Green's function: $\hat{\boldsymbol{g}}_j(t)$
- 3. Transmitter sends $\hat{\boldsymbol{g}}_j(-t) \ast I(t)$
- **4.** Receiver j records $\left\{ g_{\;i}(t)\ast\hat{g}_{\;i}(-t)\ast I(t)\!=\!\hat{C}\right\}$ $g_j(t) * \hat{g}_j(-t) * I(t) = C_{jj}(t) * I(t) \approx I(t)$ **ˆ**

Receiver *k* **records** $g_k(t) * \hat{g}_j(-t) * I(t) = C_{jk}(t) * I(t) \neq I(t)$

- 1. Receiver j sends pilot $\bm{p(t)}$ to transmitter, $\ \ \bm{p(t)} * \bm{p(-t)} = \bm{C}_{pp}(t) \approx \bm{\delta(t)}$
- **2. Transmitter receives** $z_{jp}(t) = p(t)*g_{j}(t)$
- **3. Transmitter sends** $z_{jp}(-t) * I(t)$
- **4. Receiver** *j* **records signal and convolves it with pilot**

$$
p(t) * g_j(t) * z_{jp}(-t) * I(t) = C_{pp}(t) * C_{jj}(t) * I(t) \approx I(t)
$$

Receiver *k* **produces**

$$
p(t) * g_{k}(t) * z_{jp}(-t) * I(t) = C_{pp}(t) * C_{jk}(t) * I(t) \neq I(t)
$$

… and we have implemented 2 TR receiver versions on reception :

- **1. Transmitter sends pilot** *p(t)*
- 2. Receiver *j* records $p(t)*g_{_f}(t)$ and estimates Green's function $\hat{\boldsymbol{g}}_{_f}(t)$
- **3. Transmitter sends** *I(t)*
- **4.** Receiver j records signal and convolves it with $\hat{\boldsymbol{g}}_j(-t)$

$$
\hat{g}_j(-t) * g_j(t) * I(t) = \hat{C}_{jj}(t) * I(t) \approx I(t)
$$

Receiver *k* **does the same:**

$$
\hat{g}_k(-t) * g_k(t) * I(t) = \hat{C}_{kk}(t) * I(t) \approx I(t)
$$

- 1. Transmitter sends pilot $\bm{p(t),} \;\; p(t) * p(-t)$ = $\bm{C}_{pp}(t) \approx \delta(t)$
- **2. Receiver** *j* **records** $z_{jp}(t) = p(t)*g_{j}(t)$
- **3. Transmitter sends** $p(t)*I(t)$
- 4. Receiver *j* records signal and convolves it with $z_j(-t)$

$$
z_{jp}(-t) * g_j(t) * p(t) * I(t) = C_{jj}(t) * C_{pp}(t) * I(t) \approx I(t)
$$

Receiver *k* **does the same:**

$$
z_{kp}(-t) * g_k(t) * p(t) * I(t) = C_{kk}(t) * C_{pp}(t) * I(t) \approx I(t)
$$

We developed a P2P ACOUSTICS experiment in a hostile, highly reverberant free space environment to evaluate the T/R receiver:

The experiment was accomplished with:

- **SOURCE/AMP: B&K 4296/2716 20dB**
- **PILOT/CODE: Analogic 2020 arbitrary waveform generator**
- **MICROPHONE: B&K 2716**
- **DIGITIZER: LeCroy 8-bit**

· PILOT: **Chirp pulse swept from 0.1-2KHz**

•**---**

- CODE: **CODE: BPSK 0.1KHz BW**
- **MODULATION: AM center frequency at 1.207KHz**
- **SAMPLING FREQUENCY: 10KHz**
- **SYMBOL/BIT RATE: 100 samples/symbol**

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TR acoustic receiver implementation

Calculate symbol error as a function of threshold

TR acoustic receiver performance compares favorably with the optimal linear equalizer (inverse filter)

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Summary of P2P results:

- • **We have discussed the idea of communications in a hostile environment using** *time-reversal processing* **with** *multi-channel* **(intelligent array)** *signal processing*
- • **We have discussed the approach using theory and experiment to evaluate the performance of 4 TR receiver realizations**
- • **We have evaluated receiver performance using a set of metrics based on symbol error. Performance compares favorably with more complex linear equalization (inverse filter).**

TIME-REVERSAL ARRAY REVERSAL ARRAY-TO -ARRAY (A2A) RECEIVERS (A2A) RECEIVERS

The medium (Green's function) provides UNIQUE paths (channels) from the host array to each client station---this is the key in TR communications

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TR Receiver III: G-function on Rcv

ANALYSIS of TR Receiver Operation

TR Receiver I: focus at receiver m, calculate response at receiver k

$$
z_{\scriptscriptstyle k}(t)\!=\!\!\left[\textstyle\sum\limits_{\scriptscriptstyle l=1}^{\scriptscriptstyle L}g_{\scriptscriptstyle kl}(t)\!*\!\hat{g}_{\scriptscriptstyle ml}(-t)\right]\!*\!i(t)\!=\!\!\left[\textstyle\sum\limits_{\scriptscriptstyle l=1}^{\scriptscriptstyle L}\hat{C}_{\scriptscriptstyle ll}^{\scriptscriptstyle km}(t)\right]\!*\!i(t)\!\approx L\delta_{\scriptscriptstyle km}i(t)
$$

$$
\hat{C}_{\frac{ln}{n}}^{km}(t) \equiv g_{\frac{kn}{n}}(t) * \hat{g}_{\frac{ml}{n}}(-t) \approx \delta_{\frac{kn}{n}} \delta_{\frac{nl}{n}} \delta(t)
$$
 (for high multipath)

TR Receiver III:

$$
R_{m}(t) = \sum_{l=1}^{L} \hat{g}_{ml}(-t) * z_{m}(t) = \left[\sum_{l=1}^{L} \sum_{n=1}^{L} \hat{g}_{ml}(-t) * g_{mn}(t) \right] * i(t) = \left[\sum_{l=1}^{L} \sum_{n=1}^{L} \hat{C}_{nl}^{km}(t) \right] * i(t)
$$
\n
$$
= \left[\sum_{l=1}^{L} \hat{C}_{ll}^{mm}(t) \right] * i(t) + \left[\sum_{l=n}^{L} \hat{C}_{nl}^{mm}(t) \right] * i(t)
$$
\n
$$
\approx L \underbrace{i(t) + "noise"}
$$
\n
$$
(TR I result)
$$

Outputs of active (I) and passive (III) receivers are not equivalent

We developed A2P ACOUSTICS experiment in a hostile, highly reverberant free space environment to evaluate the T/R receiver:

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TR RECEIVER I: Focuses on Each Client

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TR Receiver I: Performance

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TR RECEIVER III: Focus on Client Receiver

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TR Receiver III: Performance

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TR I realization in a 1-bit implementation **CodedInformation ˆ g (1-Bit) ***^channell and the second state of the second state state of the second state state state state state (server)
-
--**ReverseAnalog Digital A/D1-Bit BPF BPF T/R ReceiverDigital D/A1-Bit CodedInformation**

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Proof-of-principle experiments have shown great results!

- **standard receivers try to "ignore" multipath by using only direct path information (time gating)**
- **arrays have been recently introduced into comms area, but not intelligent (learn Green's function) T/R arrays**

BUT

 we have shown for array-to-point (A2P) communications the concept of a time-reversal (T/R) receiver is capable of operating successfully in a highly reverberative environment

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WIDEBAND TIME WIDEBAND TIME-REVERSAL REVERSAL $RECEIVERS$

Synchronization & demodulation create a significant problem for carrier-based NB receivers (collaborating with MIR people)

To improve our performance we:

- • \bullet decided on a wide-band design (F_{BW}=BW/F_C>20%;F^{TR}>50%)
- • **chose to use a "time-reference" (XR) synchronization and modulation/demodulation scheme (2 pulses/bit; polarity check)**
- • **performed experiments in the tunnel-like (cave) of B194 demonstrating the capability**

Time Reference Demodulation

Rzz(t) = [g(r,t) * i(t)] * [g(r, τ²-t) * i(τ²-t)] Rzz(t) = [g(r,t) * g(r, τ²-t)] * [i(r,t) * i(τ²-t)] Rzz(t) = Rgg (τ2-t) * Rii(τ2 - t) ∴Rzz a maximum at t = τ2

We performed experiments in a hostile tunnel/cave environment

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The raw transmitter-reference (XR) information is broadcast in the highly reverberant tunnel-like environment

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Compare the original information signal with the T/R received Type III signal

A zoom of the original information and received Type I signals

Calculate symbol error as a function of threshold

XR demodulation without TR processing is unable to extract information

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Conclusion

- • **TR communications schemes can be implemented either on transmit (active) or receive (passive)**
- • **Performance approaches the ideal linear equalizer (inverse filter) for point-to-point implementation**
- •**Performance improves for array-to-point implementation**
- • **Receiver performs well even when signal range is restricted to 1 bit**
- • **TR approach is compatible with wideband, carrier-less communications**