



IEEE-PES meeting

***Modelling of Wind Power Plants***

**R. TOURNIER**

REpower SAS

10th Feb 2010



# Company in brief



Continental  
EU (*Fra,  
Ger, Ita,  
Spa, Por*)

UK

USA & Canada

China &  
Japan

Australia

Employees  
world-wide

1900

Markets

Quoted on S-E  
since

2002

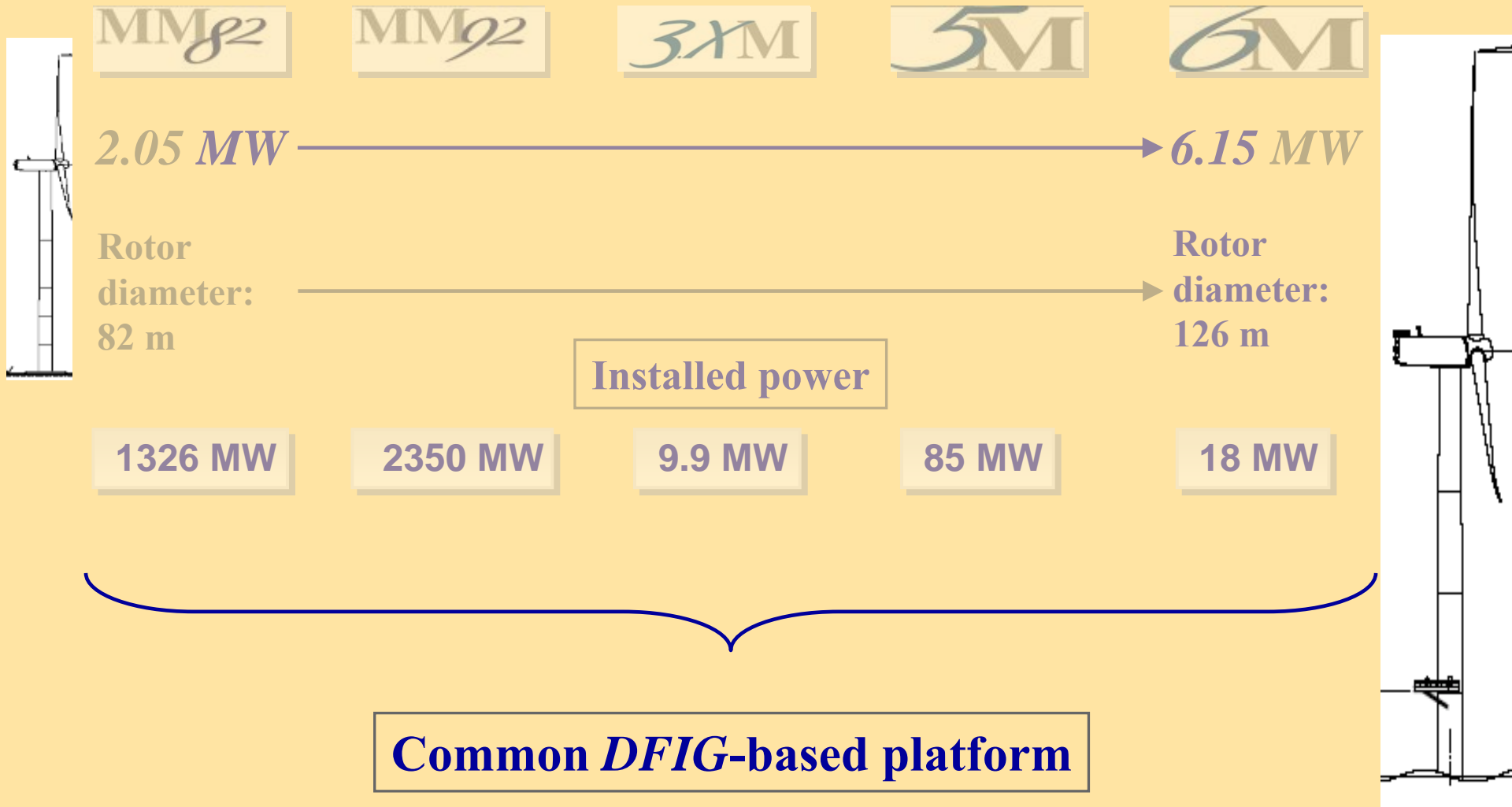
EBIT (FY  
2008-09)

76.9 M€

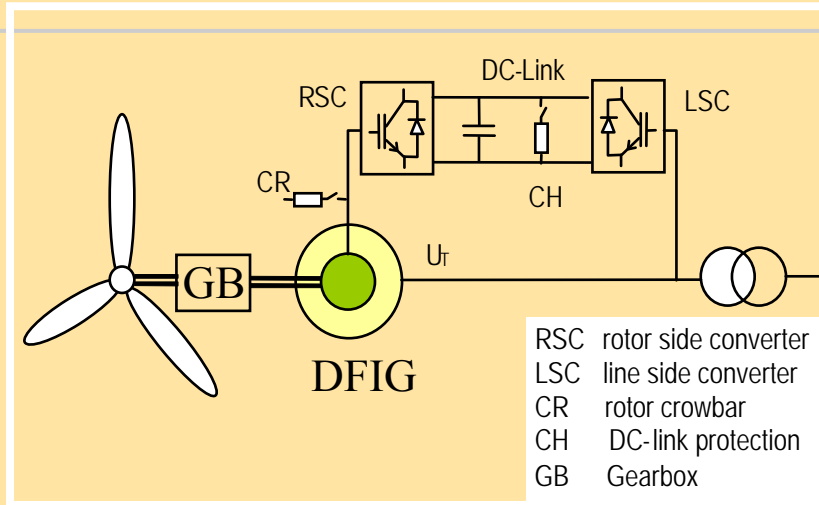
EBIT-Margin  
(expected)

7.5 %

# Company's portfolio

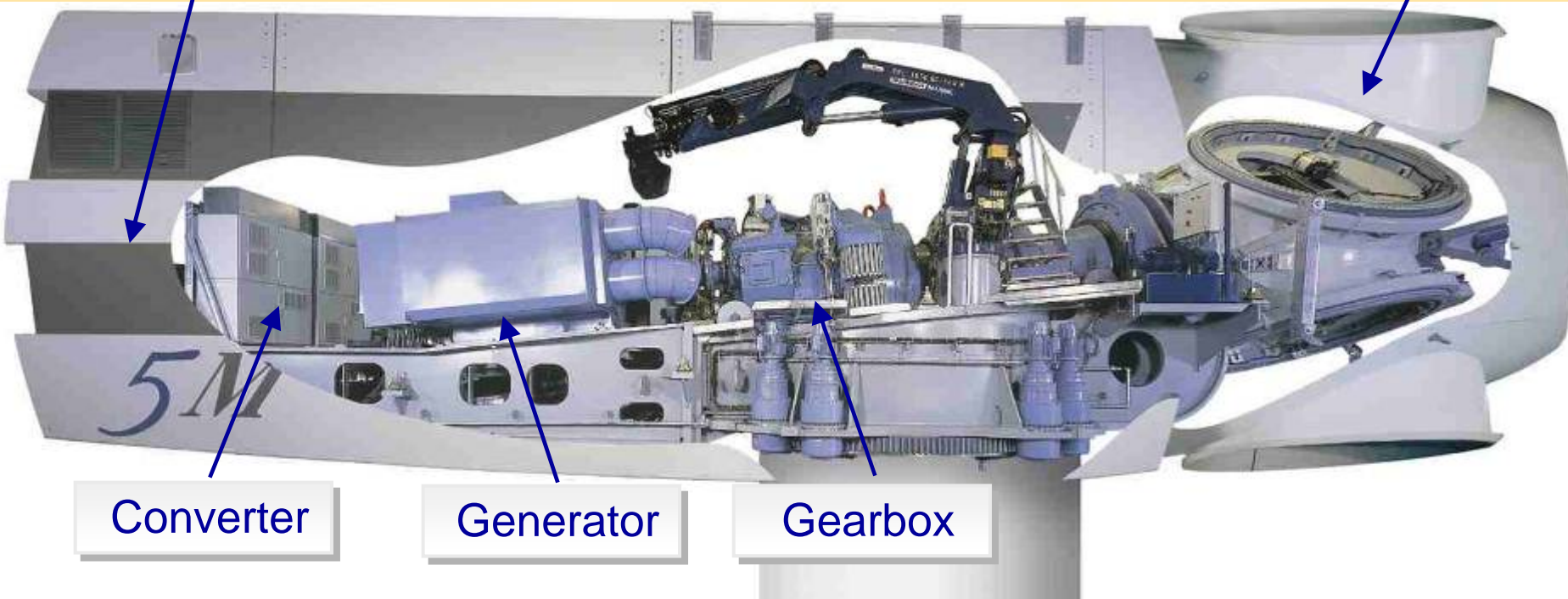


# Common DFIG-based platform



Transformer

Rotor

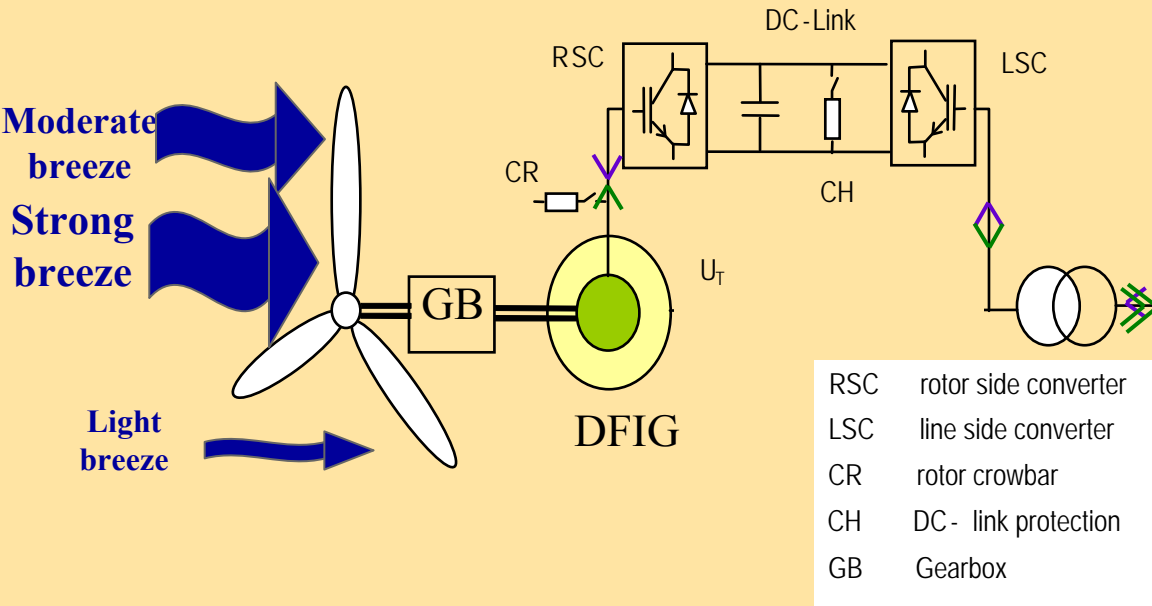


Converter

Generator

Gearbox

# DFIG Operation Principle

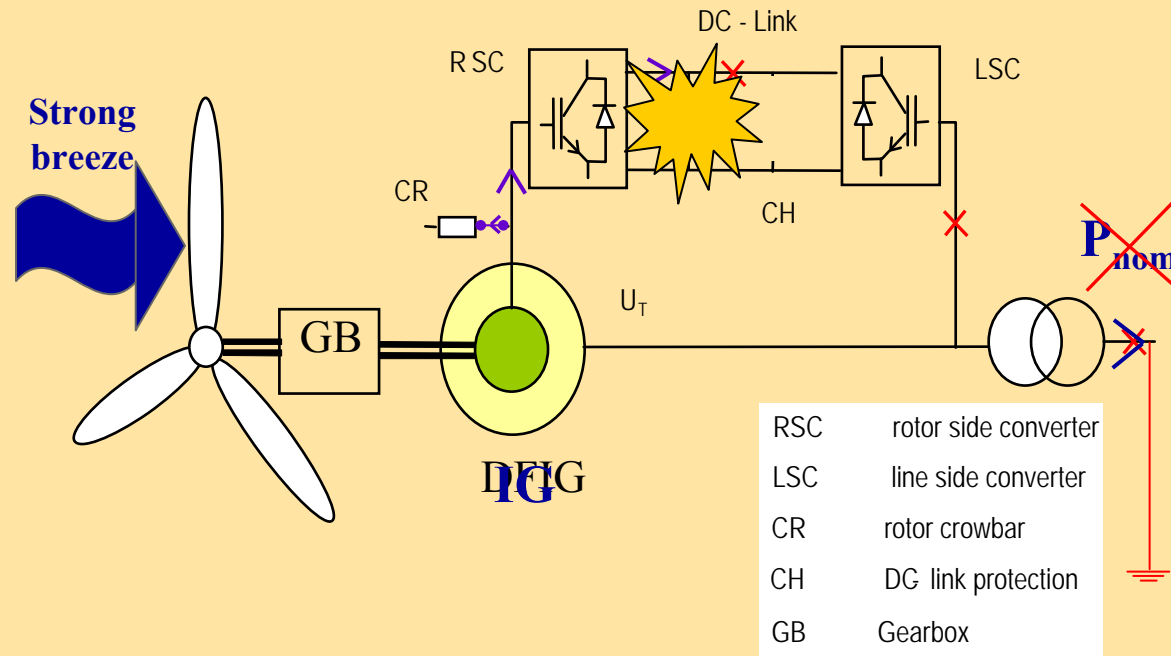


1) Rotor fed by converter (adapts  $U_{stat}$  and  $f_{stat}$  to  $U_{grid}$  and  $f_{grid}$ )

2) Stator is connected and provides power:  $P_{net} = P_{stat} - P_{rot}$

3) To keep 50 Hz on stator, rotor field inverts, rotor provides power:  $P_{net} = P_{stat} + P_{rot}$

# Protection principle during grid fault (nominal op')



## 1) Fault on the grid w/o protection:

- Rotor currents charge DC-Link
- DC-Link power cannot flow outside
- Too high DC voltage => destruction

## 2) Fault on the grid w/ crowbar:

- Rotor currents charge DC-Link
- CR short-circuits rotor, (RSC in diode mode) => DC-Link energy dissipated
- Crowbar => Induction generator

## 3) Fault on the grid w/ chopper:

- Rotor currents charge DC-Link
- CH dissipates DC-Link additional energy
- Generator control possible => grid support possible



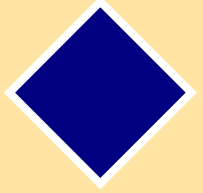
**Need of wind turbine models**



**Approach of model validation in Germany**



**Model insight**



**Comparison between simulation results and measurements**



**Benefits and future of wind-turbine modelling**



**Need of wind turbine models**



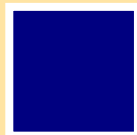
**Approach of model validation in Germany**



**Model insight**



**Comparison between simulation results and measurements**



**Benefits and future of wind-turbine modelling**



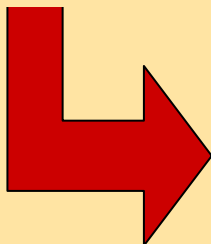




## Reasons & Objectives of making models

Reasons

Objectives of model



*The model accuracy has been standardized in Germany*



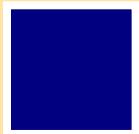
Need of wind turbine models



Approach of model validation in Germany



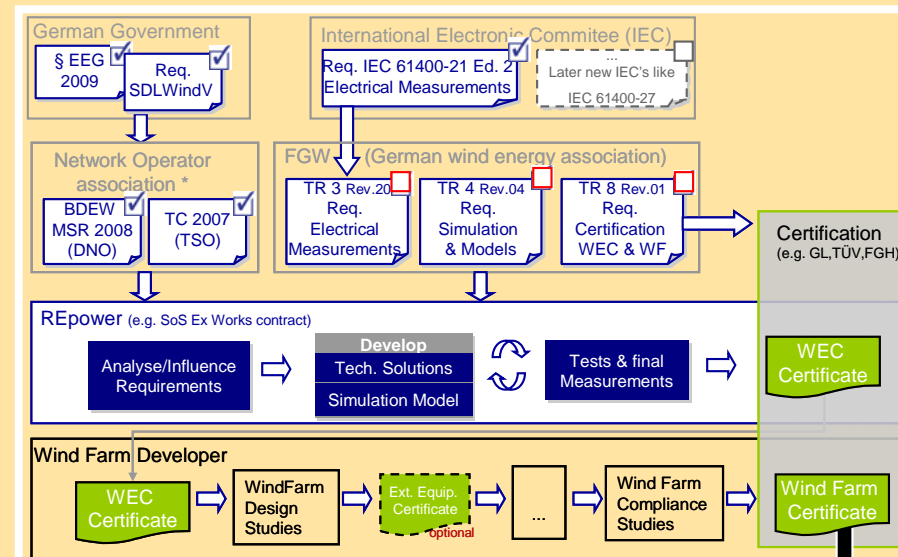
Model insight



Comparison between simulation results and measurements



Benefits and future of wind-turbine modelling

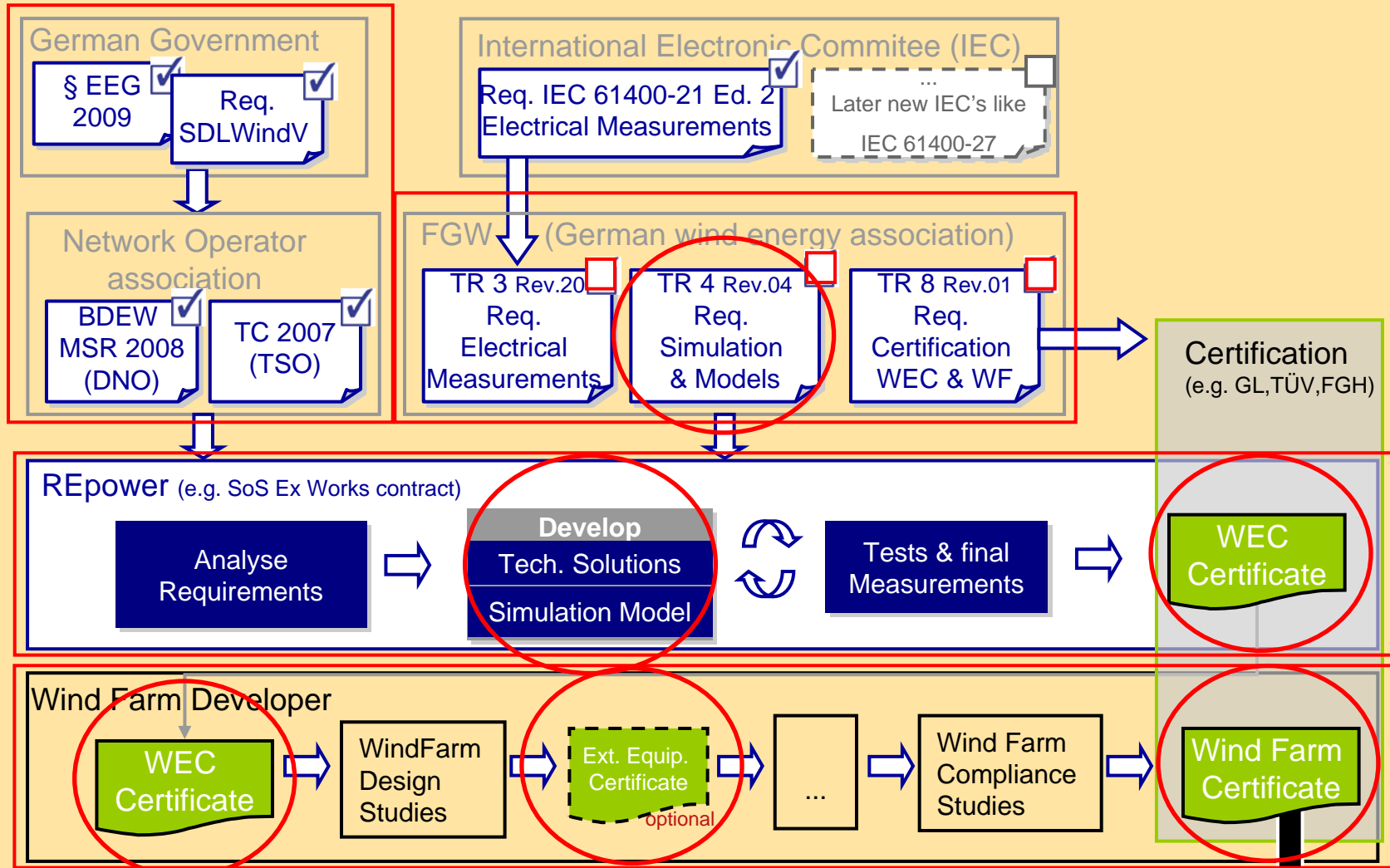


EEG 2009 - RENEWABLE ENERGY SOURCES ACT CONFORMITY:

\* Additional requirements may apply on project specific basis

"preferred connection" in acc. to EEG + feed in tariffs

## WEC model validation in the entire process



EEG 2009 - RENEWABLE ENERGY SOURCES ACT CONFORMITY:  
 "preferred connection" in acc. to EEG + feed in tariffs



## Overview of the German technical guideline: TR4



### **WHO** is concerned ?

- All renewable system manufacturers (Wind, PV, biomass,...) => same modelling and certification requirements

### **WHAT** is concerned ?

- RMS model of the renewable system

### **WHERE** is the focus on ?

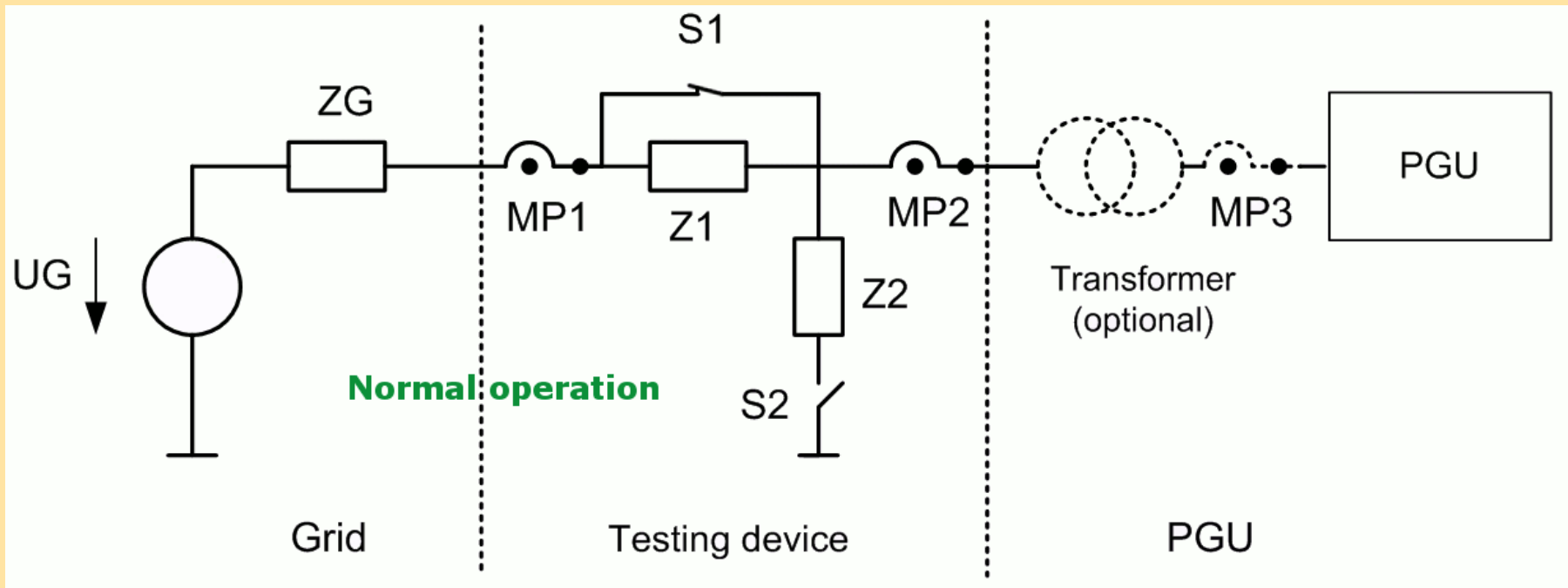
- Model accuracy compared to standardized measurements acc. to TR3 (equ. to IEC 61400-21 2<sup>nd</sup> Ed) during FRT-Tests
- Definition of baseline requirements



## 5-Step method to validate the single WEC model

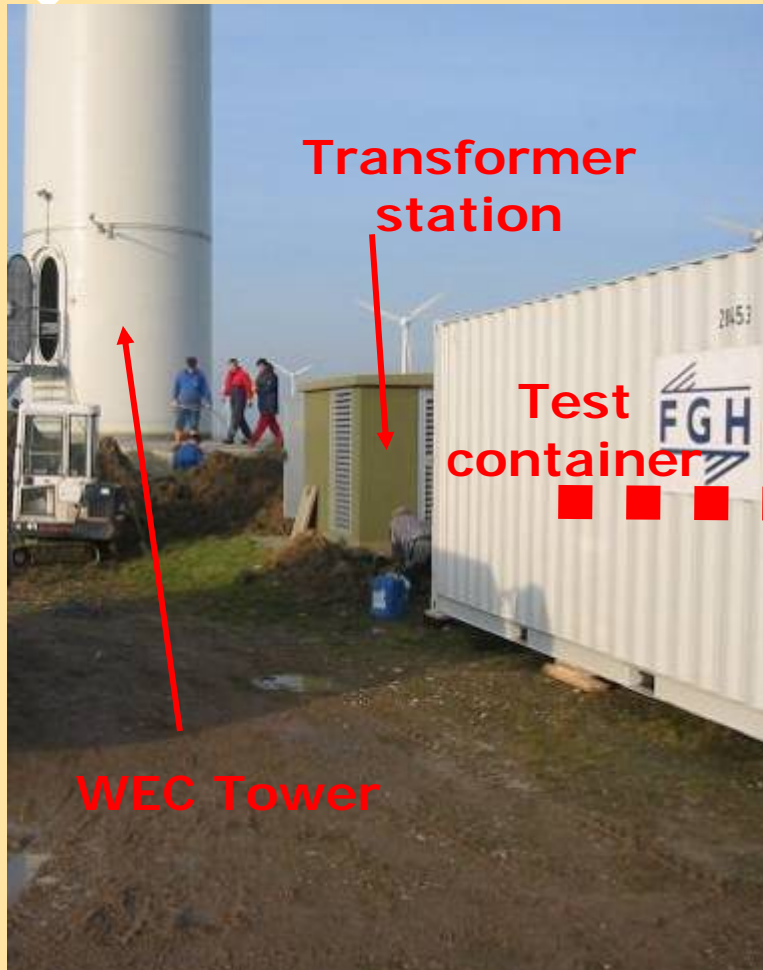
1°)

Validation through FRT-Test





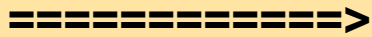
## 1° Real test-field



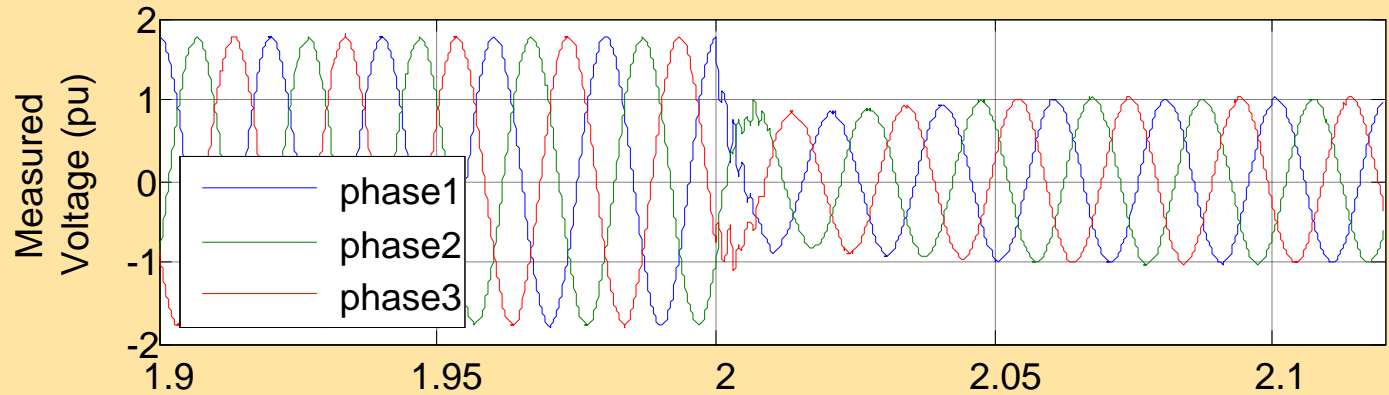


## 1°) FRT-Measurement Results

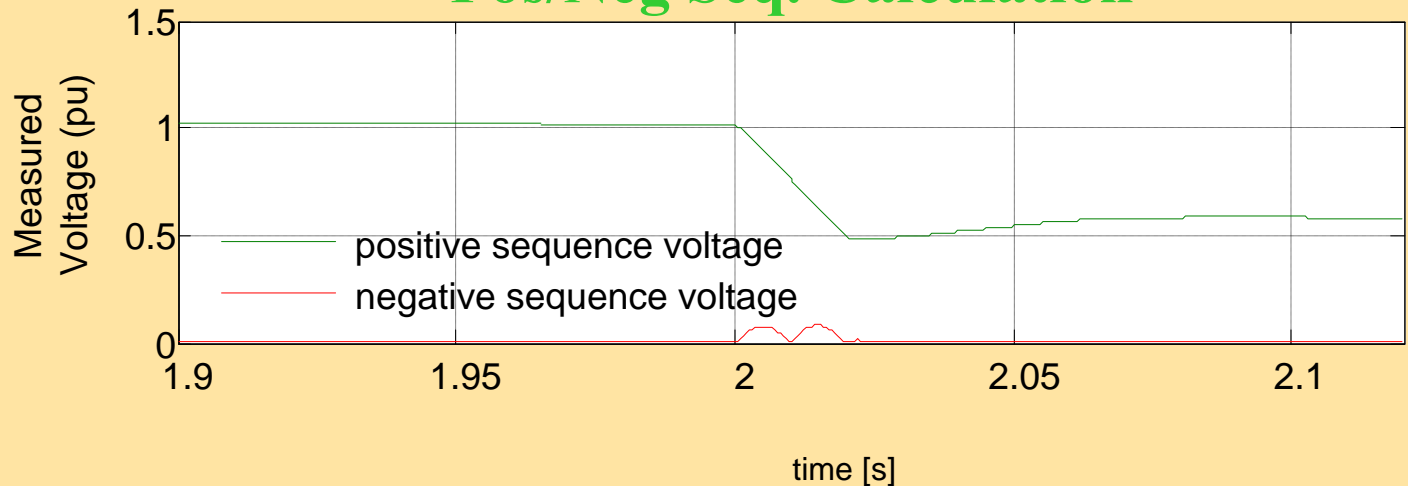
**Balanced fault**

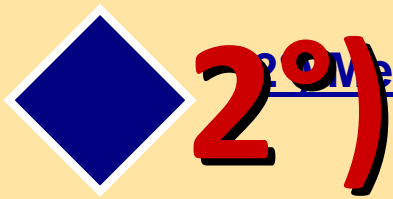


### Measurements



### Pos/Neg Seq. Calculation





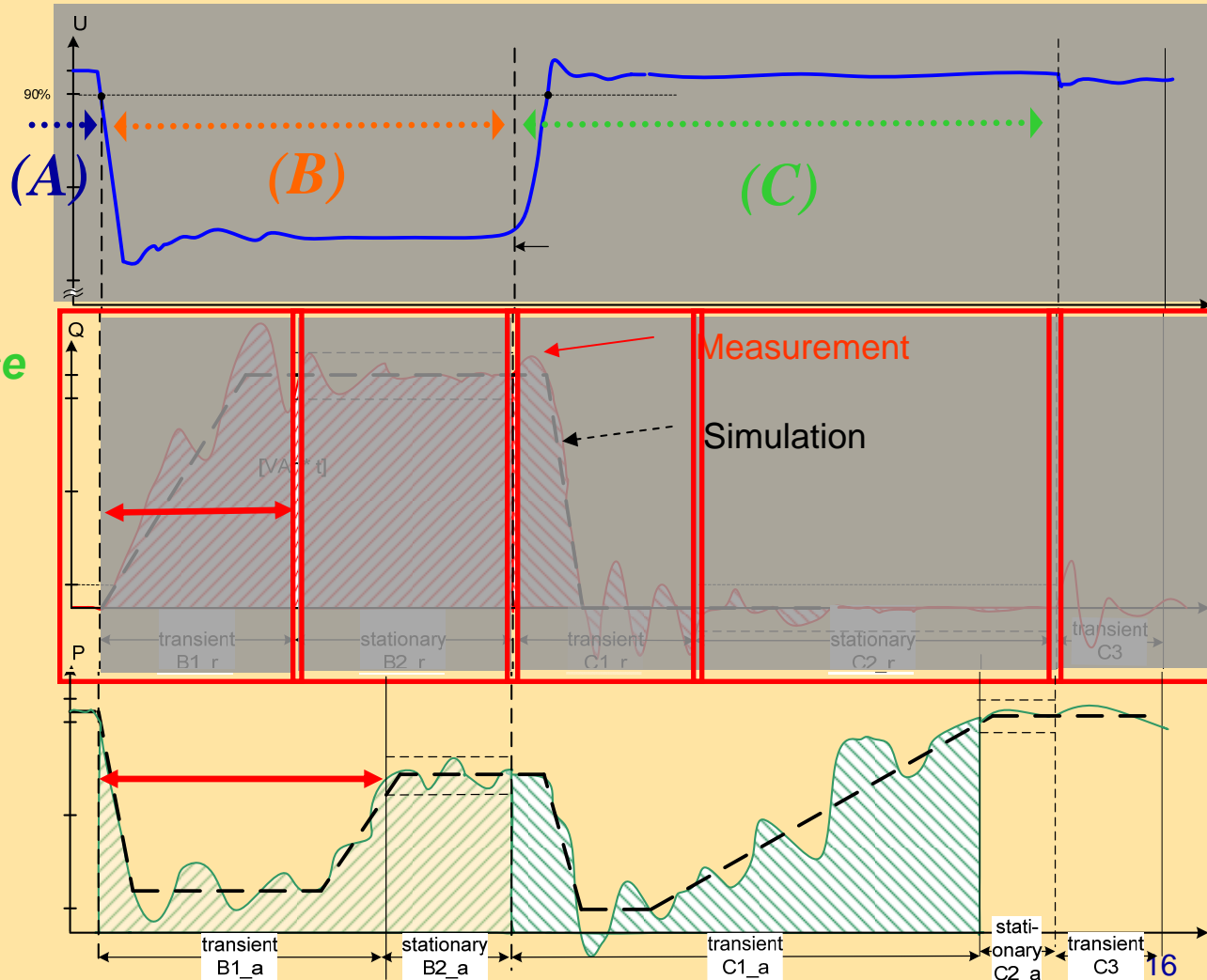
## 2. Measurement & Result formatting (arbitrary example)

> 2.1) Definition of start and end of the following periods:

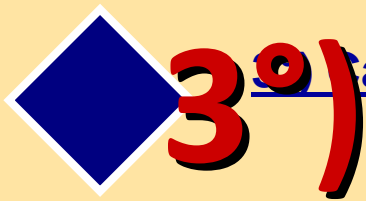
- (A): Before fault
- (B): During fault
- (C): After fault clearance

> 2.2) Identification of intervals:

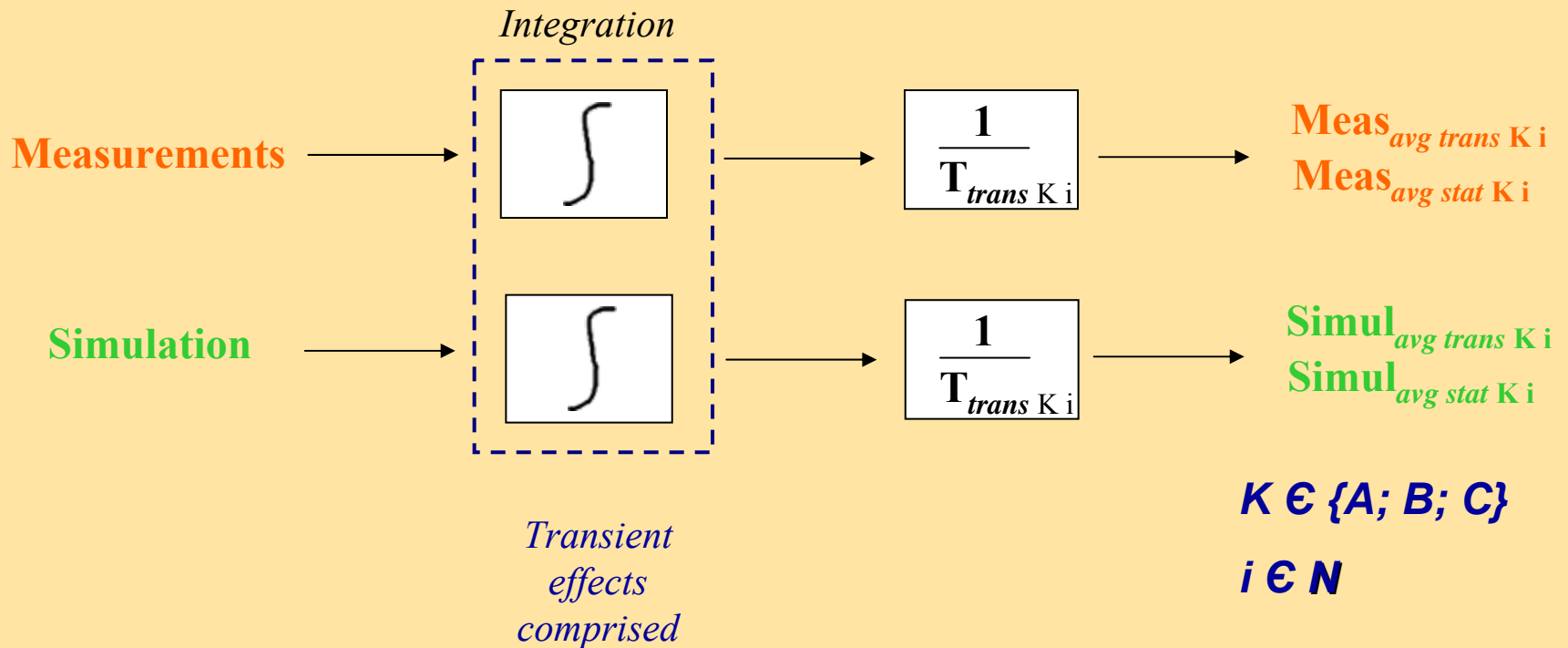
- Stationary
- Transient



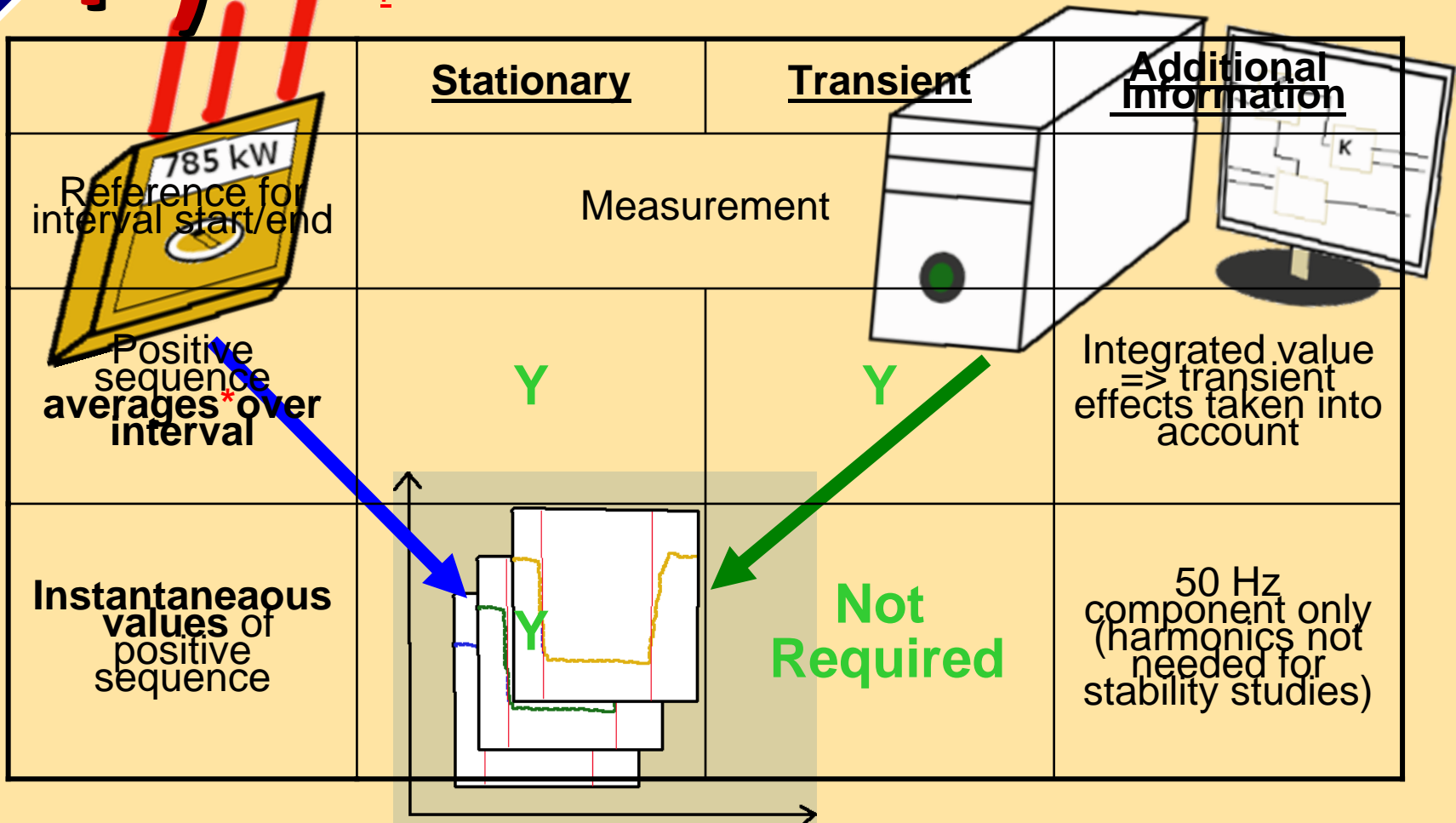




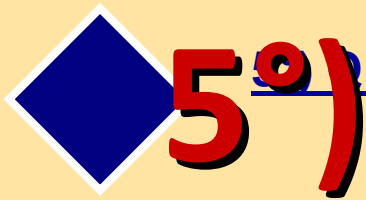
## 3) Calculating averages for each interval and for $P, Q, I_r$



## 4) Comparison of measurement and simulation in each interval and/or P, Q, I<sub>r</sub>



\* average values calculated over the considered interval duration



## Quality assessment of the simulation model for P, Q, I<sub>r</sub>

### • Transient intervals

*Average  
evaluation*

$$\sum_{i \in K} (\text{Meas}_{\text{avg trans } K i} - \text{Simul}_{\text{avg trans } K i}) = \mathbf{E}_{\text{Trans } K}$$

$$K \in \{A; B; C\}$$

$$i \in N$$

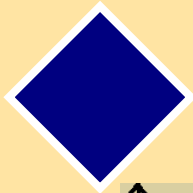
### • Stationary intervals

*Average  
evaluation*

$$\sum_{i \in K} (\text{Meas}_{\text{avg stat } K i} - \text{Simul}_{\text{avg stat } K i}) = \mathbf{E}_{\text{Stat } K}$$

*Positive  
sequence  
evaluation*

$$\text{Max}_{t_i \in (\text{stationary interval})} (\text{Meas}_{\text{pos seq } (t_i)} - \text{Simul}_{\text{pos seq } (t_i)}) = \mathbf{E}_{\text{Stat\_pos } K}$$



## 5° Quality assessment of the simulation model for P, Q, I<sub>r</sub>



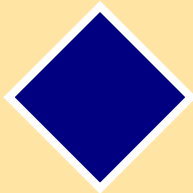
t	Difference	Diff	Diff
1	...	...	...
2	...	...	...
3	...	...	...
4	...	...	...
5	...	...	...
6	...	...	...
7	...	...	...
8	...	...	...
9	...	...	...
10	...	...	...

### Calculated deviations:

- Mean values during transient intervals ( $E_{Trans K}$ )
- Mean values during stationary intervals ( $E_{Stat K}$ )
- Positive sequence values during stationary intervals ( $E_{Stat\_pos K}$ )



**Total error of simulation model**



## 5° Quality assessment of the simulation model for P, Q, I<sub>r</sub>

Calculation of a global deviation for the entire FRT-Test

$$\text{SM total error} = C_A \times E_A + C_B \times E_B + C_C \times E_C$$

Deviation	Weight
Before fault ( $E_A$ )	10 % ( $C_A$ )
During fault ( $E_B$ )	60 % ( $C_B$ )
After fault ( $E_C$ ) clearance	30 % ( $C_C$ )

$$E_K = \sum_{K=A}^{K=C} (E_{Trans K} + E_{Stat K})$$



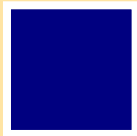
Need of wind turbine models



Approach of model validation in Germany



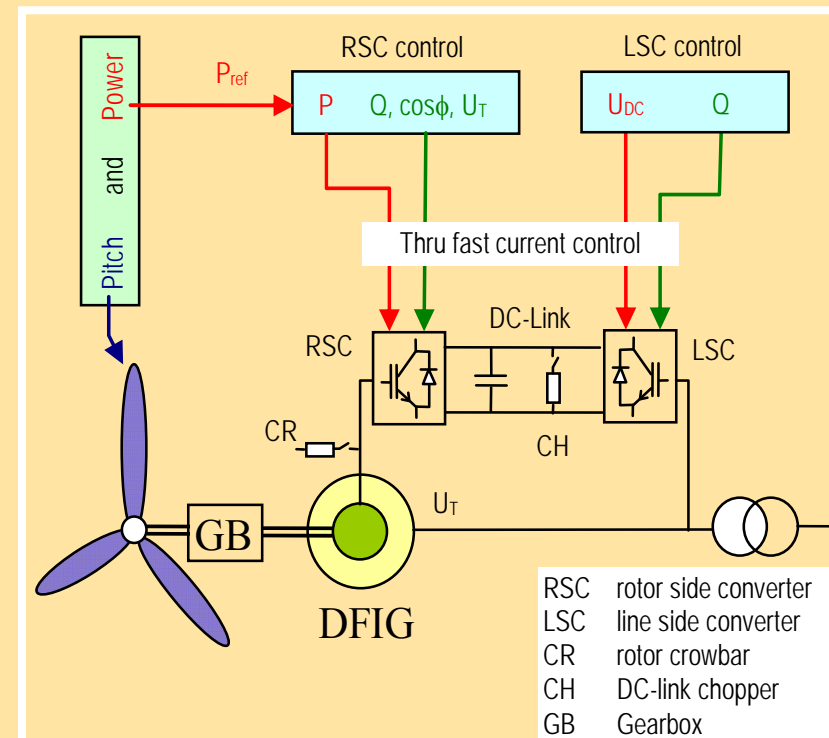
**Model insight**

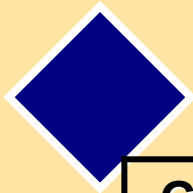


Comparison between simulation results and measurements



Benefits and future of wind-turbine modelling





## Available simulation model types

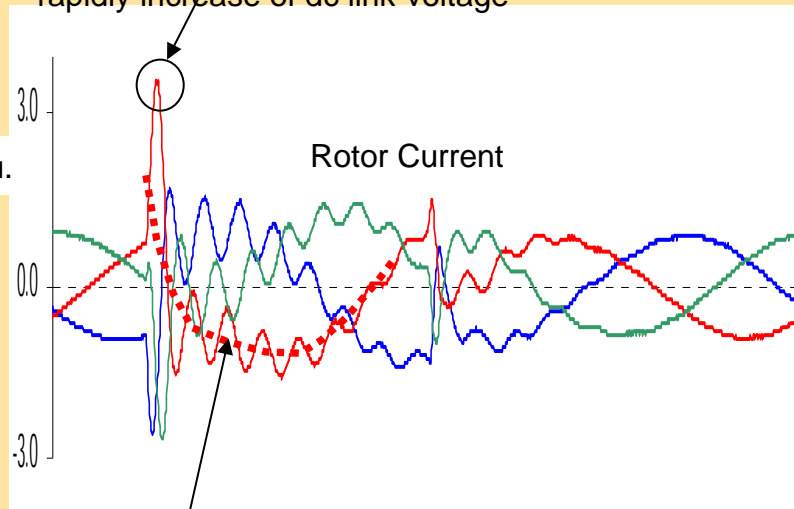
Generator detail level	Type	Applications	Remarks
Full Order Model (FOM)	EMT	<ul style="list-style-type: none"> <li>- Fast transients</li> <li>- Electro magnetic interferences</li> </ul>	Crowbar firing capabilities
Enhanced Reduced Order Model (E/ROM)	Usually RMS	<ul style="list-style-type: none"> <li>- System integration</li> <li>- Stability studies</li> </ul>	Crowbar firing capabilities
Reduced Order Model (ROM)	Usually RMS	<ul style="list-style-type: none"> <li>- System integration</li> <li>- Stability studies</li> </ul>	Quick simulation time

Complexity ↑

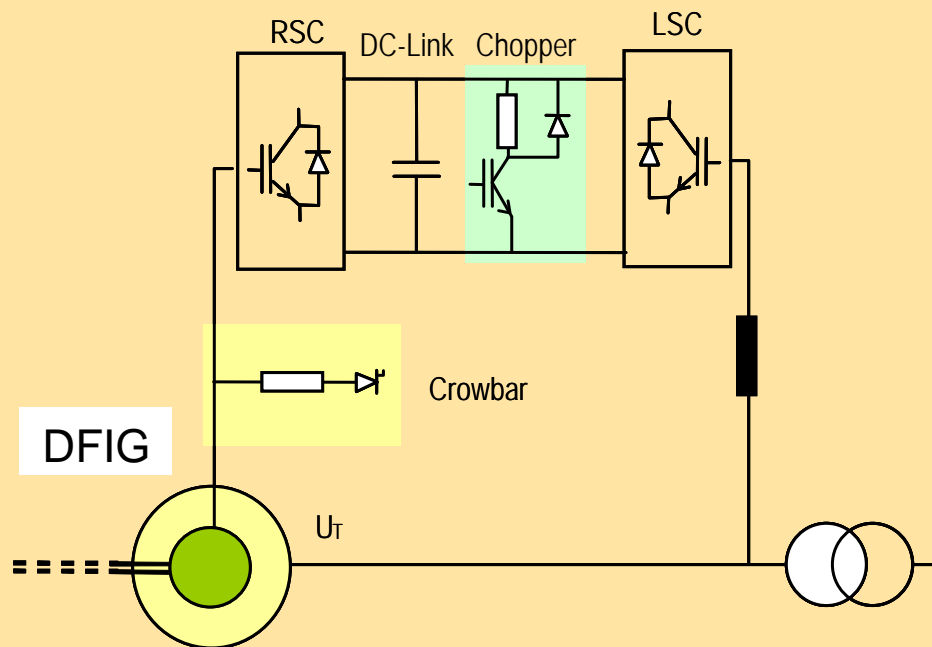


## Difference between ROM and FOM: rotor current calculation

Alternating component  
decisive in Crowbar activation:  
rapidly increase of dc link-voltage



Reduced order DFIG model triphase

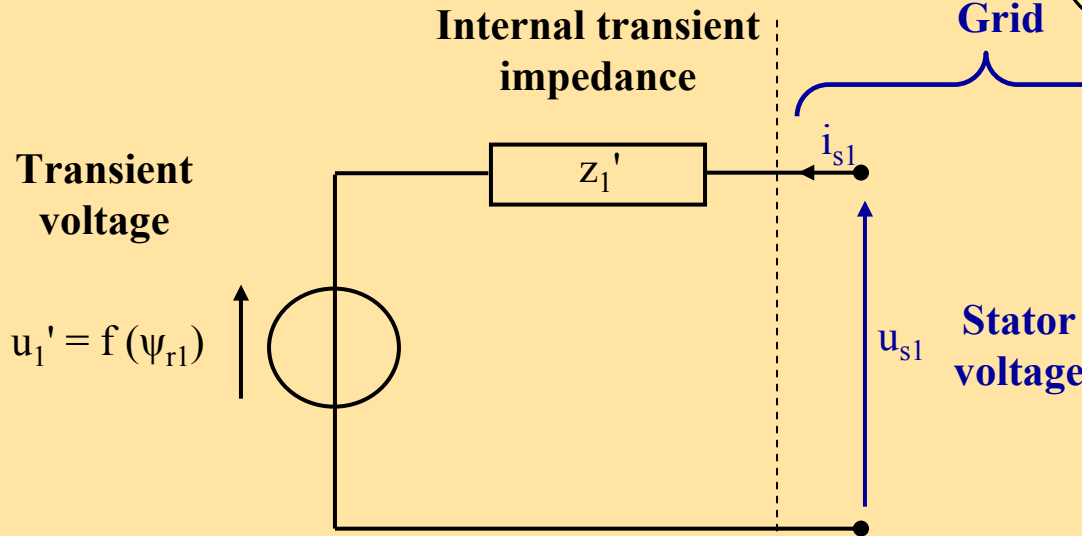
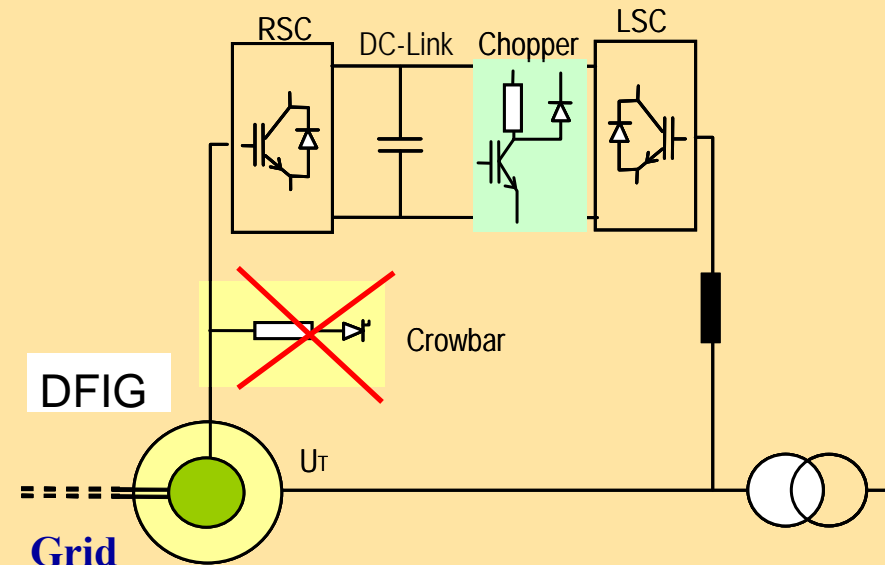






## ROM Model (RMS) features

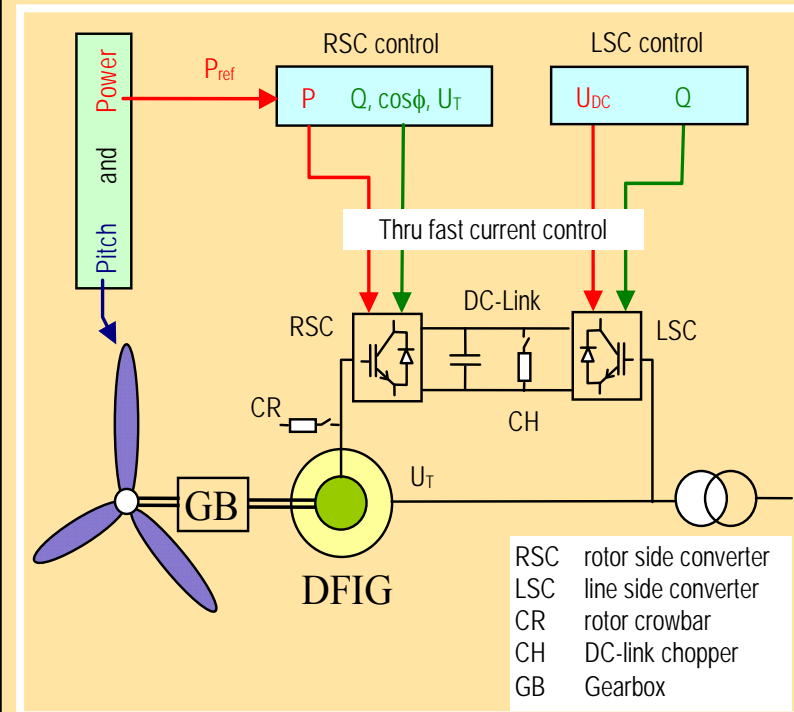
- **Simplified FOM Model**
- **No crowbar firing capabilities (not needed anymore however)**
- **Positive sequence component modelled as a Thevenin source**





## Features of REpower's simulation model (German TR4)

-Model type	<i>RMS</i>
-Maximal step size	<i>10 ms</i>
-WEC-transformer	<i>included*</i>
-Freq. protection	<i>included</i>
-Volt. protection	<i>included</i>
-Harmonics	<i>not included</i>
-Flicker	<i>not included</i>
-Aerodynamic & pitch control	<i>included*</i>



*\* not compulsory*



Need of wind turbine models



Approach of model validation in Germany



Model insight



**Comparison between simulation results and measurements**

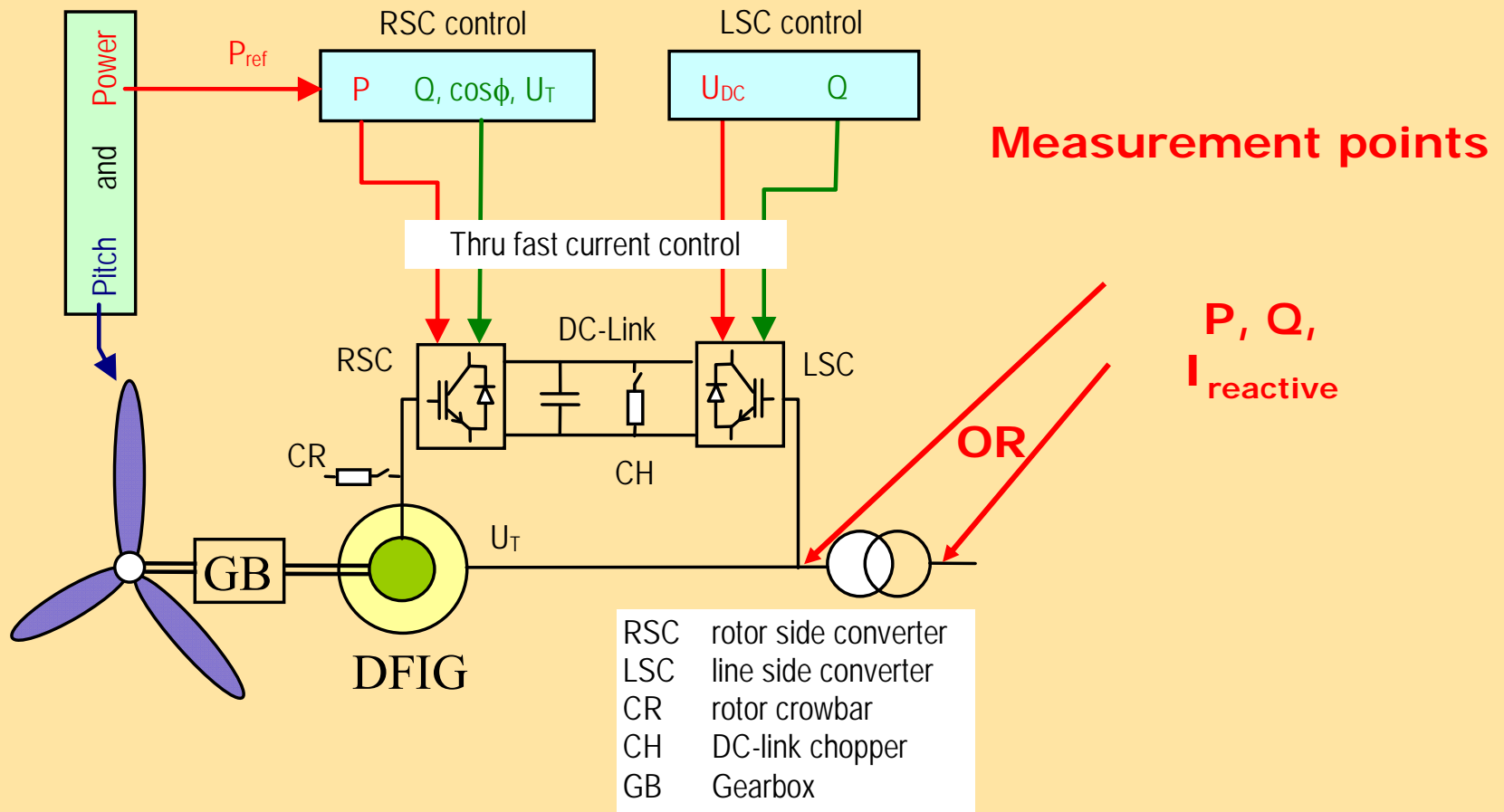


Benefits and future of wind-turbine modelling





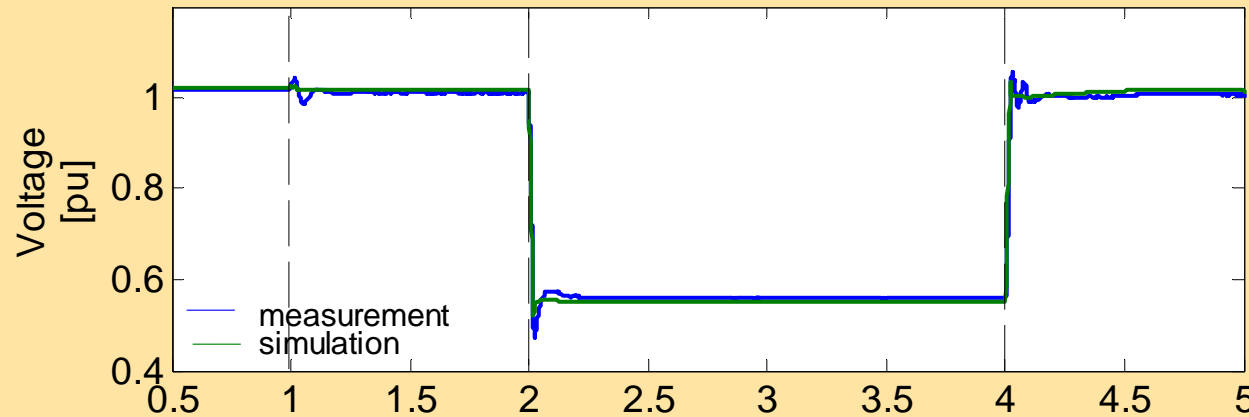
## Compared items between simulation and measurement



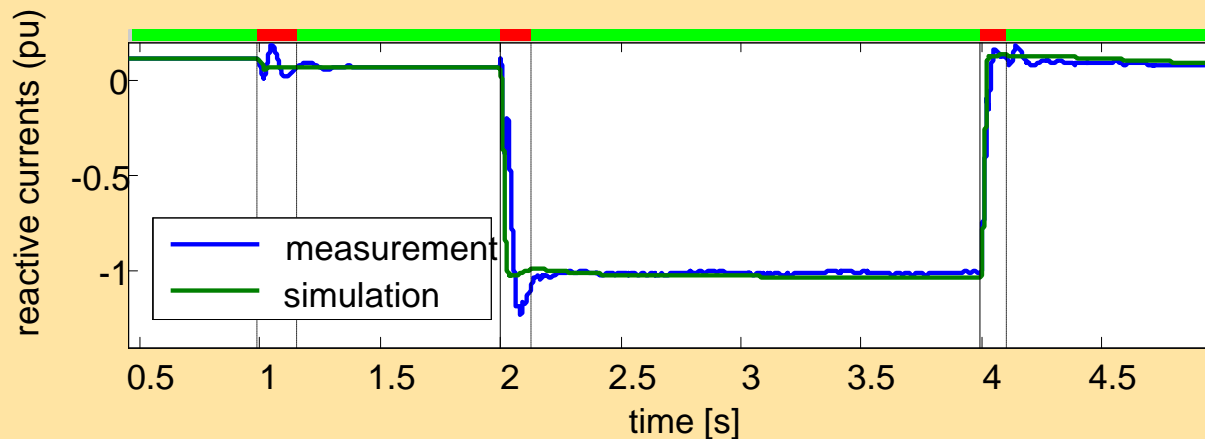


## Balanced voltage dip down to 45%

### 2°) Measurement & Result formatting



$\Rightarrow U_{WEC}(t)$

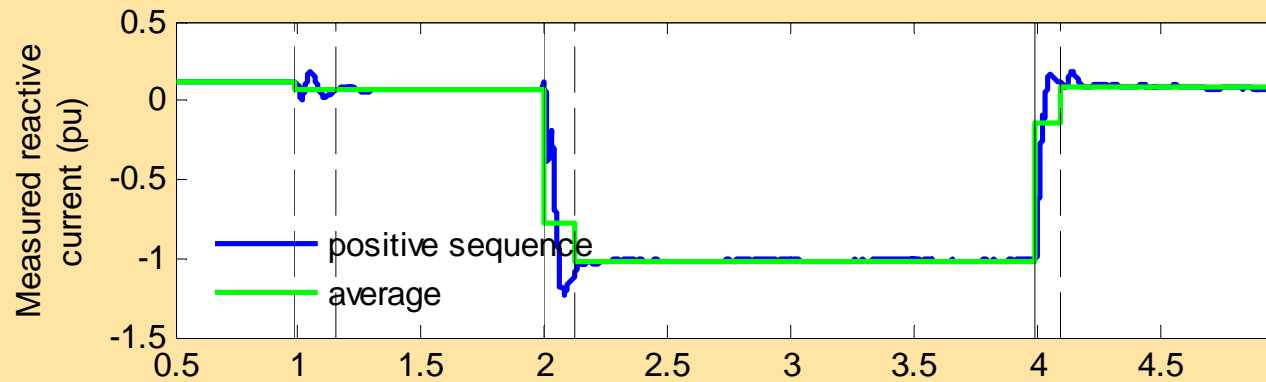


$\Rightarrow I_r(t)$

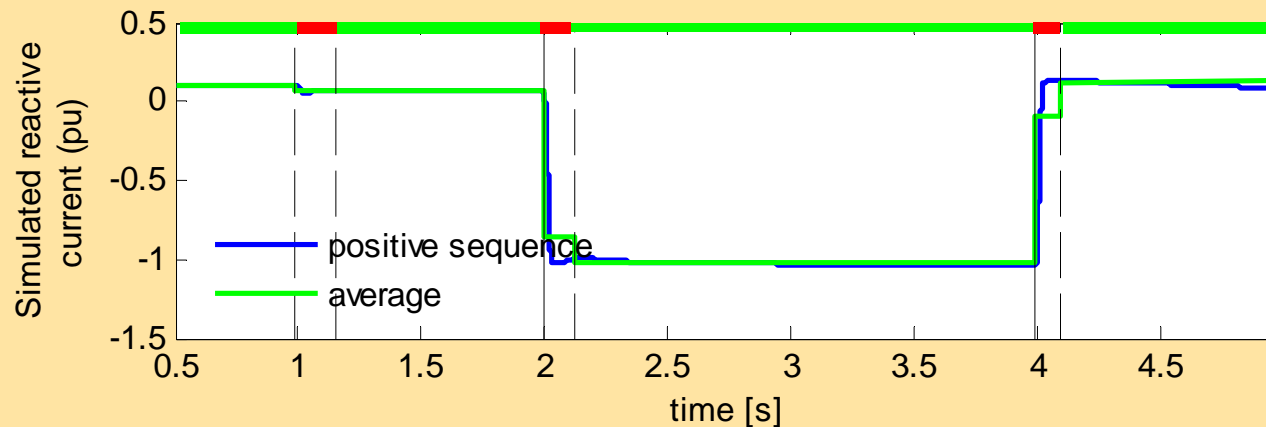


## Balanced voltage dip down to 45%

### 3° Calculating averages for each interval



$\Rightarrow I_{r \text{ Meas}}(t)$

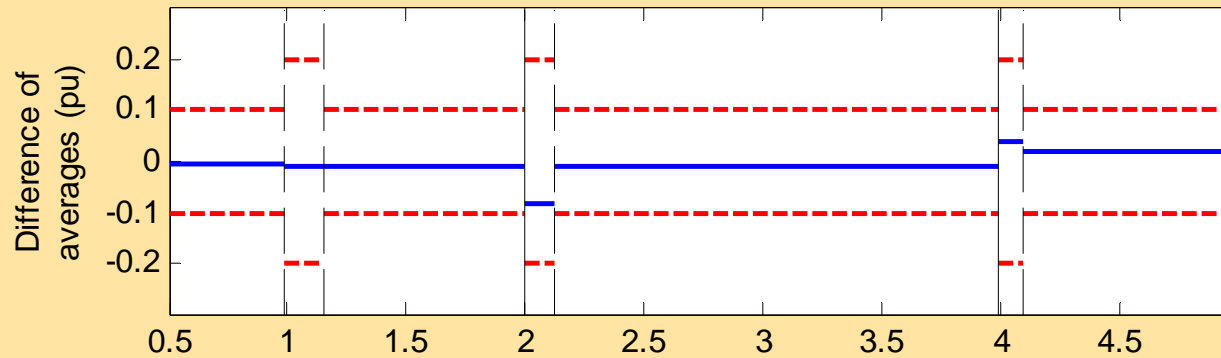


$\Rightarrow I_{r \text{ Sim}}(t)$

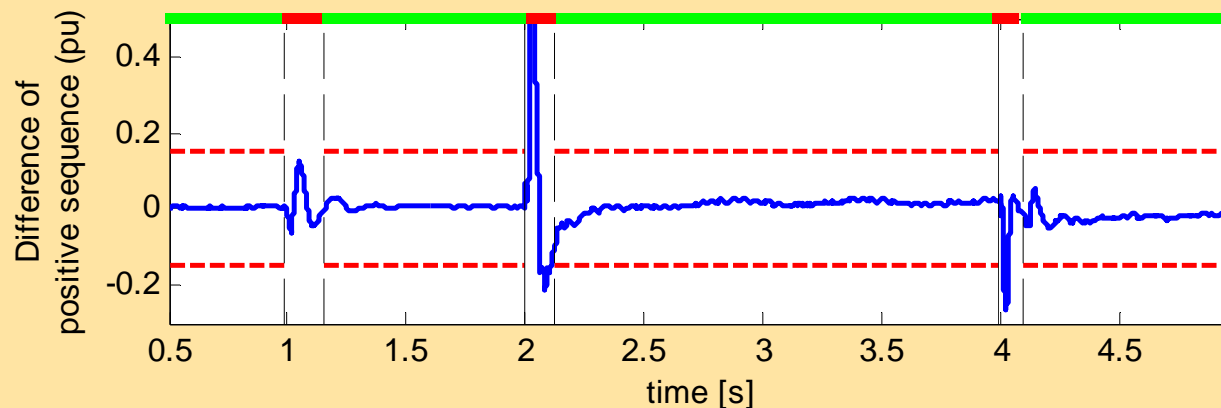


## Balanced voltage dip down to 45%

### 5° Assessing model



$\Rightarrow I_{r Avg}(t)$



$\Rightarrow I_{r Pos}(t)$

--- Allowed limits

— Differences simul. / meas.



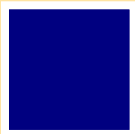
**Need of wind turbine models**



**Approach of model validation in Germany**



**Model insight**



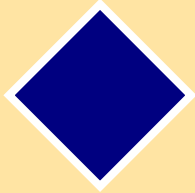
**Comparison between simulation results and measurements**



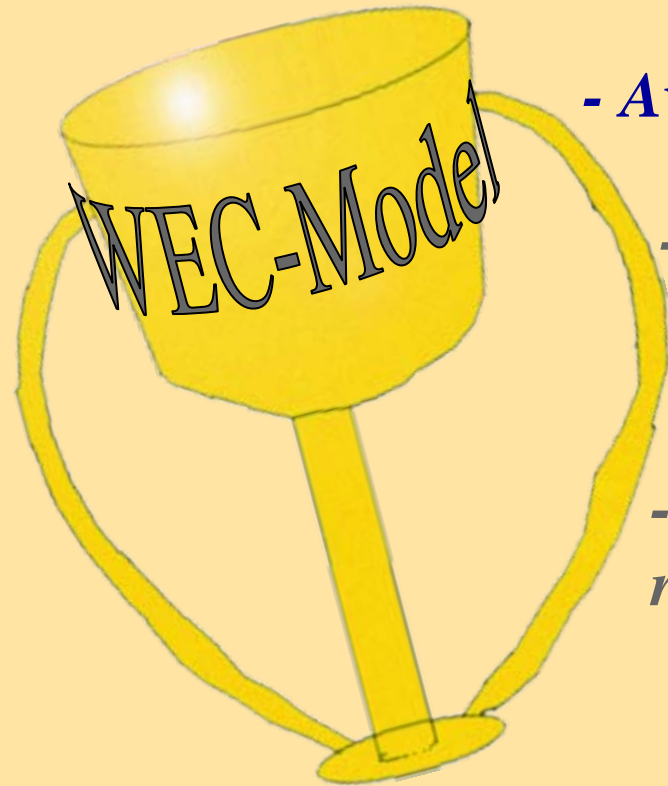
**Benefits and future of wind-turbine modelling**







## Goals of keeping modelling



- *Avoid expensive equipments*
- *Better integration into the grid*
- *Simulation of complete wind-farms*
- *Simulation of scenarios not testable in reality (stability risks)*



## External equipments included in wind-farm model





## Future process for validating wind-farm model in Germany

**Forecast release of the technical  
guide-line: end 2010**

**Wind-farm model validation**

**Wind-farm model based on  
validated WEC models**

**Wind-farm model compared to  
validated wind-farm  
measurements**

 **Recommended way**

 **Expensive or impossible way**

Thanks for your attention !



Thanks for your attention !





**Backup slides**



Equations can be found in:

***"Validation of an RMS DFIG Simulation Model according to New German Model Validation Standard FGW TR4 at Balanced and Unbalanced Grid Faults"***

Jens Fortmann, Stephan Engelhart, Jörg Kretschmann,  
Christian Feltes, Prof I Erlich.