Program at a glance

	Special Sessions	(SS) and Workshops (WS)	
	08.00-20.00 09.00-13.00	Registration WS1 - Clinical Perspectives of Hybrid Bionic Systems SS2- Human Motion Analysis and Neurorehabilitation	(Conference Service Desk – Foyer) (Rvb) (JdR2)
007	11.00-13.00	SS5a - Robot Aided Identification of Neuromuscular Properties I SS1 - Human-Robot Interfaces SS3 - Robotic Wheelchairs (JdR3)	(VSg) (JdR1)
2	13.00-14.00	Lunch (Brasserie and Lounge Circles)	
ne	14.00-18.00	WS2 - Stroke Rehabilitation	(Rvb)
Jul :		SS5b - Robot Aided Identification of Neuromuscular Properties II SS6 - Neural Interfaces for the Control of Robotic Artefacts	(JdR1) (JdR2)
12		SS7 - Rehabilitation of Hand Function	(JdR3)
Tuesday 12 June 2007	15.00-18.00	SS4 – Touch Sensing for Neurocontrolled Prosthetic Hands	(VSg)

	Day 1		
	07.00-14.00 08.15-08.30 08.30-09.15	Registration Opening Plenary Lecture Professor Homayoon Kazerooni That which does not stabilize, will only make us stronger.	(Conference Service Desk – Foyer) (JdR1-3) (JdR1-3)
	09.15-10.00 10.00-11.30 11.30-13.00	Fast Forward Presentations INT1 - Interactive Sessions POD1 - Podium Presentations Therapy Robotics I 1. Task-Orientated Biofeedback System for the Rehabilitation of the Upper Limb (81) 2. Intuitive human interactive with an arm robot for severely handicapped people - A One Click approach (113) 3. An fMRI compatible haptic interface with pneumatic actuation (136) 4. Methods for Evaluating and Improving Interlimb Coordination for Bimanual Robotic Therapy after Stroke (90) 5. Development of a Systems Architecture for Robot-Aided Telerehabilitation (36)	(JdR1-3) (JdR4-7) (JdR1-3)
Wednesday 13 June 2007	13.00-14.00 14.00-14.30 14.30-16.00	 Lunch Forum Discussion Users on Assistive Robotics POD2 - Podium Presentations Assistive Robotics I 1. Design and Construction of a Robotic Gripper for Activities of Daily Living for people with Disabilities (89) 2. The SDM Hand as a Prosthetic Terminal Device: A Feasibility Study (179) 3. Grasp force optimization in the design of an underactuated robotic hand (147) 4. Progress Towards the Development of a Highly Functional Anthropomorphic Transhumeral Prosthesis (54) 5. Optoelectronic-Based Flexible Contact Sensor for Prosthetic Hand Applications (86) 	(Brasserie and Lounge Circles) (JdR1-3) (JdR1-3)
Wednes	16.00-16.45 16.45-18.15 18.15-19.00 19.00	Fast Forward Presentations INT2 - Interactive Sessions LAB - Laboratory Presentations Steering Committee Assembly	(JdR1-3) (JdR4-7) (JdR1-3)

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	Day 2		
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	08.15-08.30 08.30-09.15	Opening Plenary Lecture prof. Frans van der Helm Diagnostic Robotics: Robot manipulators for quantifying position, velocity and force reflex gains.	(JdR1-3) (JdR1-3)
	09.15-10.00 10.00-11.30 11.30-13.00	Fast Forward Presentations INT3 - Interactive Sessions POD3 - Podium Presentations Assistive Robotics II 1. Assistive Technology: A novel approach to evaluation (152) 2. Compiling a Medical Device File and a Proposal for an International Standard for Rehabilitation Robots (99) 3. Rehabilitation walker system with standing assistance (42) 4. Design of the Modular Arm Robot System (64) 5. Developing An Intelligent Robotic Arm for Stroke Rehabilitation (180)	(JdR1-3) (JdR4-7) (JdR1-3)
Thursday 13 June 2007	13.00-14.00 14.00-14.30 14.30-16.00	 Lunch Forum Discussion Users on Assistive Robotics POD4 - Podium Presentations Control 1. Real-Time Control of the Hand by Intracortically Controlled Functional Neuromuscular Stimulation (92) 2. Low level control in a semi-autonomous rehabilitation robotic system via a Brain-Computer Interface (137) 3. Development of Vision-Based Navigation for a Robotic Wheelchair (174) 4. A Configuration-Space Approach to Controlling a Rehabilitation Arm Exoskeleton (51) 5. Biomechanical Design of a Powered Ankle-Foot Prosthesis (68) 	(Brasserie and Lounge Circles) (JdR1-3) (JdR1-3)
Thursday	16.00-16.45 16.45-18.15 18.15-18.30 19.00-23.00	Fast Forward Presentations INT4 - Interactive Sessions "Rock & Rolstoel" Beach Barbeque Dinner	(JdR1-3) (JdR4-7) (JdR1-3) (Het Zuiderbad – outside hotel)

	Day 3		
	08.15-08.30 08.30-09.15	Opening Plenary Lecture Just Child's Play? - Applications of Robot Assisted Play in Autism Therapy - Professor Kerstin Dautenhahn	(JdR1-3) (JdR1-3)
Friday 12 June 2007	09.15-10.00 10.00-11.30 11.30-13.00 13.00-13:30 13.30-14.00 14.00-18.00	Fast Forward Presentations INT5 – Interactive Sessions POD5 – Podium Presentations Therapy Robotics II 1. Assistive Technology: A novel approach to evaluation (152) 2. Compiling a Medical Device File and a Proposal for an International Standard for Rehabilitation Robots (99) 3. Rehabilitation walker system with standing assistance (42) 4. Design of the Modular Arm Robot System (64) 5. Developing An Intelligent Robotic Arm for Stroke Rehabilitation (180) Conference Closing & Awards Ceremony Take away Lunchbox Rehabilitation Robotics Research Roadmap Discussion	(JdR1-3) (JdR4-7) (JdR1-3)