

Table of Contents

Rehabilitation of hand function

- | | |
|---|---|
| <p>33 Comparison of grip action triggered by haptic or visual cue
Munih, Marko
Podobnik, Janez</p> <p>56 A Cable Driven Robotic System to Train Finger Function After Stroke
Burdet, Etienne
Chee Leong, Teo
Dovat, Ludovic
Gasser, Roger
Johnson, Vineet
Milner, Theodore
Olivier, Lambery
Salman, Berna
Wong, Stephen</p> <p>58 Development of a Hand Motion Assist Robot for Rehabilitation Therapy by Patient Self-Motion Control
Abe, Motoyuki
Aoki, Takaaki
Ishigure, Yasuhiko
Itho, Satoshi
Kawasaki, Haruhisa
Mouri, Tetuya
Nishimoto, Yutaka
Sakaeda, Hirofumi</p> <p>92 Real-Time Control of the Hand by Intracortically Controlled Functional Neuromuscular Stimulation
Kilgore, Kevin
Kirsch, Robert
Miller, Lee
Perreault, Eric
Pohlmeyer, Eric
Slutzky, Marc
Taylor, Dawn</p> | <p>129 Development of a Robot-Assisted Rehabilitation Therapy to train Hand Function for Activities of Daily Living
Burdet, Etienne Burdet
Dovat, Ludovic
Gassert, Roger Gassert
Johnson, Vineet
Lambery, Olivier
Milner, Theodore Milner
Salman, Berna
Teo Chee Leong, Teo Chee Leong
Wong, Stephen</p> <p>166 An Actuated Finger Exoskeleton for Hand Rehabilitation Following Stroke
Colgate, J. Edward
Kamper, Derek
Peshkin, Michael
Worsnopp, Thomas</p> <p>195 Design, Characterization, and Impedance Limits of a Hand Robot
Cappa, Paulo
Hogan, Neville
Krebs, Hermano Igo
Masia, Lorenzo</p> <p>136 An fMRI compatible haptic interface with pneumatic actuation
Blickenstorfer, Armin
Kollias, Spyros
Murr, Wolfram
Riener, Robert
Yu, Ningbo</p> <p>164 MR_CHIROD v.2: A fMRI Compatible Mechatronic Hand Rehabilitation Device
Khanicheh, Azadeh
Mavroidis, Constantinos
Mintzopoulos, Dionyssios
Tzika, A. Aria
Weinberg, Brian</p> |
|---|---|

Touch sensing for neurocontrolled prosthetic hands

- 86 Optoelectronic-Based Flexible Contact Sensor for Prosthetic Hand Applications
Carrozza, Maria Chiara
Persichetti, Alessandro
Vecchi, Fabrizio
- 105 Classification of EMG signals through wavelet analysis and neural networks for controlling an active hand prosthesis
Gini, Giuseppina
Arvetti, Matteo
Folgheraiter, Michele
- 108 Development of a Multifunctional Cosmetic Prosthetic Hand
Kargov, Artem
Klosek, Heinrich
Oberle, Reinhold
Pylatiuk, Christian
Roessler, Wolfgang
Schulz, Stefan
Werner, Tino
- 116 Brain-Computer Interface for a Prosthetic Hand Using Local Machine Control and Haptic Feedback
Acharya, Soumyadipta
Aggarwal, Vikram
Chatterjee, Aniruddha
Cho, Yoonju
Orourke, Brandon
Ramos Murguialday, Ander
Rasmussen, Robert
Thakor, Nitish V.
- 128 Wireless Temperature Sensing Cosmesis for Prostheses
Cho, Yoonju
Folowosele, Fopefolu
Liang, Kelvin
Miller, Brian
Thakor, Nitish
- 85 Adaptive Shared Control of a Brain-Actuated Simulated Wheelchair
Ferrez, Pierre
Lew Yi Lee, Eileen
Milla'n, José del R.
Moles, Ferran Galan
Nuttin, Marnix
Philips, Johan
van Brussel, Hendrik
Vanacker, Gerolf
- 103 On the control of axonal outgrowing for the development of new sieve interfaces
Carpaneto, Jacopo
Ciofani, Gianni
Dario, Paolo
Menciassi, Arianna
Micera, Silvestro
Navarro, Xavier
Raffa, Vittoria
Sergi, Pier Nicola
- 123 Neurobiological evaluation of thin-film longitudinal intrafascicular electrodes as a peripheral nerve interface
Koch, Klaus
Lago, Natalia
Micera, Silvestro
Navarro, Xavier
Poppendieck, Wigand
Vivó, Meritxell
Yoshida, Ken
- 186 Development of neural interfaces for chronic use in neuromotor prosthetics
Gage, Gregory J.
Kipke, Daryl R.
Marzullo, Timothy C.
Purcell, Erin K.
Seymour, John P.
Subbaroyan, Jeyakumar
- 137 Low level control in a semi-autonomous rehabilitation robotic system via a Brain-Computer Interface
Friman, Ola
Gräser, Axel
Lüth, Thorsten
Ojdanic, Darko
Prenzel, Oliver

Neural interfaces for the control of robotic artefacts

- 182 Peripheral Nerve Signals for Neural Control
Durand, Dominique
Tesfayesus, Wondimeneh
Yoo, Paul

161	Recording experience with the thin-film Longitudinal Intra-Fascicular Electrode, a multichannel peripheral nerve interface Citi, Luca Koch, Klaus Peter Kurstjens, Mathijs Micera, Silvestro Yoshida, Ken	183	Controlling a wheelchair using a BCI with low information transfer rate Ang, Marcelo Burdet, Etienne Guan, Cuntai Laugier, Christian Rebsamen, Brice Teo, Chee Leong Zeng, Qiang
Robotic wheelchairs			
30	Applying a 3DOF Orientation Tracker as a Human-Robot Interface for Autonomous Wheelchairs Frese, Udo Mandel, Christian Röfer, Thomas	198	MOVEMENT in progress Edelmayer, Georg Eimramhof, Peter Gelderblom, Gert Jan Huntemann, Alexander Kronreif, Gernot
47	Torque sensor free power assisted wheelchair Holmberg, Ulf Johansson, Jonas Pettersson, Daniel		
48	Assisted control mode for a smart wheelchair Bourhis, Guy Sahnoun, M'hamed		
80	Omni-directional wheelchair in reality and virtuality Evans, Nina Gibbs, Christopher Hillman, Michael		
115	Evaluation of the Collaborative Wheelchair Assistant System Burdet, Etienne Chee Leong, Teo Rebsamen, Brice Zeng, Qiang	77	Robot Aided Identification of Neuromuscular Properties Forrester, Larry Hogan, Neville Judkins, Timothy Khanna, Ira Krebs, Hermano Macko, Richard Patterson, Shawna Roy, Anindo
174	Development of Vision-Based Navigation for a Robotic Wheelchair Bailey, Matt Chanler, Andrew Maxwell, Bruce Micire, Mark Tsui, Katherine Yanco, Holly	102	Effects of Visual and Proprioceptive Motion Feedback on Human Control of Targeted Movement Gurari, Netta Kuchenbecker, Katherine J. Okamura, Allison M.
Robot Aided Identification of Neuromuscular Properties			
28	Passive Wrist Joint Impedance in Flexion Extension and Abduction Adduction Krebs, Hermano Igo Rijnveld, Niek		
77	Measurement of Human Ankle Stiffness Using the Anklebot Forrester, Larry Hogan, Neville Judkins, Timothy Khanna, Ira Krebs, Hermano Macko, Richard Patterson, Shawna Roy, Anindo		
102	Effects of Visual and Proprioceptive Motion Feedback on Human Control of Targeted Movement Gurari, Netta Kuchenbecker, Katherine J. Okamura, Allison M.		
112	Reduced Power: how to evoke low bandwidth motion control behaviour while estimating full bandwidth admittance Abbink, David Mugge, Winfred Van der Helm, Frans		

120	Determination of pathological clonus characteristics using a haptic ankle manipulator Arendzen, Hans de Groot, Jurriaan de Vlugt, Erwin Meskers, Carel van der Helm, Frans Wisman, Wessel	69	A 6-DOF Rehabilitation Support System for Upper Limbs including Wrists "Robotherapist" with Physical Therapy Furusho, Junji Jin, Ying Kikuchi, Takehito Morita, Tomoko Oda, Kunihiko Ohyama, Yuuki Shichi, Naoto
169	A Tele-Assessment System for Evaluating Arm Impairments in Patients with Neurological Disorders Park, Hyung-Soon Ren, Yupeng Wu, Yi-Ning Zhang, Li-Qun	71	Behavior-Based Path Modification for Shared Control of Robotic Walking Aids Graf, Birgit Schraft, Rolf D.
191	Detecting asymmetries in balance control with system identification: first experimental results from above knee amputees Nederhand, Mark van Asseldonk, Edwin van der Kooij, Herman	76	Pathological Sit-To-Stand Models for Control of a Rehabilitation Robotic Device Gas, Bruno Pasqui, Viviane Saint-Bauzel, Ludovic Zarader, Jean-Luc
125	Identification of Human Gait using Fuzzy Inferential Reasoning Brower, Richard David Ceberio, Martine Nava, Patricia Sarkodie-Gyan, Thompson Yu, Huiying	190	Motility Evaluation of a Novel Overground Functional Mobility Tool for Post Stroke Rehabilitation Brown, David Colgate, J. Edward Crombie, Gwen Lewis, Ela Makhlin, Alex Patton, James Peshkin, Michael Santos, Julio
126	Determination of Human Gait Phase Using Fuzzy Inference Brower, Richard Ceberio, Martine MacDonald, Chad Sarkodie-Gyan, Thompson Smith, Darla	Human Motion Analysis and Neurorehabilitation	
62	Human-robot interface with anticipatory characteristics based on Laban Movement and Bayesian models Dias, Jorge Rett, Jörg	146	Joint Moments Exhibited by Chronic Stroke Subjects While Walking with a Prescribed Physiological Gait Pattern Hidler, Joseph Neckel, Nathan Nichols, Diane
		154	Comparison of Neurosensorimotor Adaptation Under Kinematic and Dynamic Distortions Carignan, Craig Contreras-Vidal, Jose L. Tang, Jonathan

163	A novel experimental setup combining EEG and robotics to investigate brain activity driving controlled reaching movements in chronic stroke survivors Chen, Albert Dewald, Julius Yao, Jun	125 Identification of Human Gait using Fuzzy Inferential Reasoning Brower, Richard David Ceberio, Martine Nava, Patricia Sarkodie-Gyan, Thompson Yu, Huiying
165	ACT3D exercise targets gravity-induced discoordination and improves reaching work area in individuals with stroke DeMott, Tobey Dewald, Julius Ellis, Michael Sukal, Theresa	126 Determination of Human Gait Phase Using Fuzzy Inference Brower, Richard Ceberio, Martine MacDonald, Chad Sarkodie-Gyan, Thompson Smith, Darla
172	Usage of the ACT3D Robot in a Brain Machine Interface for Hand Opening and Closing in Stroke Survivors Dewald, Julius Sheaf, Clay Yao, Jun	127 Automated Interpretable Membership Functions in Human Gait Betancourt, Benjamin Gorripati, Sandhya Kong, Pui Wah Sarkodie-Gyan, Thompson
176	Use of the ACT3D System to Evaluate Synergies in Children with Spastic Hemiparetic Cerebral Palsy: A Pilot Study Dewald, Julius Krosschell, Kristin Sukal, Theresa	139 Analysis of the Fugl-Meyer Outcome Measures Assessing the Effectiveness of Robot-Mediated Stroke Therapy Amirabdollahian, Farshid Harwin, William Loureiro, Rui
180	Developing An Intelligent Robotic Arm for Stroke Rehabilitation Park, Hyung-Soon Ren, Yupeng Zhang, Li-Qun	
196	Learning-based methods for the analysis of intralimb-coordination and adaptation of locomotor patterns for cerebellar patients Giese, Martin Ilg, Winfried Röhrig, Rebecca Thier, Peter	14 Smooth Human-Robot Interaction in Robot-Assisted Rehabilitation Erol, Duygun Sarkar, Nilanjan
199	Dynamically Removing Partial Body Mass using Acceleration Feedback for Neural Training Ma, Ou Sarkodie-Gyan, Thompson	75 Vision Based Interface and Control of Assistive Mobile Robot System Komeda, Takashi Koyama, Hiroyuki Takagi, Motoki Takahashi, Yoshiyuki Yamamoto, Shinichiro
124	Design of a 3 DOF Robotic System for use in Neurorehabilitation Jensen, Kirt James Sarkodie-Gyan, Thompson	94 Improvement of Fail-Safe Components for Rehabilitation Robots Ohara, Takehiro Tejima, Noriyuki

INT1

170	Biomimetic Tactile Sensor for Control of Grip Johansson, Roland Loeb, Gerald Popovic, Djordje Santos, Veronica Wettels, Nicholas	44	Application of inertial sensors in rehabilitation robotics Brunetti, Fernando Miranda, J.A. Moreno Sastoque, Juan Camilo Pons Rovira, José Luis Rocon de Lima, Eduardo Ruiz Olaya, Andrés Felipe
59	Muscle Synergies in Chronic Stroke during a Robot-Assisted Wrist Training Hu, XiaoLing Liu, K. H. Lo, I. H. Song, Rong Tong, Kaiyu Zheng, XiuJuan	204	A genetic algorithm to optimum dynamic performance of industrial robots in the conceptual design phase Fadaei, Alireza Jafari, Amir Safavi, Mohsen
61	Initial patient testing of iPAM a robotic system for stroke rehabilitation Bhakta, ABipin Cozens, Alastair Culmer, Peter Jackson, Andrew Levesley, Martin Makower, Sophie Mon Williams, Mark Richardson, Robert	26	Control of a regenerative braking powered ankle foot orthosis Fleeger, Jennifer Hitt, Joesph K. Oymagil, A. Mehmet Sugar, Thomas Biard, Nicolas Chalubert, Gerard Desert, Jean-Fancois Laffont, Isabelle Leroux, Christophe Schmutz, Sophie
95	Increased range of motion and decreased muscle activity during maximal reach with gravity compensation in stroke patients Hermens, Hermie IJzerman, Maarten Jannink, Michiel Prange, Gerdienke Stienen, Arno van der Kooij, Herman	188	Recent Developments of the HLPR Chair Albus, James Bostelman, Roger Chang, Tommy
39	Exoskeleton design for functional rehabilitation in patients with neurological disorders and stroke Bureau, Maxime Eizmendi, Gorka Medina, Josep Olaiz, Edurne Perez, Maria Zabaleta, Haritz	144	Reach & Grasp Therapy: Design and Control of a 9-DOF Robotic Neuro-rehabilitation System Harwin, William Loureiro, Rui
34	Using a Robotic Gait Orthosis as Haptic Display Guidali, Marco Riener, Robert von Zitzewitz, Joachim Wellner, Mathias	25	Quasi-3-DOF Rehabilitation System for Upper Limbs: Its Force-Feedback Mechanism and Software for Rehabilitation Fukushima, Kazuki Furusho, Junji Inoue, Akio Kikuchi, Takehito Oda, Kunihiko Xinghao, Hu
187	The WILMER Elbow Orthosis Plettenburg, Dick H.	193	Optimized artificial muscles for an inherently safe robotic arm Herder, Just L. Surentu, Johan Tuijthof, Gabrielle

175	Design of a Virtual Reality-Based System For Hand and Arm Rehabilitation Adamovich, Sergei Fluet, Gerry Merians, Alma Qiu, Qinyin Talati, Binny	163 A novel experimental setup combining EEG and robotics to investigate brain activity driving controlled reaching movements in chronic stroke survivors Chen, Albert Dewald, Julius Yao, Jun
13	Stepping-in-Place Training in Virtual Environment Bajd, Tadej Koritnik, Tomaï Munih, Marko	102 Effects of Visual and Proprioceptive Motion Feedback on Human Control of Targeted Movement Gurari, Netta Kuchenbecker, Katherine J. Okamura, Allison M.
140	Haptic Device System for Upper Limb Motor and Cognitive Function Rehabilitation : Grip Movement Comparison of Normal Subjects and Stroke Patients Ito, Yuko Komeda, Takashi Lee, Hokyoo Takahashi, Yoshiyuki Terada, Takafumi	28 Passive Wrist Joint Impedance in Flexion Extension and Abduction Adduction Krebs, Hermano Igo Rijnveld, Niek
107	Concept and simulation of "Sys-Réeduc": Closed Muscular Chain Lower Limbs Rehabilitation Device Guelton, Kevin Leteneur, Sébastien Seddiki, Lynda Zaytoon, Janan	166 An Actuated Finger Exoskeleton for Hand Rehabilitation Following Stroke Colgate, J. Edward Kamper, Derek Peshkin, Michael Worsnopp, Thomas
190	Motility Evaluation of a Novel Overground Functional Mobility Tool for Post Stroke Rehabilitation Brown, David Colgate, J. Edward Crombie, Gwen Lewis, Ela Makhlin, Alex Patton, James Peshkin, Michael Santos, Julio	56 A Cable Driven Robotic System to Train Finger Function After Stroke Burdet, Etienne Chee Leong, Teo Dovat, Ludovic Gasser, Roger Johnson, Vineet Milner, Theodore Olivier, Lambercy Salman, Berna Wong, Stephen
124	Design of a 3 DOF Robotic System for use in Neurorehabilitation Jensen, Kirt James Sarkodie-Gyan, Thompson	
196	Learning-based methods for the analysis of intralimb-coordination and adaptation of locomotor patterns for cerebellar patients Giese, Martin Ilg, Winfried Röhrig, Rebecca Thier, Peter	81 Task-Orientated Biofeedback System for the Rehabilitation of the Upper Limb Caldwell, Darwin Kousidou, Sophia Smith, Christine Tsagarakis, Nikolaos

POD1 Therapy

113	Intuitive human interactive with an arm robot for severely handicapped people A One Click approach Dune, claire Leroux, christophe Marchand, Eric	54	Progress Towards the Development of a Highly Functional Anthropomorphic Transhumeral Prosthesis Fite, Kevin Goldfarb, Michael Mitchell, Jason Shen, Xiangrong Wait, Keith Withrow, Thomas
136	An fMRI compatible haptic interface with pneumatic actuation Blickenstorfer, Armin Kollias, Spyros Murr, Wolfram Riener, Robert Yu, Ningbo	86	Optoelectronic-Based Flexible Contact Sensor for Prosthetic Hand Applications Carrozza, Maria Chiara Persichetti, Alessandro Vecchi, Fabrizio
90	Methods for Evaluating and Improving Interlimb Coordination for Bimanual Robotic Therapy after Stroke Johnson, Michelle J. Wang, Sarah		
36	Development of a Systems Architecture for Robot-Aided Telerehabilitation Colombo, Roberto Delconte, Carmen Mazzone, Alessandra Minuccio, Giuseppe Pisano, Fabrizio	17	Real-time Intent Recognition for a Powered Knee and Ankle Transfemoral Prosthesis Goldfarb, Michael Varol, Huseyin Atakan
		27	Robot grasping of unknown objects, description and validation of the function with quadriplegic people Leroux, Christophe Laffont, Isabelle Biard, Nicolas Schmutz, Sophie Desert, Jean-Francois
89	Design and Construction of a Robotic Gripper for Activities of Daily Living for people with Disabilities Alqasemi, Redwan Dubey, Rajiv Mahler, Sebastian	31	Walking Phase Recognition for People with Lower Limb Disability Bien, Jzeungnam Han, Jeong-Su Jang, Hyoyoung Jung, Jin-Woo Kim, Heon-Hui Lee, Sang Wan Yi, Taeyoub
179	The SDM Hand as a Prosthetic Terminal Device: A Feasibility Study Dollar, Aaron Howe, Robert	40	A Robust Control Concept for Robotic Ankle Gait Assistance Hollander, Kevin Sugar, Thomas
147	Grasp force optimization in the design of an underactuated robotic hand Plettenburg, Dick Schuurmans, Jasper van der Helm, Frans van der Linde, Richard		

POD2 Assistive

179	The SDM Hand as a Prosthetic Terminal Device: A Feasibility Study Dollar, Aaron Howe, Robert
147	Grasp force optimization in the design of an underactuated robotic hand Plettenburg, Dick Schuurmans, Jasper van der Helm, Frans van der Linde, Richard

INT2

29	Basic Research on the Upper Limb Patient Simulator Adachi, Yoshitaka Fujisawa, Tomohiro Inoue, Kaoru Kawakami, Yukio Komeda, Takashi Lee, Hokyo Takagi, Motoki Takahashi, Yoshiyuki Terada, Takahumi	52	Active Impedance Control of a Lower-Limb Assistive Exoskeleton Aguirre-Ollinger, Gabriel Colgate, Edward Goswami, Ambarish Peshkin, Michael
98	Adaptation in velocity dependent force fields: a comparison between young and elderly subjects Carrozza, MariiaChiara Cesqui, Benedetta macri, Giovanna Micera, Silvestro Monaco, Vito	202	Development of a Mobile Arm Support (Armon): Design Evolution and Preliminary User Experience de Haan, Eelke Herder, Just Mastenbroek, Bianca van den Berg, Mieke
96	Reduction of muscle activity during repeated reach and retrieval with gravity compensation in stroke patients Hermens, Hermie Ijzerman, Maarten Jannink, Michiel Kruitbosch, Hans Maarten Prange, Gerdienke Stienen, Arno van der Kooij, Herman	38	Combined position and force control for a robot manipulator Sijss, Joris
109	Robotic Gait Trainer Reliability and Stroke Patient Case Study Balasubramanian, Sivakumar He, Jiping Sugar, Thomas Ward, Jeffrey	55	Maximizing Manipulation Capabilities for People with Disabilities Using a 9-DoF Wheelchair-Mounted Robotic Arm System Alqasemi, Redwan Dubey, Rajiv
130	Harmonic Analysis for Evaluating Circular Locus of the Tracking Exercise Imado, Keiji Ohnishi, Kengo	179	The SDM Hand as a Prosthetic Terminal Device: A Feasibility Study Dollar, Aaron Howe, Robert
35	Development of Shear Type Compact MR Brake for the Intelligent Ankle-Foot Orthosis and Its Control Akazawa, Yasushi Furusho, Junji Hashimoto, Yasunori Ikeda, Kenichi Kakehashi, Taigo Kikuchi, Takehito Morimoto, Shouji Nakagawa, Akio Tokuda, Miwa Tomiyama, Hiroki	157	Selective control of a subtask of walking in a robotic gait trainer(LOPES) Ekkelenkamp, Ralf van Asseldonk, Edwin van der Helm, Frans van der Kooij, Herman Veneman, Jan
		57	Design of a forearm rehabilitation robot Ju, Ming-Shaung Kung, Pin-Cheng Lin, Chou-Ching K.
		60	Myoelectrically Controlled Robotic System That Provide Voluntary Mechanical Help for Persons after Stroke Hu, XiaoLing Song, Rong Tong, Kaiyu Zheng, XiuJuan

43	Task Based Kinematic Design of a Serial Robot for the Treatment of Vestibular Lithiasis Berselli, Giovanni Modugno, Giovanni Carlo Vassura, Gabriele	165 ACT3D exercise targets gravity-induced discoordination and improves reaching work area in individuals with stroke DeMott, Tobey Dewald, Julius Ellis, Michael Sukal, Theresa
66	Integration of an Intelligent Decision Support System and a Robotic Haptic Device for Eye-Hand Coordination Therapy Dubey, Rajiv Edwards, Sandra Gottipati, Ramakrishna Grantner, Janos Haskin, Jill Janiak, Dana Pernalete, Norali	137 Low level control in a semi-autonomous rehabilitation robotic system via a Brain-Computer Interface Friman, Ola Gräser, Axel Lüth, Thorsten Ojdanic, Darko Prenzel, Oliver
168	Design and Development of a Haptic Peg-Board Exercise for the Rehabilitation of People with Multiple Sclerosis Louca, Loucas Xydas, Evagoras	168 Design and Development of a Haptic Peg-Board Exercise for the Rehabilitation of People with Multiple Sclerosis Louca, Loucas Xydas, Evagoras
198	MOVEMENT in progress Edelmayer, Georg Eimramhof, Peter Gelderblom, Gert Jan Huntemann, Alexander Kronreif, Gernot	103 On the control of axonal outgrowing for the development of new sieve interfaces Carpaneto, Jacopo Ciofani, Gianni Dario, Paolo
115	Evaluation of the Collaborative Wheelchair Assistant System Burdet, Etienne Chee Leong, Teo Rebsamen, Brice Zeng, Qiang	
127	Automated Interpretable Membership Functions in Human Gait Betancourt, Benjamin Gorripati, Sandhya Kong, Pui Wah Sarkodie-Gyan, Thompson	
180	Developing An Intelligent Robotic Arm for Stroke Rehabilitation Park, Hyung-Sooon Ren, Yupeng Zhang, Li-Qun	72 Rehabilitation robotics in Padua, Italy Rosati, Giulio Rossi, Aldo
		73 Realization and Evaluation of Assistive Human-Mechatronic Systems with Human-friendly Robotic Agents at HWRS-ERC Bien, Z. Zenn Chang, Pyung-Hun Do, Jun-Hyeong Lee, Hyong-Euk Park, Sang Hyun Park, Kwang-Hyun Park, Sukhoon Yoon, Yong-San

Lab

72	Rehabilitation robotics in Padua, Italy Rosati, Giulio Rossi, Aldo
73	Realization and Evaluation of Assistive Human-Mechatronic Systems with Human-friendly Robotic Agents at HWRS-ERC Bien, Z. Zenn Chang, Pyung-Hun Do, Jun-Hyeong Lee, Hyong-Euk Park, Sang Hyun Park, Kwang-Hyun Park, Sukhoon Yoon, Yong-San

INT3

- 101 **Analysis and synthesis of human and machine motion at UL FE**
Bajd, Tadej
Inkelj, Justin
Kamnik, Roman
Koritnik, Tomaž
Kurillo, Gregorij
Mali, Uroš
Mihelj, Matjaž
Munih, Marko
Perdan, Jernej
Podobnik, Janez
Veber, Mitja
- 114 **Research on Rehabilitation Engineering at ARTS Lab, Scuola Superiore Sant'Anna, Pisa, Italy**
Beccai, Lucia
Carpaneto, Jacopo
Carrozza, Maria Chiara
Dario, Paolo
Laschi, Cecilia
Mazzoleni, Stefano
Micera, Silvestro
Odetti, Luca
Pisetta, Andrea
Roccella, Stefano
Vecchi, Fabrizio
- 184 **Some Key Problems for Robot-Assisted Movement Therapy Research: A Perspective from the University of California at Irvine**
Bobrow, James E.
Galvez, Jose A.
Marchal, Laura
Reinkensmeyer, David J.
Wolbrecht, Eric T.
- 192 **The Delft Laboratory for Neuromuscular Control: Haptic Robots for the Identification of Neuro-Muscular Control**
de Vlugt, Erwin
Schouten, Alfred
van der Helm, Frans
- 201 **Exoskeletons for Gait Assistance and Training of the Movement**
Agrawal, Sunil
- 148 **Decomposition-Based Control for a Powered Knee and Ankle Transfemoral Prosthesis**
Goldfarb, Michael
Varol, Huseyin Atakan
- 148 **Decomposition-Based Control for a Powered Knee and Ankle Transfemoral Prosthesis**
Goldfarb, Michael
Varol, Huseyin Atakan
- 158 **Characterization of a New Type of Dry Electrodes for Long-Term Recordings of Surface-Electromyogram**
Dario, Paolo
Garcia, Gonzalo A.
Hoffmann, Klaus-Peter
Micera, Silvestro
Ruff, Roman
Zaccone, Franco
- 111 **Single-Trial EEG Classification of Movement Related Potential**
Castelo-Branco, Miguel
Nunes, Urbano
Pires, Gabriel
- 160 **Vision-based control of the Manus using SIFT**
Liefhebber, Freek
- 133 **Evaluation of a VMC for the selective support of gait functions using an exoskeleton**
Ekkelenkamp, Ralf
van der Kooij, Herman
- 84 **Active Leg Exoskeleton (ALEX) for Gait Rehabilitation of Motor-Impaired Patients**
Agrawal, Sunil
Banala, Sai
Scholz, John
- 37 **Mechanical Design of an Active Knee Orthosis for Gait Rehabilitation**
Beyl, Pieter
Lefeber, Dirk
Naudet, Joris
Van Ham, Ronald

149	Novel Compliant Actuator for Safe and Ergonomic Rehabilitation Robots Design of a Powered Elbow Orthosis Lefever, Dirk Naudet, Joris Van Ham, Ronald Vanderborght, Bram Vanderniepen, Innes Versluis, Rino	32	ARMin Exoskeleton for Arm Therapy in Stroke Patients Kiefer, Gabriela Mihelj, Matjaz Müller, Roland Nef, Tobias Perndl, Christina Riener, Robert
50	A Fast Motion Planning for a 7DOF Rehabilitation Robot Axel, Graeser Darko, Ojdanic	67	Development of Ankle Dorsiflexion/Plantarflexion Exercise Device with Passive Mechanical Joint Homma, Keiko Usuba, Mariko
70	Designing multimodal interaction for assistive robotic arm Hariz, Mossaab Mokhtari, Mounir Renouard, Stéphane	74	Iterative Learning Synchronization of Robotic Rehabilitation Tasks Banz, Raphael Duschau-Wicke, Alexander Riener, Robert von Zitzewitz, Joachim
106	Simple Obstacle Avoidance Algorithm for Rehabilitation Robots Römer, G.R.B.E. Stuyt, F.H.A. Stuyt, H.J.A.	171	Design of a Mobile, Inexpensive Device for Upper Extremity Rehabilitation at Home Patton, James Peshkin, Michael Sulzer, James
150	Complementary Limb Motion Estimation based on Interjoint Coordination: Experimental Evaluation Buss, Martin Ekkelenkamp, Ralf Vallery, Heike van der Kooij, Herman	36	Development of a Systems Architecture for Robot-Aided Telerehabilitation Colombo, Roberto Delconte, Carmen Mazzone, Alessandra Minuccio, Giuseppe Pisano, Fabrizio
100	Passive therapeutic arm for pelvis support during FES supported gait treadmill training a case study Cikajlo, Imre Obreza, Pavla ?avrin, Rajmond Zlatko Matja, Zlatko	132	Phonetic Control: A new Approach for Continuous, Non-invasive Device Control Using the Vocal Tract Hainisch, Reinhard Platz, Michael
122	Arm rehabilitation with a robotic exoskeleton in Virtual Reality Bergamasco, Massimo Borelli, Luigi Carboncini, Maria C. Frisoli, Antonio Marcheschi, Simone Montagner, Alberto Procopio, Caterina Rossi, Bruno Salsedo, Fabio Tolaini, Martina	153	Dampace: dynamic force-coordination trainer for the upper extremities Aalsma, Arthur Hekman, Edsdo Jannink, Michiel Prange, Gerdienke Stienen, Arno Van der Helm, Frans van der Kooij, Herman
		71	Behavior-Based Path Modification for Shared Control of Robotic Walking Aids Graf, Birgit Schraft, Rolf D.

69	A 6-DOF Rehabilitation Support System for Upper Limbs including Wrists "Robotherapist" with Physical Therapy Furusho, Junji Jin, Ying Kikuchi, Takehito Morita, Tomoko Oda, Kunihiko Ohyama, Yuuki Shichi, Naoto	120	Determination of pathological clonus characteristics using a haptic ankle manipulator Arendzen, Hans de Groot, Jurriaan de Vlugt, Erwin Meskers, Carel van der Helm, Frans Wisman, Wessel
76	Pathological Sit-To-Stand Models for Control of a Rehabilitation Robotic Device Gas, Bruno Pasqui, Viviane Saint-Bauzel, Ludovic Zarader, Jean-Luc	33	Comparison of grip action triggered by haptic or visual cue Munih, Marko Podobnik, Janez
199	Dynamically Removing Partial Body Mass using Acceleration Feedback for Neural Training Ma, Ou Sarkodie-Gyan, Thompson	58	Development of a Hand Motion Assist Robot for Rehabilitation Therapy by Patient Self-Motion Control Abe, Motoyuki Aoki, Takaaki Ishigure, Yasuhiko Itho, Satoshi Kawasaki, Haruhisa Mouri, Tetuya Nishimoto, Yutaka Sakaeda, Hirofumi
172	Usage of the ACT3D Robot in a Brain Machine Interface for Hand Opening and Closing in Stroke Survivors Dewald, Julius Sheaf, Clay Yao, Jun	195	Design, Characterization, and Impedance Limits of a Hand Robot Cappa, Paulo Hogan, Neville Krebs, Hermano Igo Masia, Lorenzo
176	Use of the ACT3D System to Evaluate Synergies in Children with Spastic Hemiparetic Cerebral Palsy: A Pilot Study Dewald, Julius Krosschell, Kristin Sukal, Theresa	164	MR_CHIROD v.2: A fMRI Compatible Mechatronic Hand Rehabilitation Device Khanicheh, Azadeh Mavroidis, Constantinos Mintzopoulos, Dionysios Tzika, A. Aria Weinberg, Brian
77	Measurement of Human Ankle Stiffness Using the Anklebot Forrester, Larry Hogan, Neville Judkins, Timothy Khanna, Ira Krebs, Hermano Macko, Richard Patterson, Shawnna Roy, Anindo	152	Assistive Technology: A novel approach to evaluation Aquilano, Michela Carrozza, Maria Chiara Chiarugi, Federico Di Lauro, Giuseppina Anna Giachetti, Giacomo Pisetta, Andrea Salatino, Claudia
169	A Tele-Assessment System for Evaluating Arm Impairments in Patients with Neurological Disorders Park, Hyung-Soon Ren, Yupeng Wu, Yi-Ning Zhang, Li-Qun		

POD3 Assistive II

152	Assistive Technology: A novel approach to evaluation Aquilano, Michela Carrozza, Maria Chiara Chiarugi, Federico Di Lauro, Giuseppina Anna Giachetti, Giacomo Pisetta, Andrea Salatino, Claudia
-----	---

99	Compiling a Medical Device File and a Proposal for an International Standard for Rehabilitation Robots Römer, GertWillem R. B. E. Stuyt, Harry J. A.	174 Development of Vision-Based Navigation for a Robotic Wheelchair Bailey, Matt Chanler, Andrew Maxwell, Bruce Micire, Mark Tsui, Katherine Yanco, Holly
42	Rehabilitation walker system with standing assistance Asama, Hajime Chugo, Daisuke Matsuoka, Wataru Songmin, Jia Takase, Kuniatsu	51 A Configuration-Space Approach to Controlling a Rehabilitation Arm Exoskeleton Carignan, Craig Naylor, Michael Roderick, Stephen Tang, Jonathan
64	Design of the Modular Arm Robot System Breitwieser, Helmut Bretthauer, Georg Kargov, Artem Klosek, Heinrich Pylatiuk, Christian Schulz, Stefan	68 Biomechanical Design of a Powered Ankle-Foot Prosthesis Au, Samuel Herr, Hugh Weber, Jeff
180	Developing An Intelligent Robotic Arm for Stroke Rehabilitation Park, Hyung-Soon Ren, Yupeng Zhang, Li-Qun	

POD4 Control

92	Real-Time Control of the Hand by Intracortically Controlled Functional Neuromuscular Stimulation Kilgore, Kevin Kirsch, Robert Miller, Lee Perreault, Eric Pohlmeyer, Eric Slutzky, Marc Taylor, Dawn	167 Design and Control of an Electrically Powered Knee Prosthesis Fite, Kevin Goldfarb, Michael Mitchell, Jason Sup, Frank
137	Low level control in a semi-autonomous rehabilitation robotic system via a Brain-Computer Interface Friman, Ola Gräser, Axel Lüth, Thorsten Ojdanic, Darko Prenzel, Oliver	93 A Real-Time EMG-based Assistive Computer Interface for the Upper Limb Disabled Choi, Changmok Kim, Jung
		117 Investigating Novel Interaction Techniques for Older People Hwang, Faustina Williams, Nitin
		119 Brain-Computer Interface for high-level control of rehabilitation robotic systems Cyricks, Marco Friman, Ola Graeser, Axel Valbuena, Diana Volosyak, Ivan

53	User involvement in developing Rehabilitation Robotic devices: An essential requirement Bhakta, Bipin Cozens, Alastair Culmer, Pete Holt, Raymond Jackson, Andrew Levesley, Martin Makower, Sophie Mon-Williams, Mark Richardson, Robert	68	Biomechanical Design of a Powered Ankle-Foot Prosthesis Au, Samuel Herr, Hugh Weber, Jeff
54	Progress Towards the Development of a Highly Functional Anthropomorphic Transhumeral Prosthetic Fite, Kevin Goldfarb, Michael Mitchell, Jason Shen, Xiangrong Wait, Keith Withrow, Thomas	152	Assistive Technology: A novel approach to evaluation Aquilano, Michela Carrozza, Maria Chiara Chiarugi, Federico Di Lauro, Giuseppina Anna Giachetti, Giacomo Pisetta, Andrea Salatino, Claudia
51	A Configuration-Space Approach to Controlling a Rehabilitation Arm Exoskeleton Carignan, Craig Naylor, Michael Roderick, Stephen Tang, Jonathan	42	Rehabilitation walker system with standing assistance Asama, Hajime Chugo, Daisuke Matsuoka, Wataru Songmin, Jia Takase, Kunikatsu
88	Passive Orthosis Linkage for Locomotor Rehabilitation Berkelman, Peter Lu, Timothy Ma, Ji Rossi, Peter	65	An Approach to Consider Upper Limb Kinematics for the Improvement of Motion Control in a Two Arm Robotic Rehabilitation System Fazekas, Gabor Horvath, Monika Jurak, Mihaly Toth, Andras
113	Intuitive human interactive with an arm robot for severely handicapped people A One Click approach Dune, claire Leroux, christophe Marchand, Eric	79	Adaptive robot training in the rehabilitation of incoordination in Multiple Sclerosis: a pilot study Brichetto, Giampaolo Casadio, Maura Sanguineti, Vittorio Solaro, Claudio Squeri, Valentina Vergaro, Elena
64	Design of the Modular Arm Robot System Breitwieser, Helmut Bretthauer, Georg Kargov, Artem Klosek, Heinrich Pylatiuk, Christian Schulz, Stefan	194	Muscle activation patterns of healthy subjects during floor walking and stair climbing on an end-effector-based gait rehabilitation robot Helmich, Ingo Hesse, Stefan Krueger, Joerg Piorko, Frank

173	Design of a Grasp Assistive Glove for ADL-focused, Robotic Assisted Therapy after Stroke Johnson, Michelle J. Nathan, Dominic	116	Brain-Computer Interface for a Prosthetic Hand Using Local Machine Control and Haptic Feedback Acharya, Soumyadipta Aggarwal, Vikram Chatterjee, Aniruddha Cho, Yoonju Orourke, Brandon Ramos Murguialday, Ander Rasmussen, Robert Thakor, Nitish V.
82	Performance of cable suspended robots for upper limb rehabilitation Andreolli, Mattia Biondi, Andrea Gallina, Paolo Rosati, Giulio	128	Wireless Temperature Sensing Cosmesis for Prostheses Cho, Yoonju Folowosele, Fopefolu Liang, Kelvin Miller, Brian Thakor, Nitish
91	STRING-MAN: Wire-robot technology for safe, flexible and human-friendly gait rehabilitation Bernhardt, Rolf Surdilovic, Dragoljub Zhang, Jingyu	30	Applying a 3DOF Orientation Tracker as a Human-Robot Interface for Autonomous Wheelchairs Frese, Udo Mandel, Christian Röfer, Thomas
203	Structural Design of an Escort Type Rehabilitation Robot for Post-Stroke Therapies of Upper-Limb Harwin, William Kojima, Yoshimasa Loureiro, Rui Nagai, Kiyoshi Okubo, Takashi Yonemoto, Shinya	174	Development of Vision-Based Navigation for a Robotic Wheelchair Bailey, Matt Chanler, Andrew Maxwell, Bruce Micire, Mark Tsui, Katherine Yanco, Holly
49	Localization method for a Rehabilitation mobile robot using visual and ultrasonic information Aitoufroukh, Naima Lelandais, Sylvie Trabelsi, Mohamed	80	Omni-directional wheelchair in reality and virtuality Evans, Nina Gibbs, Christopher Hillman, Michael
181	Toward a Scalable Home-Care Delivery for Frail Elders and People with Special Needs Abdulrazak, Bessam	125	Identification of Human Gait using Fuzzy Inferential Reasoning Brower, Richard David Ceberio, Martine Nava, Patricia Sarkodie-Gyan, Thompson Yu, Huiying
185	An Interactive Receptionist Robot for Users with Vocal Pathologies Mumolo, Enzo Nolich, Massimiliano Vercelli, Gianni	146	Joint Moments Exhibited by Chronic Stroke Subjects While Walking with a Prescribed Physiological Gait Pattern Hidler, Joseph Neckel, Nathan Nichols, Diane
189	Design of a Dynamic Arm Support (DAS) for gravity compensation Kramer, Gijs Römer, GertWillem Stuyt, Harry		

161	Recording experience with the thin-film Longitudinal Intra-Fascicular Electrode, a multichannel peripheral nerve interface Citi, Luca Koch, Klaus Peter Kurstjens, Mathijs Micera, Silvestro Yoshida, Ken	147	Grasp force optimization in the design of an underactuated robotic hand Plettenburg, Dick Schuurmans, Jasper van der Helm, Frans van der Linde, Richard
123	Neurobiological evaluation of thin-film longitudinal intrafascicular electrodes as a peripheral nerve interface Koch, Klaus Lago, Natalia Micera, Silvestro Navarro, Xavier Poppendieck, Wigand Vivó, Meritxell Yoshida, Ken	99	Compiling a Medical Device File and a Proposal for an International Standard for Rehabilitation Robots Römer, GertWillem R. B. E. Stuyt, Harry J. A.
136	An fMRI compatible haptic interface with pneumatic actuation Blickenstorfer, Armin Kollias, Spyros Murr, Wolfram Riener, Robert Yu, Ningbo	110	Arm-Training with T-WREX after Chronic Stroke: Preliminary Results of a Randomized Controlled Trial Housman, Sarah Le, Vu Rahman, Tariq Reinkensmeyer, David Sanchez, Robert
		178	Active Orthoses for the Lower-Limbs: Challenges and State of the Art Dollar, Aaron Herr, Hugh
		134	Foot orthosis strain sensing in hill walking Holmberg, Ulf Salomonsson, Tommy Svensson, Wolfgang
41	Non-Invasive, Wireless and Universal Interface for the Control of Peripheral Devices by Means of Head Movements Azkoitia, Jose Miguel Bureau, Maxime Eizmendi, Gorka Manterola, Iraitz Medina, Josep Perez, Maria Zabaleta, Haritz	135	Robust Color Object Recognition for a Service Robotic Task in the System FRIEND II Graeser, Axel Grigorescu, Sorin Mihai Ristic, Danijela Vuppala, Sai Krishna
141	Energy-Free Adjustment of Gravity Equilibrators Using the Virtual Spring Concept Barents, Rogier Herder, Just L. van Dorsser, Wouter D. Wissem, Boudewijn M.	89	Design and Construction of a Robotic Gripper for Activities of Daily Living for people with Disabilities Alqasemi, Redwan Dubey, Rajiv Mahler, Sebastian
145	Characterization of the Dynamic Properties of Pneumatic Muscle Actuators Balasubramanian, Sivakumar He, Jiping	87	Combining Immersive Virtual Environments with Robot-Aided Gait Training Banz, Raphael Colombo, Gery Lünenburger, Lars Riener, Robert Wellner, Mathias

INT5

90	Methods for Evaluating and Improving Interlimb Coordination for Bimanual Robotic Therapy after Stroke Johnson, Michelle J. Wang, Sarah	62	Human-robot interface with anticipatory characteristics based on Laban Movement and Bayesian models Dias, Jorge Rett, Jörg
162	Evaluation of the effect on walking of balance-related degrees of freedom in a robotic gait training device. Ekkelenkamp, Ralf van Asseldonk, Edwin van der Helm, Frans van der Kooij, Herman Veneman, Jan	86	Optoelectronic-Based Flexible Contact Sensor for Prosthetic Hand Applications Carrozza, Maria Chiara Persichetti, Alessandro Vecchi, Fabrizio
151	Freebal: dedicated gravity compensation for the upper extremities Aalsma, Arthur Hekman, Edsko Jannink, Michiel Prange, Gerdienke Stienen, Arno Van der Helm, Frans van der Kooij, Herman	108	Development of a Multifunctional Cosmetic Prosthetic Hand Kargov, Artem Klosek, Heinrich Oberle, Reinhold Pylatiuk, Christian Roessler, Wolfgang Schulz, Stefan Werner, Tino
81	Task-Orientated Biofeedback System for the Rehabilitation of the Upper Limb Caldwell, Darwin Kousidou, Sophia Smith, Christine Tsagarakis, Nikolaos	105	Classification of EMG signals through wavelet analysis and neural networks for controlling an active hand prosthesis Gini, Giuseppina Arvetti, Matteo Folgheraiter, Michele
83	An Experimental Facility using Functional Electrical Stimulation for Stroke Rehabilitation of the Upper Limb Burridge, Jane Chappell, Paul Freeman, Chris Hughes, Ann-Marie Lewin, Paul Rogers, Eric	47	Torque sensor free power assisted wheelchair Holmberg, Ulf Johansson, Jonas Pettersson, Daniel
156	Towards Realistic Facial Behaviour in Humanoids Mapping from Video Footage to a Robot Head Campbell, Neill Jaekel, Peter Melhuish, Chris	183	Controlling a wheelchair using a BCI with low information transfer rate Ang, Marcelo Burdet, Etienne Guan, Cuntai Laugier, Christian Rebsamen, Brice Teo, Chee Leong Zeng, Qiang
142	Observing conversational expressiveness of elderly users interacting with a robot and screen agent Evers, Vanessa Heerink, Marcel Kröse, Ben Wielinga, Bob	126	Determination of Human Gait Phase Using Fuzzy Inference Brower, Richard Ceberio, Martine MacDonald, Chad Sarkodie-Gyan, Thompson Smith, Darla

154	Comparison of Neurosensorimotor Adaptation Under Kinematic and Dynamic Distortions Carignan, Craig Contreras-Vidal, Jose L. Tang, Jonathan	182	Peripheral Nerve Signals for Neural Control Durand, Dominique Tesfayesus, Wondimeneh Yoo, Paul
139	Analysis of the Fugl-Meyer Outcome Measures Assessing the Effectiveness of Robot-Mediated Stroke Therapy Amirabdollahian, Farshid Harwin, William Loureiro, Rui	85	Adaptive Shared Control of a Brain-Actuated Simulated Wheelchair Ferrez, Pierre Lew Yi Lee, Eileen Milla'n, José del R. Moles, Ferran Galan Nuttin, Marnix Philips, Johan van Brussel, Hendrik Vanacker, Gerolf
112	Reduced Power: how to evoke low bandwidth motion control behaviour while estimating full bandwidth admittance Abbink, David Mugge, Winfred Van der Helm, Frans	97	Robot-mediated Active Rehabilitation (ACRE) A user trial Campagne, Antonet Schoone, Marian van Os, Peter
191	Detecting asymmetries in balance control with system identification: first experimental results from above knee amputees Nederhand, Mark van Asseldonk, Edwin van der Kooij, Herman		
92	Real-Time Control of the Hand by Intracortically Controlled Functional Neuromuscular Stimulation Kilgore, Kevin Kirsch, Robert Miller, Lee Pereault, Eric Pohlmeyer, Eric Slutzky, Marc Taylor, Dawn		
129	Development of a Robot-Assisted Rehabilitation Therapy to train Hand Function for Activities of Daily Living Burdet, Etienne Burdet Dovat, Ludovic Gassert, Roger Gassert Johnson, Vineet Lamberg, Olivier Milner, Theodore Milner Salman, Berna Teo Chee Leong, Teo Chee Leong Wong, Stephen		

POD5 Therapy

- 157 **Selective control of a subtask of walking in a robotic gait trainer(LOPES)**
Ekkelenkamp, Ralf
van Asseldonk, Edwin
van der Helm, Frans
van der Kooij, Herman
Veneman, Jan
- 79 **Adaptive robot training in the rehabilitation of in-coordination in Multiple Sclerosis: a pilot study**
Brichetto, Giampaolo
Casadio, Maura
Sanguineti, Vittorio
Solaro, Claudio
Squeri, Valentina
Vergaro, Elena
- 144 **Reach & Grasp Therapy: Design and Control of a 9-DOF Robotic Neuro-rehabilitation System**
Harwin, William
Loureiro, Rui
- 87 **Combining Immersive Virtual Environments with Robot-Aided Gait Training**
Banz, Raphael
Colombo, Gery
Lünenburger, Lars
Riener, Robert
Wellner, Mathias
- 163 **A novel experimental setup combining EEG and robotics to investigate brain activity driving controlled reaching movements in chronic stroke survivors**
Chen, Albert
Dewald, Julius
Yao, Jun