

## Program in Short

### Wednesday 25<sup>th</sup> of May, 2011

9:00-18:00	<b>Registration</b>
9:00-15:00	<p align="center"><b>Joint Industry-Research Networking and Matchmaking Meeting</b></p> <p align="center"><b>Technical Visits</b>  <b>Fastems Oy Ab:</b> <a href="http://www.fastems.com/">http://www.fastems.com/</a>  <b>Avant Tecno Oy:</b> <a href="http://www.avanttecno.com/">http://www.avanttecno.com/</a>  <b>Katsa Oy:</b> <a href="http://www.katsa.fi/">http://www.katsa.fi/</a>  <b>Agco Sisu Power Oy:</b> <a href="http://www.agcosisupower.com/">http://www.agcosisupower.com/</a>  <b>TUT/Department of Production Engineering:</b> <a href="http://www.tut.fi/tte">http://www.tut.fi/tte</a>  <b>VTT Technical Research Centre of Finland:</b> <a href="http://www.vtt.fi/">http://www.vtt.fi/</a></p>
15:00-17:30	<p align="center"><b>Opening Ceremony</b> <i>Location: Studio</i></p> <p align="center"><b>Plenary Session</b> <i>Chair: Prof. Reijo Tuokko, Tampere University of Technology, Finland</i> <i>Location: Studio</i></p> <p><b>Keynote 1:</b> Challenges of Manufacturing in the Future - <i>Prof. Paul H. Andersson, Tampere University of Technology, Finland</i></p> <p><b>Keynote 2:</b> Lean Product and Process Development for Competitive Enterprises - <i>Prof. F. Frank Chen, University of Texas at San Antonio, USA</i></p> <p><b>Keynote 3:</b> Novel industrial robot systems for manufacturing in Japan - <i>Prof. Tamio Arai, The University of Tokyo, Japan</i></p>
18:00-20:00	<p align="center"><b>IEEE ISAM 2011 Reception</b> <i>Chair: Prof. Reijo Tuokko, Dr. Minna Lanz, Tampere University of Technology, Finland</i> <i>Location: Restaurant Fuuga, Tampere Hall</i></p>

### Thursday 26<sup>th</sup> of May, 2011

8:30-9:20	<p align="center"><b>Keynote Plenary Session</b> <i>Chair: Prof. Tamio Arai, The University of Tokyo, Japan</i> <i>Location: Studio</i></p> <p align="center"><b>Keynote 4:</b> Concrete and Fiber of the Toyota Production System - <i>Richard P. Alloo, Toyota Motor Engineering and Manufacturing North America, Inc., US</i></p>		
9:20-9:40	<p align="center">Coffee Break</p>		
9:40-11:00	<p>Session 1A1: Micro and Macro Assembly and Manufacturing Processes: CNC</p> <p align="center"><i>Chair: Prof. Paul H. Andersson, Tampere University of Technology</i> <i>Location: Studio</i></p> <p><b>ID:111</b> Member Stiffnesses and Interface Contact Characteristics of Bolted Joints, <i>Zhaohui Yang</i>  <b>ID:147</b> An error compensation method for</p>	<p>Session 1B1: Competitive and Sustainable Production and Systems: Towards Sustainable Systems</p> <p align="center"><i>Chair: Prof. Esko Niemi, Aalto University</i> <i>Location: Sonaatti 1</i></p> <p><b>ID: 132</b> Improving accuracy of aging CNC machines without physical changes, <i>Kimmo Mäkelä</i>  <b>ID:189</b> Implementation of Energy-Related Aspects into Model-Based Design of</p>	<p>Session 1C1: Digital Manufacturing: Utilization of Knowledge and Information Systems</p> <p align="center"><i>Chair: Dr. Tero Juuti, Tampere University of Technology</i> <i>Location: Sonaatti 2</i></p> <p><b>ID:181</b> Presenting capabilities of resources and resource combinations to support production system adaptation, <i>Eeva Järvenpää</i>  <b>ID:192</b> User-Centric</p>

	<p>multi-axis machining based on the actual contour measurement, <i>Xuwei Li</i>  <b>ID:194</b> Dynamic Stabilization of Technological Systems for Processing Edge Cutting Through the Local Metastability, <i>Marten Madisoo</i>  <b>ID:224</b> Milling Estimation Study, Assuming Estimation of Cutting Force, <i>Virginija Gyliene</i></p>	<p>Processes and Process Chains, <i>Sven Goller</i>  <b>ID:209</b> Analysis of Learning Pallets in Flexible Scheduling by Closed Queue Network, <i>Afshin Mehraei</i></p>	<p>Development Of Simulation Based Manufacturing Operation Planning And Scheduling System, <i>Juhani Heilala</i>  <b>ID:233</b> Assessing the cost of robust capacity allocation for serving dynamic customer demand, <i>Thomas Makuschewitz</i></p>
11:00-11:20	Coffee Break		
11:20-12:40	<p>Session 1A2: Micro and Macro Assembly and Manufacturing Processes: Miniaturized Robotics and Assembly Systems  <i>Chair: Mr. Riku Heikkilä, Tampere University of Technology</i>  <i>Location: Studio</i></p> <p><b>ID:102</b> Fuzzy Logic based Ultrasonic Gripper Design for Handling Small Parts, <i>Thomas Kirchmeier</i>  <b>ID:122</b> Micro Robot for Rotary Desktop Assembly Line, <i>Philipp Kobel</i>  <b>ID:216</b> Pollution Monitoring Sensor for a Micro-Factory, <i>Miroslav Kral</i></p>	<p>Session 1B2: Competitive and Sustainable Production and Systems: Sustainable System Units and Systems  <i>Chair: Dr. Mikko Koho, Tampere University of Technology</i>  <i>Location: Sonaatti 1</i></p> <p><b>ID:130</b> The Effect of Short-term Planning Delays in Multi-Item Production-Inventory Systems, <i>prof. Esko Niemi</i>  <b>ID:156</b> Limitations in Modeling Autonomous Logistic Processes - Challenges and Solutions in Business Process Modeling, <i>Daniel Rippel</i>  <b>ID:195</b> Ambient Intelligence Based Monitoring And Energy Efficiency Optimisation System, <i>Juhani Heilala</i></p>	<p>Session 1C2: Digital Manufacturing: Merging the Real and Virtual Environments  <i>Chair: Mr. Hasse Nylund, Tampere University of Technology</i>  <i>Location: Sonaatti 2</i></p> <p><b>ID:141</b> Development of production cells with regard to physical and cognitive automation - A decade of evolution, <i>Sandra Mattsson</i>  <b>ID:177</b> Triple Stereo Vision System for Safety Monitoring of Human-Robot Collaboration in Cellular Manufacturing, <i>prof. Tamio Arai</i>  <b>ID:231</b> On the integration of skilled robot motions for productivity in manufacturing, <i>Klas Nilsson</i>  <b>ID:235</b> Dynamic Operation Environment – Towards Intelligent Adaptive Production Systems, <i>Pasi Luostarinen</i></p>
12:40-13:40	Lunch Break		
13:40-15:00	<p>Session 1A3: Micro and Macro Assembly and Manufacturing Processes: Gears and Bearings  <i>Chair: Prof. Michael Yu Wang, The Chinese University of Hong Kong</i>  <i>Location: Studio</i></p> <p><b>ID:133</b> A Zero Wear Assembly of a Hydrodynamic Bearing and a Rolling Bearing, <i>Dun Lui</i></p>	<p>Special Session 1B3: Evolvable Production Systems  <i>Chair: Mr. Antonio Maffei, KTH Royal Institute of Technology</i>  <i>Location: Sonaatti 1</i></p> <p><b>ID:184</b> Evolvable Production Systems: a new business environment, <i>Antonio Maffei</i>  <b>ID:203</b> Where EPS meets Complexity Science, <i>Luis Ribeiro</i></p>	<p>Session 1C3: Digital Manufacturing: Modelling and Measurement aspects  <i>Chair: Prof. Heikki Tikka, Tampere University of Technology</i>  <i>Location: Sonaatti 2</i></p> <p><b>ID:95</b> Process Planning Based on Feature Recognition Method, <i>Fernando Garcia</i>  <b>ID:183</b> Efficiency</p>

	<p><b>ID:135</b> Theoretical Method to Reduce the Non-repetitive Run- out (NRRO) of Angular Contact Ball Bearings, <i>ZhaoHui Yang</i></p> <p><b>ID:172</b> Finite Element Simulation of an Analogy Process for the Fine Blanking of Helical Gears, <i>Martin Zimmermann</i></p>	<p><b>ID:165</b> Evolvable Production Systems and Impacts on Production Planning, <i>Hakan Akillioglu</i></p>	<p>Improvement in Generation of a Contact State Graph by Eliminating Unnecessary Elements, <i>Sung Jo Kwak</i></p> <p><b>ID:186</b> A Central Axis and Radius Estimation Method for Torus Object Modeling, <i>Kyeongdae Yoo</i></p>
15:00-15:20	Coffee Break		
15:20-16:40	<p>Session 1A4: Micro and Macro Assembly and Manufacturing Processes: Advances in Material Science</p> <p><i>Chair: Mr. Jorma Vihinen, Tampere University of Technology</i> <i>Location: Studio</i></p> <p><b>ID:155</b> Innovative Developments For Automated Magnet Handling And Bonding Of Rare Earth Magnets, <i>Jan Tremel</i></p> <p><b>ID:160</b> A New Method for Glass-Fiber Reinforced Composites Manufacturing: Automated Fiber Placement with In-situ UV Curing, <i>Dilimulati Abulizi</i></p> <p><b>ID:227</b> Machining of a Hollow Shaft Made of b-Titanium Ti-10V-2Fe-3Al, <i>Christian Machai</i></p>	<p>Special Session 1B4: Micro and Macro Assembly and Manufacturing Processes: Microfactories</p> <p><i>Chair: Prof. Kensuke Tsuchiya, The University of Tokyo</i> <i>Location: Sonaatti 1</i></p> <p><b>ID:97</b> microFLEX - A New Concept to Address the Needs for Adaptable Meso and Micro Assembly Lines, <i>Andreas Hofmann</i></p> <p><b>ID:173</b> Modular Microfactory System for Gas Sensor Assembly, <i>Niko Siltala</i></p> <p><b>ID:220</b> Evolvable Micro Production Systems: Specific Needs and Differences to Macro, <i>Andreas Hofmann</i></p>	<p>Session 1C4: Digital Manufacturing: Advances in sheet metal products' manufacturing</p> <p><i>Chair: Mr. Juhani Heilala, VTT Technical Research Centre of Finland</i> <i>Location: Sonaatti 2</i></p> <p><b>ID:99</b> DFMA-Aspects of sheet metal product in case of low-cost strategy, <i>Merja Huhtala</i></p> <p><b>ID:143</b> Observations of Applying DFM(A) in MW Mechanics and Sheet Metal Work, <i>Mika Lohtander</i></p> <p><b>ID:207</b> Feature Precedence Graphs as an Approach for the Forming Operations Planning of Integral Sheet Metal Parts, <i>Oliver J. Weitzmann</i></p>
16:40-17:40	Research Forum and Networking Event <i>Location: Lobby 1<sup>st</sup> floor, Studio</i>		
19:30-22:30	<p>Banquette Juvenes Restaurant Ziberia Itäinkatu 9 33210 Tampere</p>		

## Friday 27<sup>th</sup> of May, 2011

8:30-9:20	<p><b>Keynote Plenary Session</b></p> <p><i>Chair: Prof. Reijo Tuokko, Tampere University of Technology, Finland</i> <i>Location: Studio</i></p> <p><b>Keynote 5: Implementing Sustainable Manufacturing for Innovation at Product, Process and Systems Levels – Prof. I.S. Jawahir, University of Kentucky, US</b></p>
9:20-9:40	Coffee Break

9:40-11:00	<p>Session 2A1: Micro and Macro Assembly and Manufacturing Processes: Process Improvement <i>Chair: Dr. Raúl Suárez, Universitat Politècnica de Catalunya</i> <i>Location: Studio</i></p> <p><b>ID:107</b> Development of Permanent Lubrication Using Grease on the Slide in the Machine Tool for Economical and Eco-friendly, <i>Ikuo Tanabe</i> <b>ID:148</b> Fluid-Structure Interactions (FSI) on Static Characteristics of Hydrostatic Guideways, <i>Jun Zhang</i> <b>ID:151</b> Modal analysis of machine tools during working process by matrix perturbation method, <i>Haitao Li</i></p>	<p>Special Session 2B1: Robot-based Automation of Nanohandling Processes I  <i>Chair: Mr. Daniel Jasper, University of Oldenburg</i> <i>Location: Sonaatti 1</i></p> <p><b>ID:129</b> 3-Dimensional Electrokinetic Tweezing for Micro and Nano Assembly, <i>Roland Probst</i> <b>ID:161</b> Assembly of a novel MEMS-based 3D vibrating micro-scale co-ordinate measuring machine probe using desktop factory automation, <i>James D Claverley</i> <b>ID:182</b> Automated robot-based separation and palletizing of microcomponents, <i>Daniel Jasper</i></p>	<p>Session 2C1: Micro and Macro Assembly and Manufacturing Processes: CNC <i>Chair: Mr. Andreas Hofmann, Karlsruhe Institute of Technology</i> <i>Location: Sonaatti 2</i></p> <p><b>ID:157</b> Dynamic Transmission Error Analysis for A CNC Machine Tool Based on Built-In Encoders, <i>Dilimulati Abulizi</i> <b>ID:167</b> Measuring mechanical properties of micro structures using micro manipulator with low rigidity, <i>Kensuke Tsuchiya</i> <b>ID:170</b> Multiple-axis Synchronization Evaluation for CNC Machine Tool Based on Sensorless Measurement, <i>Lin Jing</i> <b>ID:219</b> Failure prediction by means of cepstral analysis and coherence function between thrust force and torque signals, <i>Jaroslava Janekova</i></p>
11:00-11:20	Coffee Break		
11:20-12:40	<p>Session 2A2: Micro and Macro Assembly and Manufacturing Processes: Intelligent Robotics  <i>Chair: Dr. Klas Nilsson, Lund Institute of Technology</i> <i>Location: Studio</i></p> <p><b>ID:137</b> Including virtual constraints in motion planning for anthropomorphic hands, <i>Raúl Suárez</i> <b>ID:166</b> View-based Programming with Reinforcement Learning for Robotic Manipulation, <i>Yusuke Maeda</i> <b>ID:178</b> Towards Robot Systems for Small Batch Manufacturing, <i>Martijn Rooker</i> <b>ID:138</b> Importance Sampling based on Adaptive Principal Component Analysis, <i>Raúl Suárez</i></p>	<p>Special Session 2B2: Robot-based Automation of Nanohandling Processes II  <i>Chair: Mr. Daniel Jasper, University of Oldenburg</i> <i>Location: Sonaatti 1</i></p> <p><b>ID:100</b> Determination of Lattice Parameters of SCS Nanobeam in Process of Tensile Testing Using MEMS Actuator, <i>Hongjiang Zeng</i> <b>ID:127</b> Microrobotic Platform for Making, Manipulating and Breaking Individual Paper Fiber Bonds, <i>Pooya Saketi</i> <b>ID:202</b> Automated Handling and Assembly of Customizable AFM-Tips, <i>Daniel Jasper</i></p>	<p>Session 2C2: Micro and Macro Assembly and Manufacturing Processes: Measurements and Control  <i>Chair: Dr. Felix Kahleyß, Technische Universität Dortmund</i> <i>Location: Sonaatti 2</i></p> <p><b>ID:105</b> A New Measuring Method for Circular Motion Accuracy of NC Machine Tools Based on Dual-frequency Laser Interferometer, <i>Shanzhi Tang</i> <b>ID:190</b> Scanner test pattern for evaluation of beam manipulation accuracy, <i>Jorma Vihinen</i> <b>ID:193</b> A Dual Side Electroluminescence Measurement System for Manufacturing Epiwafers, <i>HyungTae Kim</i></p>
12:40-13:40	Lunch Break		
13:40-	Session 2A3: Micro and	Special Session 2B3: Micro	Session 2C3: Competitive and

15:00	<p>Macro Assembly and Manufacturing Processes: Robotics and Production</p> <p><i>Chair: Dr. Martijn Rooker, PROFACTOR GmbH Location: Studio</i></p> <p><b>ID:205</b> Cost Modelling for Micro Manufacturing Logistics when using a Grid of Equiplets, <i>Erik Puik</i> <b>ID:223</b> 3D-Assembly of Molded Interconnect Devices with Standard SMD Pick &amp; Place Machines Using an Active Multi Axis Workpiece Carrier, <i>Michael Pfeffer</i> <b>ID:230</b> Manufacturing of micro-structured parts for mass production purposes, <i>Stephan Eilbracht</i></p>	<p>and Macro Assembly and Manufacturing Processes: Collaborative Robotics</p> <p><i>Chair: Mr. Niko Siltala, Tampere University of Technology Location: Sonaatti 1</i></p> <p><b>ID:124</b> Safety of Collaborative Industrial Robots, <i>Björn Matthias</i> <b>ID:204</b> A Flexible Robotic Gripper for Automation of Assembly Tasks, <i>Timothy Vittor</i> <b>ID:208</b> Requirements on Flexible Robot Systems for Small Parts Assembly, <i>Mikael Hedelind</i> <b>ID:211</b> A Robot Concept for Scalable, Flexible Assembly Automation, <i>Mikael Hedelind</i></p>	<p>Sustainable Production and Systems: Aspects of Sustainability</p> <p><i>Chair: Dr. Timo Lehtonen, Tampere University of Technology Location: Sonaatti 2</i></p> <p><b>ID:180</b> Enforcing employees participation in the factory planning process, <i>Riechel Christoph</i> <b>ID:187</b> Objectives, enablers and challenges of sustainable development and sustainable manufacturing: Views and opinions of Spanish companies, <i>Mikko Koho</i> <b>ID:236</b> Life Cycle Simulation (LCS) Approach to the Manufacturing Process Design for Sustainable Manufacturing, <i>Khair Harun</i></p>
15:00-15:20	Coffee Break		
15:20-16:30	<p>Session 2A4: Micro and Macro Assembly and Manufacturing Processes: Robotics and Assembly Systems</p> <p><i>Chair: Mr. Timo Prusi, Tampere University of Technology Location: Studio</i></p> <p><b>ID:150</b> Control of automatic assembly platform for a large unit based on equivalent parallel, <i>Jinhua Zhang</i> <b>ID:153</b> Research on dual-driving synchronous control system modeling of gantry-type machine tools with travelling bridge, <i>Yuxia Li</i> <b>ID:174</b> Modular Control System for Reconfigurable Robot Applications, <i>Markus Janßen</i></p>	<p>Session 2B4: Competitive and Sustainable Production and Systems: New Sustainable Environments</p> <p><i>Chair: Mr. Kai Salminen, Tampere University of Technology Location: Sonaatti 1</i></p> <p><b>ID:106</b> Combining Facility Layout Redesign and Dynamic Routing for Job-shop Assembly Operations, <i>Lihui Wang</i> <b>ID:117</b> A Prototype of Modeling and Simulation for Sustainable Machining, <i>Guodong Shao</i> <b>ID:234</b> Introduction of a Competitive and Sustainable Research Environment, <i>Ari Ranta</i> <b>ID:206</b> Towards learning Pallets Applied in Pull control job-open shop, <i>Afshin Mehrsai</i></p>	
16:30-17:00	Closing Session <i>Location: Studio</i>		